

1 Inequality Constraints

1.1 One Inequality constraint

Problem: maximize $f(x, y)$ subject to $g(x, y) \leq b$.

As we see here the constraint is written as inequality instead of equality.

An inequality constraint $g(x, y) \leq b$ is called *binding (or active) at a point* (x, y) if $g(x, y) = b$ and *not binding (or inactive)* if $g(x, y) < b$.

Again we consider the same Lagrangian function

$$L(x, y, \lambda) = f(x, y) - \lambda[g(x, y) - b].$$

Theorem 1 Suppose (x^*, y^*) is a solution of the above problem: (x^*, y^*) maximizes f on the constraint set $g^*(x, y) \leq b$.

Suppose the following **qualification** is satisfied: If $g(x^*, y^*) = b$ (i.e. if (x^*, y^*) is binding) then $Dg(x^*, y^*) \neq (0, 0)$. Then there exists a multiplier λ^* such that

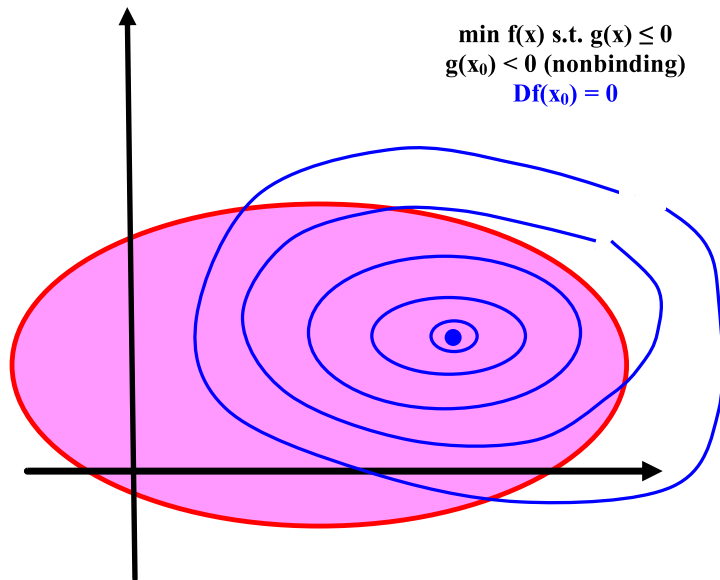
- (a) $\frac{\partial L}{\partial x}(x^*, y^*, \lambda^*) = 0,$
- (b) $\frac{\partial L}{\partial y}(x^*, y^*, \lambda^*) = 0,$
- (c) $\lambda^*[g(x^*, y^*) - b] = 0,$
- (d) $\lambda^* \geq 0,$
- (e) $g(x^*, y^*) \leq b.$

Remark 1. These conditions, as well as the conditions from theorems below concerning with inequality conditions are called Karush-Kuhn-Tucker (KKT) conditions.

Remark 2. For the minimization problem the condition (d) must be replaced by
(d') $\lambda^* \leq 0.$

Almost a proof. Consider the following two cases: (x^*, y^*) is binding or not binding.

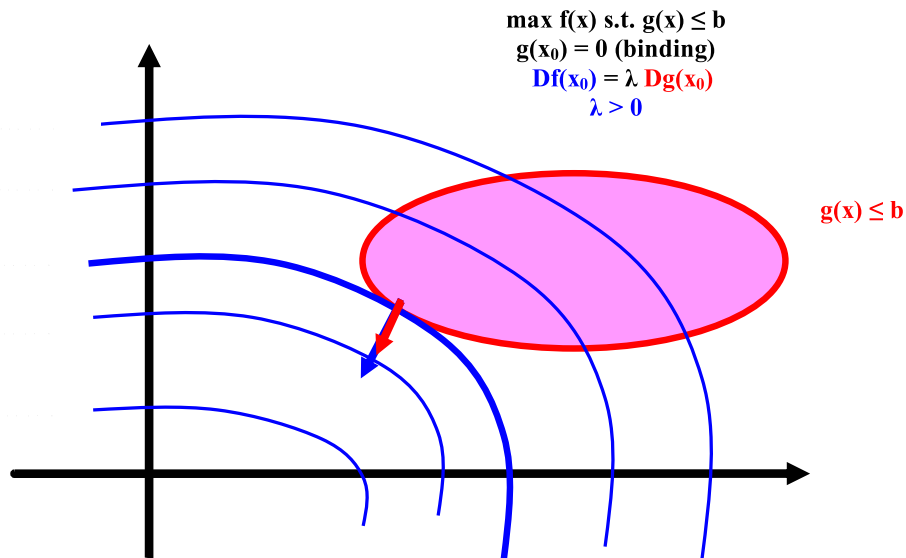
Case 1: (x^*, y^*) is not binding $g(x^*, y^*) < b$.



This means that (x^*, y^*) is an *inner* (unconstrained) maximum, thus $f_x(x^*, y^*) = 0$, $f_y(x^*, y^*) = 0$. In this case we *can take* $\lambda = 0$ the conditions (a) - (e) are satisfied. Indeed

- (a) $L_x(x^*, y^*, \lambda^*) = f_x(x^*, y^*) - \lambda \cdot g_x(x^*, y^*) = f_x(x^*, y^*) - 0 \cdot g_x(x^*, y^*) = 0$;
- (b) $L_y(x^*, y^*, \lambda^*) = f_y(x^*, y^*) - \lambda \cdot g_y(x^*, y^*) = f_y(x^*, y^*) - 0 \cdot g_y(x^*, y^*) = 0$;
- (c) $\lambda^* \cdot [g(x^*, y^*) - b] = 0 \cdot [g(x^*, y^*) - b] = 0$;
- (d) $0 = \lambda^* \geq 0$;
- (e) $g(x^*, y^*) - b < 0$.

Case 2: (x^*, y^*) is binding $g(x^*, y^*) = 0$.



This means that (x^*, y^*) is a maximizer constrained by the equality condition, thus there exists λ^* such that

$$L_x(x^*, y^*) = 0, \quad L_y(x^*, y^*) = 0, \quad L_\lambda(x^*, y^*) = 0,$$

this again implies the needed conditions (a) - (e):

- (a) $L_x(x^*, y^*, \lambda^*) = 0$;
- (b) $L_y(x^*, y^*, \lambda^*) = 0$;
- (c) $\lambda^* \cdot [g(x^*, y^*) - b] = \lambda^* \cdot 0 = 0$;
- (d) since of maximality of (x^*, y^*) the gradients $\nabla f(x^*, y^*)$ and $\nabla g(x^*, y^*)$ must have the same directions, thus $\lambda \geq 0$;
- (e) $g(x^*, y^*) - b = 0$.

Remark. What is the meaning of the zero $\lambda = 0$ multiplier in Case 1? The shadow price in this case is 0: the maximal value $f(x^*, y^*)$ does not change when we change b a little.

Example 1. Minimize $f(x, y) = x^2 + y^2$ subject of $g(x, y) = 2x + y \leq 2$.

Solution. There are no critical points of g at all, so the qualification is satisfied.

The lagrangian in this case is

$$L(x, y, \lambda) = x^2 + y^2 - \lambda(2x + y - 2),$$

and the KKT conditions from Theorem are

- (a) $\frac{\partial L}{\partial x}(x, y, \lambda) = 2x - 2\lambda = 0$,
- (b) $\frac{\partial L}{\partial y}(x, y, \lambda) = 2y - \lambda = 0$,
- (c) $\lambda[g(x, y) - b] = \lambda(2x + y - 2) = 0$,
- (d) $\lambda \leq 0$,
- (e) $g(x, y) = 2x + y \leq 2$.

We consider two cases:

Case 1. $\lambda = 0$, in this case our system looks as

- (a) $x = 0$,
- (b) $y = 0$,
- (c) $0 = 0$,
- (d) $0 \leq 0$,
- (e) $2x + y \leq 2$,

so the solution in this case is $(x, y, \lambda) = (0, 0, 0)$.

Case 2. $2x + y - 2 = 0$, in this case our system looks as

- (a) $2x = 2\lambda$,
- (b) $2y = \lambda$,
- (c) $2x + y - 2 = 0$,
- (d) $\lambda \leq 0$,
- (e) $2x + y \leq 2$,

so $x = 2y$, $2x + y = 2$, this gives the solution $x = 0.8$, $y = 0.4$ but $\lambda = 0.8 > 0$ so this solution *can not* be a minimizer.

So if this constrained minimization problem has a solution, it *can be* only $(0, 0)$.

Example 2. Maximize $f(x, y) = xy$ subject of $g(x, y) = x^2 + y^2 \leq 2$.

Solution. The constraint function $g(x, y)$ has no critical points at all, so the qualification is satisfied.

The Lagrangian in this case is

$$L(x, y, \lambda) = xy - \lambda(x^2 + y^2 - 2),$$

and the KKT conditions from Theorem are

- (a) $\frac{\partial L}{\partial x}(x, y, \lambda^*) = y - 2\lambda x = 0,$
- (b) $\frac{\partial L}{\partial y}(x, y, \lambda) = x - 2\lambda y = 0,$
- (c) $\lambda^*[g(x, y) - b] = \lambda(x^2 + y^2 - 2) = 0,$
- (d) $\lambda \geq 0,$
- (e) $g(x, y) = x^2 + y^2 \leq 2.$

We consider two cases:

Case 1: $\lambda = 0$. In this case our system looks as

- (a) $y = 0,$
- (b) $x = 0,$
- (c) $0 = 0,$
- (d) $0 \geq 0,$
- (e) $x^2 + y^2 \leq 2$

so the solution in this case is $(x^*, y^*, \lambda^*) = (0, 0, 0)$.

Case 2: $x^2 + y^2 - 2 = 0$. In this case our system looks as

- (a) $y - 2\lambda x = 0,$
- (b) $x - 2\lambda y = 0,$
- (c) $(x^2 + y^2 - 2) = 0,$
- (d) $\lambda \geq 0,$
- (e) $x^2 + y^2 \leq 2.$

The first two equations yield

$$\lambda = \frac{y}{2x} = \frac{x}{2y}, \quad \text{or } x^2 = y^2.$$

Together with the condition (c) it gives the system

$$\begin{aligned} x^2 &= y^2 \\ x^2 + y^2 &= 2. \end{aligned}$$

The solution gives $x^2 = 1$, $y^2 = 1$, or $x = \pm 1$, $y = \pm 1$. Combining with $\lambda = \frac{y}{2x}$ we obtain corresponding $\lambda = \pm \frac{1}{2}$.

Combining all these solutions we get the following candidates for maximizers

$$\begin{aligned} x^* &= +1, & y^* &= +1, & \lambda^* &= +\frac{1}{2}; \\ x^* &= -1, & y^* &= -1, & \lambda^* &= +\frac{1}{2}; \\ x^* &= +1, & y^* &= -1, & \lambda^* &= -\frac{1}{2}; \\ x^* &= -1, & y^* &= +1, & \lambda^* &= -\frac{1}{2}. \end{aligned}$$

The last two solution contradict to the condition (e) $\lambda \geq 0$, so, including $(0, 0, 0)$ there are three candidates which satisfy the first order conditions. Note that the constraint set is compact. Plugging these three into the objective function, we find that $f(1, 1) = 1$, $f(-1, -1) = 1$ so both $(1, 1)$ and $(-1, -1)$ are the needed maximizers.

Note that the two points with negative multipliers

$$\begin{aligned} x^* &= +1, & y^* &= -1, & \lambda^* &= -\frac{1}{2}; \\ x^* &= -1, & y^* &= +1, & \lambda^* &= -\frac{1}{2}. \end{aligned}$$

are the solutions of the problem of *minimizing* of $f(x, y) = xy$ subject to $g(x, y) = x^2 + y^2 \leq 1$.

Economical Application. Consider the standard problem of maximization of the utility function

$$U(x_1, x_2)$$

subject to the budget *inequality* constraint

$$p_1x_1 + p_2x_2 \leq I.$$

Suppose additionally that $p_1 > 0$, $p_2 > 0$ and the utility function is *monotonic* in both arguments, that is for each commodity bundle (x_1, x_2)

$$\frac{\partial U}{\partial x_1}(x_1, x_2) > 0, \quad \frac{\partial U}{\partial x_2}(x_1, x_2) > 0.$$

This means that our commodities are *goods*.

Then the KKT implies an important result: the optimal solution is *necessarily binding*

$$p_1x_1 + p_2x_2 = I,$$

that is at optimizer the *consumer spends all the available income*.

Indeed, for the Lagrangian

$$L(x_1, x_2) = f(x_1, x_2) - \lambda(p_1x_1 + p_2x_2 - I)$$

we have

$$\begin{aligned} \frac{\partial L}{\partial x_1}(x_1, x_2) &= \frac{\partial U}{\partial x_1}(x_1, x_2) - \lambda p_1 = 0, \\ \frac{\partial L}{\partial x_2}(x_1, x_2) &= \frac{\partial U}{\partial x_2}(x_1, x_2) - \lambda p_2 = 0, \end{aligned}$$

now, since $\frac{\partial U}{\partial x_1}(x_1, x_2) > 0$ and (or) $\frac{\partial U}{\partial x_2}(x_1, x_2) > 0$, it follows that $\lambda > 0$. Then from the condition

$$\lambda(p_1x_1 + p_2x_2 - I) = 0$$

we get

$$p_1x_1 + p_2x_2 - I = 0.$$

Notice that it is enough to require that just one of commodities is a good.

1.2 Two Inequality Constraints

Maybe it will be useful to consider separately the following problem:

$$\max f(x_1, x_2, x_3) = 0 \quad \text{s.t.} \quad g_1(x_1, x_2, x_3) \leq b_1, \quad g_2(x_1, x_2, x_3) \leq b_2.$$

Lagrangian function in this case is

$$L(x_1, x_2, x_3) = f(x_1, x_2, x_3) - \lambda_1(g_1(x_1, x_2, x_3) - a) - \lambda_2(g_2(x_1, x_2, x_3) - b_2).$$

The KKT conditions in this case look as

- (1) $\frac{\partial}{\partial x_1} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_1} g_1(x_1, x_2, x_3) - \lambda_2 \frac{\partial}{\partial x_1} g_2(x_1, x_2, x_3) = 0$
- (2) $\frac{\partial}{\partial x_2} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_2} g_1(x_1, x_2, x_3) - \lambda_2 \frac{\partial}{\partial x_2} g_2(x_1, x_2, x_3) = 0$
- (3) $\frac{\partial}{\partial x_3} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_3} g_1(x_1, x_2, x_3) - \lambda_2 \frac{\partial}{\partial x_3} g_2(x_1, x_2, x_3) = 0$
- (4) $\lambda_1[g_1(x_1, x_2, x_3) - b_1] = 0$
- (5) $\lambda_2[g_2(x_1, x_2, x_3) - b_2] = 0$
- (6) $\lambda_1 \geq 0$
- (7) $\lambda_2 \geq 0$
- (8) $g_1(x_1, x_2, x_3) \leq b_1$
- (9) $g_2(x_1, x_2, x_3) \leq b_2.$

Consider, concerning complementary slackness conditions (4) and (5), the following 4 cases:

Case 1: $\lambda_1 = 0, \lambda_2 = 0.$

Case 2: $g_1(x_1, x_2, x_3) - b_1 = 0, \lambda_2 = 0.$

Case 3: $\lambda_1 = 0, g_2(x_1, x_2, x_3) - b_2 = 0.$

Case 4: $g_1(x_1, x_2, x_3) - b_1 = 0, g_2(x_1, x_2, x_3) - b_2 = 0.$

We rewrite the KKT conditions in these cases:

Case 1: $\lambda_1 = 0, \lambda_2 = 0$.

- (1) $\frac{\partial}{\partial x_1} f(x_1, x_2, x_3) = 0$
- (2) $\frac{\partial}{\partial x_2} f(x_1, x_2, x_3) = 0$
- (3) $\frac{\partial}{\partial x_3} f(x_1, x_2, x_3) = 0$
- (4)
- (5)
- (6)
- (7)
- (8) $g_1(x_1, x_2, x_3) \leq b_1$
- (9) $g_2(x_1, x_2, x_3) \leq b_2$

so in this case we face ordinary nonconstrained optimization problem

$$\max f(x_1, x_2, x_3),$$

but with additional conditions $g_1(x_1, x_2, x_3) \leq b_1$ and $g_2(x_1, x_2, x_3) \leq b_2$, that is ignore all candidates (critical points of f) which are out of feasible region.

Case 2: $g_1(x_1, x_2, x_3) - b_1 = 0, \lambda_2 = 0$.

- (1) $\frac{\partial}{\partial x_1} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_1} g_1(x_1, x_2, x_3) = 0$
- (2) $\frac{\partial}{\partial x_2} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_2} g_1(x_1, x_2, x_3) = 0$
- (3) $\frac{\partial}{\partial x_3} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_3} g_1(x_1, x_2, x_3) = 0$
- (4) $g_1(x_1, x_2, x_3) - b_1 = 0$
- (5)
- (6) $\lambda_1 \geq 0$
- (7)
- (8)
- (9) $g_2(x_1, x_2, x_3) \leq b_2$

so in this case we face the problem with one equality constraint

$$\max f(x_1, x_2, x_3) \text{ s.t. } g_1(x_1, x_2, x_3) = b_1$$

with additional conditions $g_2(x_1, x_2, x_3) \leq b_2, \lambda_1 \geq 0$, that is we ignore all candidates with $g_2(x_1, x_2, x_3) > b_2$ or $\lambda_1 < 0$.

Case 3: $\lambda_1 = 0, g_2(x_1, x_2, x_3) - b_2 = 0$.

- (1) $\frac{\partial}{\partial x_1} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_1} g_1(x_1, x_2, x_3) = 0$
- (2) $\frac{\partial}{\partial x_2} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_2} g_1(x_1, x_2, x_3) = 0$
- (3) $\frac{\partial}{\partial x_3} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_3} g_1(x_1, x_2, x_3) = 0$
- (4)
- (5) $g_2(x_1, x_2, x_3) - b_2 = 0$
- (6)
- (7) $\lambda_2 \geq 0$
- (8) $g_1(x_1, x_2, x_3) \leq b_1$
- (9)

so in this case we face the problem with one equality constraint

$$\max f(x_1, x_2, x_3) \quad \text{s.t.} \quad g_2(x_1, x_2, x_3) = b_2$$

with additional conditions $g_1(x_1, x_2, x_3) \leq b_1$, $\lambda_2 \geq 0$, that is we ignore all candidates with $g_1(x_1, x_2, x_3) > b_2$ or $\lambda_2 < 0$.

Case 4: $g_1(x_1, x_2, x_3) - b_1 = 0$, $g_2(x_1, x_2, x_3) - b_2 = 0$.

- (1) $\frac{\partial}{\partial x_1} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_1} g_1(x_1, x_2, x_3) - \lambda_2 \frac{\partial}{\partial x_1} g_2(x_1, x_2, x_3) = 0$
- (2) $\frac{\partial}{\partial x_2} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_2} g_1(x_1, x_2, x_3) - \lambda_2 \frac{\partial}{\partial x_2} g_2(x_1, x_2, x_3) = 0$
- (3) $\frac{\partial}{\partial x_3} f(x_1, x_2, x_3) - \lambda_1 \frac{\partial}{\partial x_3} g_1(x_1, x_2, x_3) - \lambda_2 \frac{\partial}{\partial x_3} g_2(x_1, x_2, x_3) = 0$
- (4) $g_1(x_1, x_2, x_3) - b_1 = 0$
- (5) $g_2(x_1, x_2, x_3) - b_2 = 0$
- (6) $\lambda_1 \geq 0$
- (7) $\lambda_2 \geq 0$
- (8)
- (9)

so in this case we face the problem with two equality constraint

$$\max f(x_1, x_2, x_3) \quad \text{s.t.} \quad g_1(x_1, x_2, x_3) = b_1, \quad g_2(x_1, x_2, x_3) = b_2$$

with additional conditions $\lambda_1 \geq 0$, $\lambda_2 \geq 0$, that is we ignore all candidates with $\lambda_1 < 0$ or $\lambda_2 < 0$.

1.3 Several Inequality Constraints

Problem: maximize $f(x_1, \dots, x_n)$ subject to k inequality constraints

$$g_1(x_1, \dots, x_n) \leq b_1, \quad \dots, \quad g_k(x_1, \dots, x_n) \leq b_k.$$

Recall that constraint $g_i(x) \leq b$ is **binding** at a solution candidate $x^* = (x_1^*, \dots, x_n^*)$ if $g_i(x^*) = b$, and it is called **not binding** or **slack** if $g_i(x^*) < b$.

Theorem 2 Suppose $x^* = (x_1^*, \dots, x_n^*)$ is a maximizer for our problem, and suppose first k_0 constraints are binding at x^* and the last $k - k_0$ are not binding.

Suppose that the following **qualification** is satisfied: the rank of the Jacobian of the binding constraints

$$\begin{pmatrix} \frac{\partial g_1}{\partial x_1}(x^*) & \dots & \frac{\partial g_1}{\partial x_n}(x^*) \\ \dots & \dots & \dots \\ \frac{\partial g_{k_0}}{\partial x_1}(x^*) & \dots & \frac{\partial g_{k_0}}{\partial x_n}(x^*) \end{pmatrix}$$

is k_0 , as large as it can be. In other words the gradients of the active inequality constraints are linearly independent at x^* .

Consider the lagrangian

$$L(x_1, \dots, x_n, \lambda_1, \dots, \lambda_k) = f(x_1, \dots, x_n) - \lambda_1[g_1(x_1, \dots, x_n) - b_1] - \dots - \lambda_k[g_k(x_1, \dots, x_n) - b_k].$$

Then there exist multipliers $\lambda^* = (\lambda_1^*, \dots, \lambda_k^*)$ such that the following KKT conditions are satisfied

- (a) $\frac{\partial L}{\partial x_1}(x^*, \lambda^*) = 0, \dots, \frac{\partial L}{\partial x_n}(x^*, \lambda^*) = 0,$
- (b) $\lambda_1^*[g_1(x^*) - b_1] = 0, \dots, \lambda_k^*[g_k(x^*) - b_k] = 0,$
- (c) $\lambda_1^* \geq 0, \dots, \lambda_k^* \geq 0,$
- (d) $g_1(x^*) \leq b_1, \dots, g_k(x^*) \leq b_k.$

Remark. Actually, the Theorem can be reformulated as follows:

Suppose $x^* \in R^n$ is a maximizer of $f(x)$ s.t. $g_1(x) \leq b_1, \dots, g_k(x) \leq b_k$, suppose also that first k_0 constraints are binding at x^* , i.e.

$$g_1(x) = b_1, \dots, g_{k_0}(x) = b_{k_0}$$

and others are nonbinding, and suppose the vectors

$$Dg_1(x^*), \dots, Dg_{k_0}(x^*)$$

are linearly independent. Then

$$Df(x^*) \in \text{span}(Dg_1(x^*), \dots, Dg_{k_0}(x^*)),$$

i.e.

$$Df(x^*) = \lambda_1 Dg_1(x^*) + \dots + \lambda_{k_0} Dg_{k_0}(x^*),$$

and all the coefficients are nonnegative: $\lambda_1 \geq 0, \dots, \lambda_{k_0} \geq 0$.

Remark. For the minimization problem the condition (c) must be replaced by

$$(c') \lambda_1^* \leq 0, \dots, \lambda_k^* \leq 0.$$

Example 3. Solve the problem

maximize $f(x_1, x_2) = -(x_1 - 4)^2 - (x_2 - 4)^2$ subject to $g_1(x_1, x_2) = x_1 + x_2 \leq 4$, $g_2(x_1, x_2) = x_1 + 3x_2 \leq 9$.

Solution. The Lagrangean looks as

$$L(x_1, x_2) = -(x_1 - 4)^2 - (x_2 - 4)^2 - \lambda_1(x_1 + x_2 - 4) - \lambda_2(x_1 + 3x_2 - 9).$$

The KKT conditions look as

$$\begin{aligned}
 -2(x_1 - 4) - \lambda_1 - \lambda_2 &= 0 \\
 -2(x_2 - 4) - \lambda_1 - 3\lambda_2 &= 0 \\
 \lambda_1(x_1 + x_2 - 4) &= 0 \\
 \lambda_2(x_1 + 3x_2 - 9) &= 0 \\
 \lambda_1 \geq 0, \quad \lambda_2 \geq 0 \\
 x_1 + x_2 \leq 4, \quad x_1 + 3x_2 \leq 9.
 \end{aligned}$$

Analyzing the conditions $\lambda_1(x_1 + x_2 - 4) = 0$, $\lambda_2(x_1 + 3x_2 - 9) = 0$ we consider the following cases

Case 1: $x_1 + x_2 - 4 = 0$, $x_1 + 3x_2 - 9 = 0$. In this case the solution gives $x_1 = \frac{3}{2}$, $x_2 = \frac{5}{2}$, $\lambda_1 = 6$, $\lambda_2 = -1$ but this solution violates the condition $\lambda_2 \geq 0$, so NO SOLUTION of KKT in this case.

Case 2: $x_1 + x_2 - 4 = 0$, $\lambda_2 = 0$. In this case the solution gives $x_1 = 2$, $x_2 = 2$, $\lambda_1 = 4$, $\lambda_2 = 0$. This solution is OK, it fulfills KKT.

Case 3: $\lambda_1 = 0$, $x_1 + 3x_2 - 9 = 0$. In this case the solution gives $x_1 = 3.3$, $x_2 = 1.8$ but this violates the condition $x_1 + x_2 \leq 4$, so NO SOLUTION of KKT in this case.

Case 4: $\lambda_1 = 0$, $\lambda_2 = 0$. In this case the solution gives $x_1 = 4$, $x_2 = 4$, $\lambda_1 = 0$, $\lambda_2 = 0$, this solution violates $x_1 + x_2 \leq 4$, so NO SOLUTION of KKT in this case.

Finally we have the single solution of KKT $x_1 = 2$, $x_2 = 2$, $\lambda_1 = 4$, $\lambda_2 = 0$. But KKT is just a necessary condition. So, is it a solution of our maximization problem?

1.4 Mixed constraints

Problem: maximize $f(x_1, \dots, x_n)$ subject to k inequality and m equality constraints

$$\begin{aligned}
 g_1(x_1, \dots, x_n) &\leq b_1, \quad \dots, \quad g_k(x_1, \dots, x_n) \leq b_k, \\
 h_1(x_1, \dots, x_n) &= c_1, \quad \dots, \quad h_m(x_1, \dots, x_n) = c_m.
 \end{aligned}$$

Theorem 3 Suppose $x^* = (x_1^*, \dots, x_n^*)$ is a maximizer for our problem, and suppose first k_0 inequality constraints are binding at x^* and the last $k - k_0$ are not binding.

Suppose that the following **qualification** is satisfied: the rank of the

Jacobian of the binding constraints

$$\begin{pmatrix} \frac{\partial g_1}{\partial x_1}(x^*) & \dots & \frac{\partial g_1}{\partial x_n}(x^*) \\ \dots & \dots & \dots \\ \frac{\partial g_{k_0}}{\partial x_1}(x^*) & \dots & \frac{\partial g_{k_0}}{\partial x_n}(x^*) \\ \frac{\partial h_1}{\partial x_1}(x^*) & \dots & \frac{\partial h_1}{\partial x_n}(x^*) \\ \dots & \dots & \dots \\ \frac{\partial h_m}{\partial x_1}(x^*) & \dots & \frac{\partial h_m}{\partial x_n}(x^*) \end{pmatrix}$$

is $k_0 + m$, as large as it can be. In other words the gradients of the active inequality constraints and the gradients of the equality constraints are linearly independent at x^* .

Consider the lagrangian

$$\begin{aligned} L(x_1, \dots, x_n, \lambda_1, \dots, \lambda_k, \mu_1, \dots, \mu_m) &= f(x_1, \dots, x_n) + \\ &- \lambda_1[g_1(x_1, \dots, x_n) - b_1] - \dots - \lambda_k[g_k(x_1, \dots, x_n) - b_1] + \\ &- \mu_1[h_1(x_1, \dots, x_n) - c_1] - \dots - \mu_m[h_m(x_1, \dots, x_n) - c_1]. \end{aligned}$$

Then there exist multipliers $\lambda^* = (\lambda_1^*, \dots, \lambda_k^*)$, $\mu^* = (\mu_1^*, \dots, \mu_m^*)$ such that

- (a) $\frac{\partial L}{\partial x_1}(x^*, \lambda^*, \mu^*) = 0, \dots, \frac{\partial L}{\partial x_n}(x^*, \lambda^*, \mu^*) = 0,$
- (b) $\lambda_1^*[g_1(x^*) - b_1] = 0, \dots, \lambda_k^*[g_k(x^*) - b_1] = 0,$
- (c) $h_1(x^*) = c_1, \dots, h_m(x^*) = c_m,$
- (d) $\lambda_1^* \geq 0, \dots, \lambda_k^* \geq 0,$
- (e) $g_1(x^*) \leq b_1, \dots, g_1(x^*) \leq b_1.$

Remark. Actually, the Theorem can be reformulated as follows:

Suppose $x^* \in R^n$ is a maximizer of $f(x)$ s.t.

$$g_1(x) \leq b_1, \dots, g_k(x) \leq b_k, \quad h_1(x) = c_1, \dots, h_m(x) = c_m.$$

Suppose also that first k_0 inequality constraints are binding at x^* , i.e.

$$g_1(x) = b_1, \dots, g_{k_0}(x) = b_{k_0}$$

and the others are nonbinding, and and suppose the vectors

$$Dg_1(x^*), \dots, Dg_{k_0}(x^*), Dh_1(x^*), \dots, Dh_m(x^*)$$

are linearly independent. Then

$$Df(x^*) \in \text{span}(Dg_1(x^*), \dots, Dg_{k_0}(x^*), Dh_1(x^*), \dots, Dh_m(x^*))$$

i.e.

$$Df(x^*) = \lambda_1 Dg_1(x^*) + \dots + \lambda_{k_0} Dg_{k_0}(x^*) + \mu_1 Dh_1(x^*) + \dots + \mu_m Dh_m(x^*)$$

and all the λ_i coefficients are nonnegative: $\lambda_1 \geq 0, \dots, \lambda_{k_0} \geq 0.$

1.5 Economical Applications

The KKT conditions sometimes are used not for the finding of optimizers, rather for some important qualitative conclusions.

1.5.1 A Sales-Maximizing Firm with Advertizing

Let:

$y \in R_+$ production;

$C(y)$ - cost of manufacturing y units (assume that $C' > 0$);

$a \in R_+$ - advertising cost;

$C(y) + a$ - total cost;

$R(y, a)$ - revenue (assume that $R_a > 0$);

$m \in R_+$ - minimal level of profit.

$\Pi = R(y, a) - C(y) - a$ - profit.

Problem:

$$\max R(y, a) \quad \text{s.t.} \quad \Pi \geq m, \quad a \geq 0.$$

Equivalently

$$\max R(y, a) \quad \text{s.t.} \quad -a \leq 0, \quad m - R(y, a) + C(y) + a \leq 0.$$

Lagrangian:

$$L(y, a, \lambda_1, \lambda_2) = R(y, a) + \lambda_1 a - \lambda_2 (m - R(y, a) + C(y) + a).$$

The KKT conditions for a maximizer y^* :

- (1) $L_y = (1 + \lambda_2)R_y(y^*, a) - \lambda_2 C'(y^*) = 0$
- (2) $L_a = (1 + \lambda_2)R_a(y^*, a) + \lambda_1 - \lambda_2 = 0$
- (3) $\lambda_1 a = 0$
- (4) $\lambda_2 (m - R(y^*, a) + C(y^*) + a) = 0$
- (5) $\lambda_1 \geq 0$
- (6) $\lambda_2 \geq 0$
- (7) $-a \leq 0$
- (8) $m - R(y^*, a) + C(y^*) + a \leq 0.$

Observation 1. In (2) we have $(1 + \lambda_2)R_a(y^*, a) > 0$, $\lambda_1 \geq 0 \Rightarrow \lambda_2 > 0$. This, (4) gives

$$m - R(y^*, a) + C(y^*) + a = 0$$

i.e. at maximizer y^* we have $R(y^*) - C(y^*) - a = m$, *that is the revenue is maximal when the profit is at minimal allowed level!*

Observation 2. Let us estimate the marginal profit at the revenue maximizer y^* using (1):

$$\begin{aligned} (1 + \lambda_2)\Pi_y(y^*, a) &= \\ (1 + \lambda_2)(R_y(y^*) - C'(y^*)) &= (1 + \lambda_2)R_y(y^*) - (1 + \lambda_2)C'(y^*) = \\ (1 + \lambda_2)R_y(y^*) - \lambda_2 C'(y^*) - C'(y^*) &= L_y(y^*, a) - C'(y^*) = 0 - C'(y^*) = \\ &= -C'(y^*) < 0, \end{aligned}$$

thus the revenue maximizer y^ is greater than the profit maximizer.*

Exercises

1. Compare the solutions of following problems

(a) Find the maximizer of $f(x, y) = 10 - x^2 - y^2$.

(b) Find the maximizer of $f(x, y) = 10 - x^2 - y^2$, subject to the constraint $h(x, y) = 2x^2 + y^2 = 2$.

(c) Find the maximizer of $f(x, y) = 10 - x^2 - y^2$, subject to the constraint $g(x, y) = 2x^2 + y^2 \leq 2$.

(d) Find the maximizer of $f(x, y) = 10 - x^2 - y^2$, subject to the constraint $g(x, y) = 2x^2 + y^2 \geq 2$.

2. Compare the solutions of following problems

(a) Find the minimizer of $f(x, y) = 10 + x^2 + y^2$.

(b) Find the minimizer of $f(x, y) = 10 + x^2 + y^2$, subject to the constraint $h(x, y) = 2x^2 + y^2 = 2$.

(c) Find the minimizer of $f(x, y) = 10 + x^2 + y^2$, subject to the constraint $g(x, y) = 2x^2 + y^2 \leq 2$.

(d) Find the minimizer of $f(x, y) = 10 + x^2 + y^2$, subject to the constraint $g(x, y) = 2x^2 + y^2 \geq 2$.

3. Find the dimensions of the box with largest volume if the total surface area is 24 cm^2 .

4. Find the maximum and minimum of $f(x, y) = 5x - 3y$ subject to the constraint $x^2 + y^2 = 136$.

5. Find the maximum and minimum of $f(x, y) = 4x^2 + 10y^2$ subject to the constraint $x^2 + y^2 \leq 4$.

6. Write down the KKT conditions for the problem:

Minimize $f(x_1, x_2, x_3) = -x_1^3 + x_2^2 - 2x_1x_3^2$ subject to the constraints: $2x_1 + x_2^2 + x_3 - 5 = 0$, $5x_1^2 - x_2^2 - x_3 \geq 2$, $x_1 \geq 0$, $x_2 \geq 2$, $x_3 \geq 0$. Verify the KKT conditions for $(1, 0, 3)$.

7. Write down the KKT conditions for the problem:

Minimize $f(x_1, x_2, x_3) = x_1^2 + x_2^2 + x_3^2$ subject to the constraints: $-x_1 + x_2 - x_3 \geq -10$, $x_1 + x_2 + 4x_3 \geq 20$. Find all the solutions.

Homework

Exercises 18.10, 18.11, 18.12, 18.15, 18.17 from [Simon].