

ISET MATH II Term Final

Answers without work or justification will not receive credit.

1. Diagonalize $A = \begin{pmatrix} 1 & 4 \\ 4 & 1 \end{pmatrix}$, i.e. show that it is similar to a diagonal matrix, that is find a matrix S such that $S^{-1}AS$ is a diagonal matrix.

$$S = \begin{pmatrix} & \\ & \end{pmatrix}, \quad S^{-1}AS = \begin{pmatrix} & \\ & \end{pmatrix}$$

2. Let $U = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$, $V = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$ and $W = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$.

(2a) Are the U and W similar?

(2b) Are U and V similar?

(write "yes" or "no" and justify your answer).

(2a)

(2b)

3. Let $A = \begin{pmatrix} 2 & 3 \\ 1 & 2 \\ 2 & 5 \end{pmatrix}$. Find or show the nonexistence of a matrix B such that $B \cdot A$ is unit 2×2 matrix.

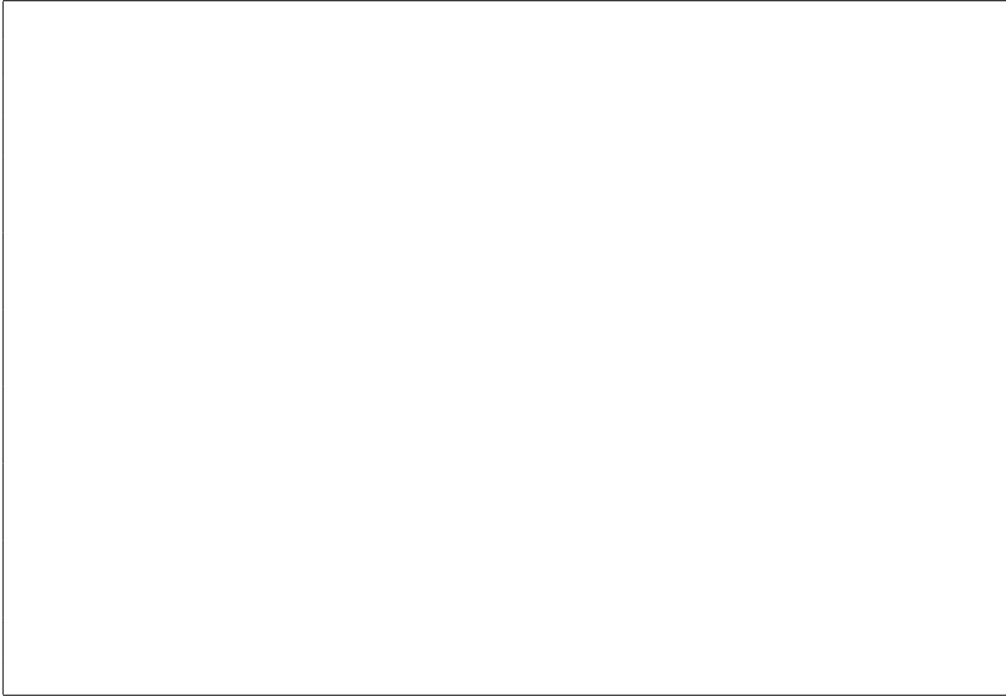
4. Let V and W be vectors in the plane R^2 with lengths $\|V\| = 3$ and $\|W\| = 5$. (4a) What are the maxima and minima of $\|V + W\|$? (4b) When do these occur?

<p>(4a)</p> <p>$\max(\ V + W\) =$</p> <p>$\min(\ V + W\) =$</p>
<p>(4b)</p>

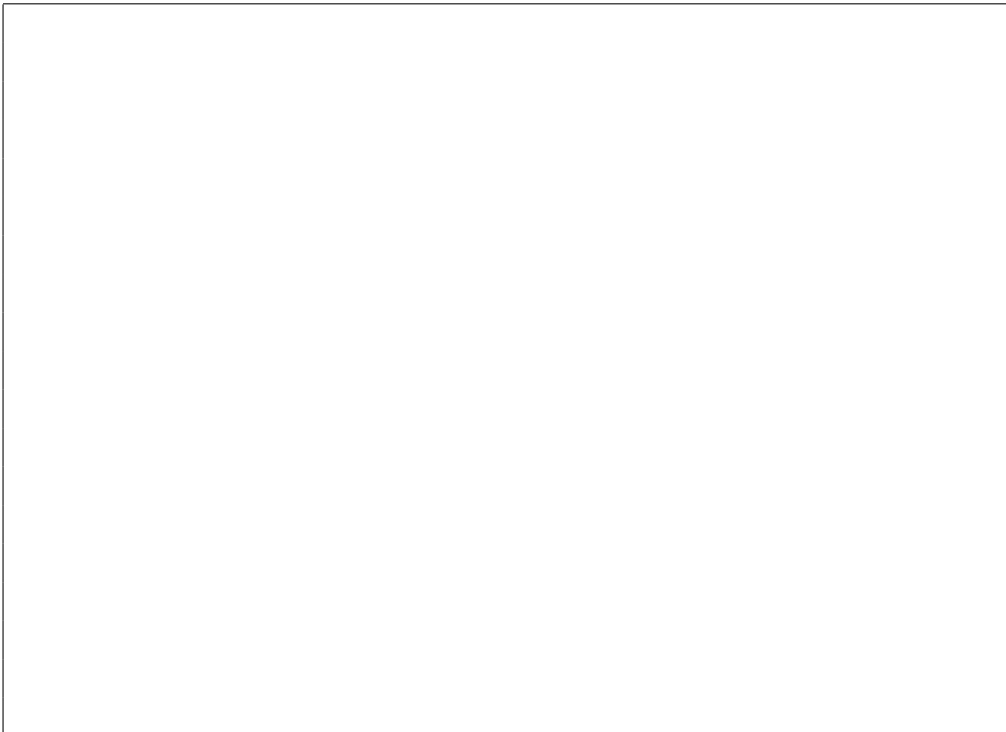
5. Find a vector which (5a) does belong, and (5b) does not belong to $L((1, 3, 4), (4, 0, 1), (3, 1, 2))$.

<p>(5a)</p>
<p>(5b)</p>

6. In the plane (through the origin) spanned by $V = (1, 1, -2)$ and $W = (-1, 1, 1)$, find all vectors that are perpendicular to the vector $Z = (2, 1, 2)$.



7. Let $S \subset \mathbb{R}^3$ be the subspace spanned by the two vectors $u = (1, -1, 0)$ and $v = (1, -1, 1)$. Write the equation of a line orthogonal to S which passes through the origin.



8. Find a basis of the subspace of solutions of the equation

$$x_1 + x_2 + x_3 + x_4 = 0.$$

9. Give a proof or counterexample to the following.

a) Suppose that u , v and w are vectors in R^n and $T : R^n \rightarrow R^m$ is a linear map. If u , v and w are linearly dependent, is it true that $T(u)$, $T(v)$ and $T(w)$ are linearly dependent? Why?

b) If $T : R^6 \rightarrow R^4$ is a linear map, is it possible that the nullspace of T is one dimensional?

(9a)
(9b)

10. **Remainder.** Let $T : R^n \rightarrow R^k$ be a linear transformation determined by $T(X) = A \cdot X$.

Equation $AX = Y$ has a solution iff $Y \in Im(T) = Col(A)$.

X is a solution of $AX = 0$ iff $X \in Ker(T) = Null(A)$.

Particularly, if $rank(A) = r < k$, then $dimIm(T) = dimCol(A) = r < k$ thus $Im(T)$ does not fulfill R^k , i.e. T is not surjective. Hence there exists $Y \in R^k$ which is not in $Im(T)$, that is $AX = Y$ does not have a solution.

Now the problem:

Say you have k linear algebraic equations in n variables; in matrix form $AX = Y$. For each of the following write "yes" and justify or write "no" and give a counterexample.

- (a) If $n = k$ then for each Y the system $AX = Y$ has at most one solution.
- (b) If $n > k$ you can solve $AX = Y$ for any Y .
- (c) If $n > k$ then $AX = 0$ has nonzero solutions.
- (d) If $n < k$ then for some Y there is no solution of $AX = Y$.
- (e) If $n < k$ the only solution of $AX = 0$ is $X = 0$.

(10a)	
(10b)	
(10c)	
(10d)	
(10e)	

11. Each of three elementary row operations may be performed on a matrix A by multiplication from the left by certain elementary matrices. For example the elementary row operation

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \longrightarrow \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} + r \cdot a_{11} & a_{22} + r \cdot a_{12} & a_{23} + r \cdot a_{13} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$$

in fact is the matrix product $\begin{pmatrix} 1 & 0 & 0 \\ r & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix}$.

(a) Write 3×3 elementary matrices for the following row operations

a1. Multiplication of each element of the third row by r .

a2. Interchanging of second and third rows.

a3. Adding to the third row the second row multiplied by k .

(b) For $A = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 4 \\ 3 & 2 & 2 \end{pmatrix}$, find a matrix B such that $B \cdot A$ will be in Gauss row echelon form;

(a1)	$\begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$
(a2)	$\begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$
(a3)	$\begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$
(b)	$B = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}, \quad BA = \begin{pmatrix} & & \\ & & \\ & & \end{pmatrix}$

12. (a) Find a 3×3 matrix that acts on R^3 as follows: it keeps the x_1 axis fixed but rotates the $x_2 x_3$ plane by 90 degrees (counterclockwise when you look from $(1, 0, 0)$).

b) Find a 3×3 matrix A mapping $R^3 \rightarrow R^3$ that rotates the $x_1 x_3$ plane by 180 degrees and leaves the x_2 axis fixed.

(a)	$\left(\begin{array}{ccc} & & \\ & & \\ & & \end{array} \right)$
(b)	$\left(\begin{array}{ccc} & & \\ & & \\ & & \end{array} \right)$

ADDITIONAL PAPER

ADDITIONAL PAPER

Solutions

1. $\begin{pmatrix} -3 & 0 \\ 0 & -5 \end{pmatrix} = \begin{pmatrix} -0.5 & 0.5 \\ 0.5 & 0.5 \end{pmatrix} \cdot \begin{pmatrix} 1 & 4 \\ 4 & 1 \end{pmatrix} \cdot \begin{pmatrix} -1 & 1 \\ 1 & 1 \end{pmatrix}.$

2. (a) No: $\det(U) \neq \det(W)$.

(b) Yes: $U = S^{-1}VS$ with $S = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}.$

3. $B = \begin{pmatrix} 2+z & -3-4z & z \\ -1+t & 2-4t & t \end{pmatrix}.$ Particularly

$$B = \begin{pmatrix} 2 & -3 & 0 \\ -1 & 2 & 0 \end{pmatrix}.$$

4. $\max(\|V+W\|) = 8$ when V and W are colinear and of same direction;
 $\min(\|V+W\|) = 2$ when V and W are colinear and of opposite direction

5. (a) Say $(1, 3, 4)$. (b) Say $(0, 0, 1)$.

6. Solve $(\alpha \cdot V + \beta \cdot U) \cdot Z = 0$. Answer $(0, 2\alpha, -\alpha)$.

7. $(x = t, y = t, z = 0)$.

8. General solution $\begin{pmatrix} -x_1 - x_2 - x_3 - x_4 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}.$

Basis $\begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ 0 \\ 1 \end{pmatrix}.$

9. (a) Yes: if $\alpha u + \beta v + \gamma w = 0$, $(\alpha, \beta, \gamma) \neq 0$ then $0 = T(\alpha u + \beta v + \gamma w) = T(\alpha u) + T(\beta v) + T(\gamma w) = \alpha T(u) + \beta T(v) + \gamma T(w)$.

(b) No: It is clear that $r = \text{rank}(T) \leq \min(6, 4) = 4$, thus $\dim \text{Null}(T) = 6 - r \geq 6 - 4 = 2$.

10. a) No, if $\det(A) = 0$ and $Y = 0$ there are infinitely many solutions.

Example: take $A = \begin{pmatrix} 1 & 1 \\ 2 & 2 \end{pmatrix}$ and $Y = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$

b) No: Suppose $\text{rank}(A) = r < k$. Then for $T : R^n \rightarrow R^k$ given by $T(X) = AX$ we have $\dim \text{Im}(T) = \dim \text{Col}(A) = r < k$ thus $\text{Im}(T)$ does not

fulfill R^k , i.e. T is not surjective. Hence there exists $Y \in R^k$ which is not in $Im(T)$, that is $AX = Y$ does not have a solution.

Example: take $A = \begin{pmatrix} 1 & 1 & 1 \\ 2 & 2 & 2 \end{pmatrix}$ and $Y = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

c) Yes: $dim Null(A) = n - r > n - k > 0$ thus $Null(A)$ contains nonzero vectors which are nonzero solutions of $AX = 0$.

d) Yes: $T : R^n \rightarrow R^k$ can not be surjective since $dim Im(A) = dim Col(A) = r \leq n < k$, thus there exist Y which is not in $Im(T)$ that is $AX = Y$ does not have a solution.

e) No: If $r < n$ then $dim Null(A) = n - r > 0$ so there exist nonzero vectors in $Null(A)$, they are nonzero solutions of $AX = 0$. Example: take

$$A = \begin{pmatrix} 1 & 1 \\ 2 & 2 \\ 3 & 3 \end{pmatrix}$$

11. a1. $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & r \end{pmatrix}$

a2. $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$

a3. $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & k & 1 \end{pmatrix}$

b.

$$B = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -3 & 0 & 1 \end{pmatrix} \cdot \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ -3 & 0 & 1 \\ -2 & 1 & 0 \end{pmatrix}$$

$$B \cdot A = \begin{pmatrix} 1 & 1 & 1 \\ 0 & -1 & -1 \\ 0 & 0 & 2 \end{pmatrix}$$

12.

(a) $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$. (b) $\begin{pmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -1 \end{pmatrix}$.