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ON THE PROBLEM WITH A SLOPING DERIVATIVE FOR A MIXED TYPE EQUATION IN THE CASE OF A TWO-DIMENSIONAL DEGENERATION DOMAIN **Abstract.** The paper considers a mixed type equation when the parabolic degeneration is two-dimensional. For this equation we study the problem with a sloping derivative and show that this problem is Noetherian.

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რე ზუშე, ნაშრომში გამოკვლეელია დაბრილწარმოებელიანი ამოტანა შერეული ტაპიბ განტოლებიბათვის, რომელიც განიცდის პარაბოლერ გადაგვარებას ორგანსომილებიან არეზე, ნაჩვენებაა ამოცანის ნეტერისეფლობა. On the Problem with a Sloping Derivative

We consider the equation

$$K(y)u_{xx} + u_{yy} + p(x,y)u_y + q(x,y)u = 0,$$
(1)

where

$$K(y) = \begin{cases} 1 & \text{for } y > 0, \\ 0 & \text{for } -\delta < y < 0, \\ -1 & \text{for } y < -\delta. \end{cases}$$

For $\delta > 0$ equation (1) is a mixed type model equation with two independent variables, whose domain of parabolicity, like the domains of ellipticity and hyperbolicity, is two-dimensional.

Let Ω be a finite domain bounded by a simple arc $\sigma \in C^2$ with ends $C_1(0,0)$ and $C_2(1,0)$ that lies in a half-plane y > 0, by the segments x = 0, x = 1 and by the characteristics $C_{1\delta}C : y = -x - \delta$ and $C_{2\delta}C : y = x - 1 - \delta$, $\delta = const > 0$, of equation (1), where p and q are the given functions. These characteristics outgo from the points $C_{1\delta}(0, -\delta)$ and $C_{2\delta}(1, -\delta)$.

Let further $\Omega_1 = \Omega \cap \{(x, y) : y > 0\}, \ \Omega_2 = \Omega \cap \{(x, y) : -\delta < y < 0\}, \ \Omega_3 = \Omega \cap \{(x, y) : y < -\delta\}, \ I_{\delta} = \{(x, -\delta) : \delta > 0, \ 0 < x < 1\}.$

Below it is assumed that the coefficients p(x, y) and q(x, y) of equation (1) are constant in the domain Ω_2 .

Let us consider the problem formulated as follows: find a function u(x, y)with the following properties: 1) u(x, y) is a regular solution of equation (1) in the domains Ω_1 , Ω_2 , Ω_3 ; 2) u(x, y) is continuous in the closed domain Ω and has continuous first derivatives in the same domain everywhere except perhaps for the points $C_1(0,0)$ and $C_2(1,0)$ in whose neighborhood u_x and u_y may reduce to infinity of order less than unity; 3) u(x, y) satisfies the boundary conditions

$$(p_1 u_x + q_1 u_y + \lambda_1 u)|_{\sigma} = \varphi, \tag{2}$$

$$(p_2 u_x + q_2 u_y + \lambda_2 u)|_{C_{1\delta}C} = \psi, \tag{3}$$

where p_i, q_i, λ_i $(i = 1, 2), \varphi, \psi$ are the given real functions.

Below it is assumed that $\partial \Omega_1 \in C^{2,h}$, $\varphi, p_i, q_i, \lambda_i \in C^{1,h}$ (i = 1, 2), $\psi \in C^{2,h}$, 0 < h < 1.

We introduce the following notation: $u(x, -\delta) = \tau_{\delta}(x), u_y(x, -\delta) = -\nu_{\delta}(x), u(x, 0) = \tau(x), u_y(x, 0) = \nu(x), 0 \le x \le 1, 2\alpha = -p, 2\beta = \sqrt{|p^2 - 4q|}$. Using this notation, the solution u(x, y) of problem (1), (2), (3) is representable in the domain Ω_2 for $p^2 - 4q = 0, p^2 - 4q > 0$ and $p^2 - 4q < 0$, respectively, in the form

$$u(x,y) = [(1 - \alpha y)\tau(x) + y\nu(x)]\exp(\alpha y),$$

$$u(x,y) = [(\beta \operatorname{ch} \beta y - \alpha \operatorname{sh} \beta y)\tau(x) + \nu(x)\operatorname{sh} \beta y]\beta^{-1}\exp(\alpha y),$$

$$u(x,y) = [(\beta \cos\beta y - \alpha \sin\beta y)\tau(x) + \nu(x)\sin\beta y]\beta^{-1}\exp(\alpha y).$$

Hence we easily conclude that the functions $\tau_{\delta}(x)$ and $\nu_0(x)$ are related to the functions $\tau(x)$ and $\nu(x)$ as follows:

a) for
$$p^2 - 4q = 0$$
 by
 $\tau_{\delta}(x) = [(1 + \alpha\delta)\tau(x) - \delta\nu(x)] \exp(-\alpha\delta),$
 $\nu_{\delta}(x) = [\alpha^2 \delta \tau(x) + (1 - \alpha\delta)\nu(x)] \exp(-\alpha\delta);$
b) for $p^2 - 4q > 0$ by
 $\tau_{\delta}(x) = [(\beta \operatorname{ch} \beta\delta + \alpha \operatorname{sh} \beta\delta)\tau(x) - \nu(x) \operatorname{sh} \beta\delta] \beta^{-1} \exp(-\alpha\delta),$
 $\nu_{\delta}(x) = [(\alpha^2 - \beta^2)\tau(x) \operatorname{sh} \beta\delta + (\beta \operatorname{ch} \beta\delta - \alpha \operatorname{sh} \beta\delta)\nu(x)]$ (4)
 $\times \beta^{-1} \exp(-\alpha\delta);$
c) for $p^2 - 4q < 0$ by

$$\tau_{\delta}(x) = \left[(\beta \cos \beta \delta + \alpha \sin \beta \delta) \tau(x) - \nu(x) \sin \beta \delta \right] \beta^{-1} \exp(-\alpha \delta),$$

$$\nu_{\delta}(x) = \left[(\alpha^{2} + \beta^{2}) \tau(x) \sin \beta \delta + (\beta \cos \beta \delta - \alpha \sin \beta \delta) \nu(x) \right]$$

$$\times \beta^{-1} \exp(-\alpha \delta).$$

If we assume that conditions (3) are fulfilled on the characteristic $C_{1\delta}C$ as in [1], then we obtain the following relation between $\tau_{\delta}(x)$ and $\nu_{\delta}(x)$ on I_{δ} :

$$\frac{1}{2}(p_2 - q_2)\tau_{\delta}(x) - \frac{1}{2}(p_2 - q_2)\nu_{\delta}(x) + [T(\tau_{\delta}, \nu_{\delta})](x) = \widetilde{\psi}(x), \qquad (5)$$

where $T(\tau_{\delta}, \nu_{\delta})$ is a completely defined linear integral operator, $\psi = \frac{\psi}{R(x, -x, x, 0)}$, and $R(x, y, \xi, \eta)$ is a Riemann function [2].

As will be seen below, assuming that $p_1(C_1) = 0$, $q_1(C_1) \neq 0$ at the point C_1 we can conclude that the derivatives u_x and u_y of the solution of problem (1), (2), (3) are continuous. In addition to this, we assume that $p_2(t) - q_2(t) \neq 0$, $t \in C_{1\delta}C$.

If $\tau_{\delta}(x)$ and $\nu_{\delta}(x)$ are sewn continuously on I_{δ} from (4), (5), then we obtain the equalities

a)
$$\delta\nu'(x) + (1 - \alpha\delta)\nu(x) = \frac{2(T(\tau, \nu) - \psi)}{p_2 - q_2} \exp(\alpha\delta)$$

+ $(1 + \alpha\delta)\tau'(x) - \alpha^2\delta\tau(x)$ for $p^2 - 4q = 0$;
b) $\operatorname{sh}\beta\delta\nu'(x) + (\beta\operatorname{ch}\beta\delta - \alpha\operatorname{sh}\beta\delta)\nu(x) = \frac{2\beta(\widetilde{T}(\tau, \nu) - \widetilde{\psi})}{p_2 - q_2} \exp(\alpha\delta)$

$$+ (\beta \operatorname{ch} \beta \delta + \alpha \operatorname{sh} \beta \delta) \tau'(x) - (\alpha^2 - \beta^2) \operatorname{sh} \beta \delta \tau(x)$$
for $p^2 - 4q > 0;$

$$(6)$$

c)
$$\sin\beta\delta\nu'(x) + (\beta\cos\beta\delta - \alpha\sin\beta\delta)\nu(x) = \frac{2\beta(\widetilde{T}(\tau,\nu) - \widetilde{\psi})}{p_2 - q_2} \exp(\alpha\delta) + (\beta\cos\beta\delta + \alpha\sin\beta\delta)\tau'(x) - (\alpha^2 + \beta^2)\sin\beta\delta\tau(x)$$

for $p^2 - 4q > 0$.

Solving (6) as a linear differential equation with respect to $\nu(x)$, the relations between $\tau(x)$ and $\nu(x)$ after some transformations can be written in the form

a)
$$\nu(t) \exp\left[\frac{1-\alpha\delta}{\delta}t\right] = \nu(0)$$

 $+ \int_{0}^{t} \left[\frac{2(\widetilde{T}(\tau,\nu)-\widetilde{\psi})}{\delta(p_{2}-q_{2})}\exp(\alpha\delta) - \alpha^{2}\tau(x)\right] \exp\left[\frac{1-\alpha\delta}{\delta}x\right] dx$
 $+ \frac{1+\alpha\delta}{\delta} \left[\tau(t)\exp\left(\frac{1-\alpha\delta}{\delta}t\right) - \tau(0)\right]$
 $- \frac{1-\alpha\delta}{\delta}\int_{0}^{t}\tau(x)\exp\left[\frac{(1-\alpha\delta)x}{\delta}\right] dx$ for $p^{2}-4q=0$;
b) $\nu(t)\exp\left[\frac{(\beta ch\beta\delta - \alpha sh\beta\delta)}{sh\beta\delta}t\right] = \nu(0) + \int_{0}^{t} \left[\frac{2(\widetilde{T}(\tau,\nu) - \widetilde{\psi})\beta}{sh\beta\delta(p_{2}-q_{2})}\exp(\alpha\delta)\right]$
 $- (\alpha^{2}-\beta^{2})\tau(x) \exp\left[\frac{\beta ch\beta\delta - \alpha sh\beta\delta}{sh\beta\delta}x\right] dx$
 $+ \frac{\beta ch\beta\delta + \alpha sh\beta\delta}{sh\beta\delta} \left[\tau(t)\exp\left(\frac{\beta ch\beta\delta - \alpha sh\beta\delta}{sh\beta\delta}t\right) - \tau(0)\right]$ (7)
 $- \frac{\beta ch\beta\delta - \alpha sh\beta\delta}{sh\beta\delta}\int_{0}^{t}\tau(x)\exp\left[\frac{\beta ch\beta\delta - \alpha sh\beta\delta}{sh\beta\delta}x\right] dx$

c)
$$\nu(t) \exp\left[\frac{(\beta\cos\beta\delta - \alpha\sin\beta\delta)}{\sin\beta\delta}t\right] = \nu(0) + \int_0^t \left[\frac{2(\tilde{T}(\tau,\nu) - \tilde{\psi})\beta}{\sin\beta\delta(p_2 - q_2)}\exp(\alpha\delta) - (\alpha^2 + \beta^2)\tau(x)\right] \exp\left[\frac{\beta\cos\beta\delta - \alpha\sin\beta\delta}{\sin\beta\delta}x\right] dx + \frac{\beta\cos\beta\delta + \alpha\sin\beta\delta}{\sin\beta\delta}\left[\tau(t)\exp\left(\frac{\beta\cos\beta\delta - \alpha\sin\beta\delta}{\sin\beta\delta}t\right) - \tau(0) - \frac{\beta\cos\beta\delta - \alpha\sin\beta\delta}{\sin\beta\delta}\int_0^t \tau(x)\exp\left[\frac{\beta\cos\beta\delta - \alpha\sin\beta\delta}{\sin\beta\delta}x\right] dx\right]$$

for $p^2 - 4q < 0$ and $\sin\beta\delta \neq 0$.

When $p^2 - 4q < 0$ and $\sin \beta \delta = 0$, (6) immediately implies the relation

$$\nu(t) = \frac{2(\widetilde{T}(\tau,\nu) - \widetilde{\psi})}{(p_2 - q_2)\cos\beta\delta} \exp(\alpha\delta) + \tau'(t).$$

Let us use a general representation of regular solutions of equation (1) in Ω_1 by analytic functions $\omega(z)$ [3]

$$u(x,y) = \operatorname{Re}\left\{\alpha(z,\overline{z})\omega(z) + \int_{p_0}^{z} \beta(z,\overline{z},t)\omega(t)\,dt\right\},\tag{8}$$

where $\omega(z)$ is an arbitrary analytic function in Ω_1 that satisfies the condition Im $\omega(p_0) = 0$, $p_0 \in \Omega_1$; $\alpha(z, \overline{z})$ and $\beta(z, \overline{z}, t)$ are entire functions of their arguments. I. Vekua proved that if $\omega(z) \in C^{1,h}(\Omega_1)$ is an analytic function in a 1-connected domain Ω_1 satisfying the condition Im $\omega(p_0) = 0$, then there exists a unique real function $\mu(t) \in C^{0,h}$ such that the formula

$$\omega(z) = \int_{\partial \Omega_1} \mu(t) \log e\left(1 - \frac{z}{t}\right) \, dS_t \tag{9}$$

holds, where dS_t are elements of an arc of the boundary $\partial\Omega_1$, while under log $e\left(1-\frac{z}{t}\right)$, $z \in \Omega_1$, $t \in \partial\Omega_1$, we understand a branch if this function that is equal to zero for z = 0. Assuming that (8) is a boundary condition [4], we can rewrite (2) equivalently as

$$\alpha_1(t)\mu(t) + \beta_1(t) \int_{\partial\Omega_1} \frac{\mu(t_1) dt_1}{t_1 - t} + \int_{\partial\Omega_1} K(t, t_1)\mu(t_1) dt_1 = \varphi(t), \quad t \in \partial\Omega_1 \setminus C_1 C_2,$$
(10)

where

$$\alpha_1(t) = \operatorname{Re}[-\pi t' \alpha(t, \overline{t})(p_1(t) + iq_1(t)),$$

$$\beta_1(t) = \operatorname{Im}[-i\overline{t}'(p_1(t) + iq_1(t))\alpha(t, \overline{t})],$$

$$\alpha(z, \overline{z}) = \exp\left[\int_0^{\overline{z}} p(z, \overline{t}) dt\right].$$

From (8) we find that [4]

$$\tau'(t) = \widetilde{\alpha}_1(t)\mu(t) + \widetilde{\beta}_1(t) \int_{\partial\Omega_1} \frac{\mu(t_1)\,dt_1}{t_1 - t} + K_1(\mu),\tag{11}$$

$$\nu(t) = \widetilde{\alpha}_2(t)\mu(t) + \widetilde{\beta}_2(t) \int_{\partial\Omega_1} \frac{\mu(t_1)\,dt_1}{t_1 - t} + K_2(\mu),\tag{12}$$

$$\widetilde{\alpha}_1(t) = \operatorname{Re}(-\pi i \alpha(t, \overline{t}) t'), \quad \widetilde{\beta}_1(t) = \operatorname{Im}(-i \alpha(t, \overline{t}) \overline{t}'),$$

$$\widetilde{\alpha}_2(t) = \operatorname{Re}(\pi \alpha(t, \overline{t}) t'), \quad \widetilde{\beta}_2(t) = \operatorname{Im}(\alpha(t, \overline{t}) t').$$

Here $K_1(\mu)$, $K_2(\mu)$ are completely defined integral operators.

Using formulas (8), (11), (12), from the boundary condition (3) we obtain a singular integral equation with Cauchy kernel which, together with equation (10) can be rewritten in the form of a singular equation on the whole boundary $\partial\Omega_1$

$$\alpha_i^*(t)\mu(t) + \beta_i^*(t) \int_{\partial\Omega_1} \frac{\mu(t_1)\,dt_1}{t_1 - t} + K_i^* = f_i^*(t) \quad (i = 1, 2, 3, 4), \tag{13}$$

where K_i^* (i = 1, 2, 3, 4) are completely defined compact linear integral operators, f_i^* (i = 1, 2, 3, 4) are the known functions, for $p^2 - 4q = 0$

$$\begin{aligned} \alpha_1^*(t) &= \begin{cases} \alpha_1(t), & t \in \partial\Omega_1 \setminus AB, \\ \widetilde{\alpha}_2(t) \exp\left[\frac{1-\alpha\sigma}{\sigma} f(t)\right], & t \in AB, \end{cases} \\ \beta_1^*(t) &= \begin{cases} \beta_1(t), & t \in \partial\Omega_1 \setminus AB, \\ \widetilde{\beta}_2(t) \exp\left[\frac{1-\alpha\sigma}{\sigma} f(t)\right], & t \in AB; \end{cases} \end{aligned}$$

for $p^2 - 4q > 0$

$$\begin{aligned} \alpha_2^*(t) &= \begin{cases} \alpha_1(t), & t \in \partial\Omega_1 \setminus AB, \\ \widetilde{\alpha}_2(t) \exp\left[(\alpha - \operatorname{cth} \beta \sigma) f(t)\right], & t \in AB, \end{cases} \\ \beta_2^*(t) &= \begin{cases} \beta_1(t), & t \in \partial\Omega_1 \setminus AB, \\ \widetilde{\beta}_2(t) \exp\left[\frac{1 - \alpha \sigma}{\sigma} f(t)\right], & t \in AB; \end{cases} \end{aligned}$$

for $p^2 - 4q < 0$, $\sin \beta \sigma \neq 0$

$$\alpha_3^*(t) = \begin{cases} \alpha_1(t), & t \in \partial\Omega_1 \setminus AB, \\ \widetilde{\alpha}_2(t) \left[(\alpha - \operatorname{ctg} \beta \sigma) f(t) \right], & t \in AB, \end{cases}$$
$$\beta_3^*(t) = \begin{cases} \beta_1(t), & t \in \partial\Omega_1 \setminus AB, \\ \widetilde{\beta}_2(t) \left[(\alpha - \operatorname{ctg} \beta \sigma) f(t) \right], & t \in AB. \end{cases}$$

for $p^2 - 4q < 0$, $\sin \beta \sigma = 0$

$$\begin{aligned} \alpha_4^*(t) &= \begin{cases} \beta_1(t), & t \in \partial\Omega_1 \setminus AB, \\ (p_2 + q_2) \cos \sigma \widetilde{\beta}_2(t) - 2(p_2 - q_2) \cos \beta \widetilde{\alpha}_1(t), & t \in AB, \end{cases} \\ f(x) &= \int_0^x \frac{p_2 + q_2}{p_2 - q_2} \, dt. \end{aligned}$$

So, in terms of solvability, problem (1), (2), (3) is equivalently reduced to the integral equation (13).

The solution $\mu(t)$ of the obtained singular integral equations is sought in the space $H^*(\partial\Omega_1)$ [5], assuming that the node of the curve $\partial\Omega_1$ is the point $C_2(1,0)$, while the index of (13) is calculated in the same manner as in [1].

Thus the following theorem is valid.

Theorem. Let the conditions

1)
$$H(t) = p_1(t) + iq_1(t) \neq 0, t \in \sigma,$$

2) $p_1(C_1) = 0,$
3) $p_2^2(t) - q_2^2(t) \neq 0, t \in C_1C_2, \varphi(0) = \psi(0)$

be fulfilled. Then problem (1), (2), (3) is Noetherian.

In this direction a special mention should be made of work [6].

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