## T. KIGURADZE

## ON INITIAL–BOUNDARY VALUE PROBLEMS FOR DEGENERATE LINEAR HYPERBOLIC SYSTEMS

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Let l, m and  $n \ge 2$  be natural numbers,  $0 < b < +\infty$  and  $I \subset \mathbb{R}$  be a compact interval containing zero. In the rectangle  $\Omega = I \times (0, b)$  consider the hyperbolic system

$$\gamma_n(y)u^{(m,n)} = \sum_{k=0}^{n-1} \gamma_k(y) P_{mk}(x,y)u^{(m,k)} + \sum_{j=0}^{m-1} \sum_{k=0}^n \gamma_k(y) P_{jk}(x,y)u^{(j,k)} + q(x,y)$$
(1)

with the initial–boundary conditions

$$u^{(j,0)}(0,y) = \varphi_j(y) \ (j = 0, \dots, m-1),$$
  

$$h_k(u^{(m,0)}(x,\cdot))(x) = \psi_k(x) \ (k = 1, \dots, n),$$
(2)

where

$$u^{(j,k)}(x,y) = \frac{\partial^{j+k}u(x,y)}{\partial x^{j}\partial y^{k}} \quad (j = 0, \dots, m; \ k = 0, \dots, n),$$
  
$$y_{k}(y) = y^{k}(b-y)^{k} \quad (k = 0, \dots, n-1), \quad \gamma_{n}(y) = \gamma_{n-1}(y).$$

Everywhere below it will be assumed that  $P_{jk}: \Omega \to \mathbb{R}^{l \times l}$   $(j = 0, \ldots, m; k = 0, \ldots, n; j + k < m + n)$  are continuous and bounded matrix functions,  $q: \Omega \to \mathbb{R}^{l}$  and  $\psi_{k}: I \to \mathbb{R}^{l}$   $(k = 1, \ldots, n)$  are continuous and bounded vector functions,  $\varphi_{j}: (0, b) \to \mathbb{R}^{l}$   $(j = 0, \ldots, m - 1)$  are *n*-times continuously differentiable vector functions such that

$$\sup \left\{ \gamma_k(y) \| \varphi_j^{(k)}(y) \| : 0 < y < b \right\} < +\infty \quad (j = 0, \dots, m-1; \ k = 0, \dots, n),$$

and  $h_k: C([0,b]; \mathbb{R}^l) \to C(I; \mathbb{R}^l)$  (k = 1, ..., n) are bounded linear operators.

System (1) degenerates along the intervals y = 0 and y = b. These degeneration is removable only when  $P_{jk}$  and q admit the representation

$$P_{jk}(x,y) = \frac{\gamma_n(y)}{\gamma_k(y)} \widetilde{P}_{jk}(x,y) \quad (j=0,\ldots,m; \ k=1,\ldots,n), \quad q(x,y) = \gamma_n(y)\widetilde{q}(x,y),$$

i.e., when system (1) has the form

$$u^{(m,n)} = \sum_{k=0}^{n-1} \widetilde{P}_{mk}(x,y)u^{(m,k)} + \sum_{j=0}^{m-1} \sum_{k=0}^{n} \widetilde{P}_{jk}(x,y)u^{(j,k)} + \widetilde{q}(x,y),$$

where  $\widetilde{P}_{jk}: \overline{\Omega} \to \mathbb{R}^{l \times l}$  (j = 0, ..., m; k = 0, ..., n; j + k < m + n) and  $\widetilde{q}: \overline{\Omega} \to \mathbb{R}^{l}$  are continuous matrix and vector functions. In this case the criterion of well–posedness of problem (1),(2) is established in [3]. However, in the case, where degeneration is not removable (e.g., when  $\limsup_{y\to 0} \|P_{jk}(x,y)\| > 0$ , or  $\limsup_{y\to b} \|P_{jk}(x,y)\| > 0$  for

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some  $x \in I$  and  $j \in \{0, \ldots, m\}$ ) the question of well-posedness of problem (1), (2) was opened. The results formulated below concern this case namely.

Throughout the paper we will use the following notation:

 $\mathbb{R} = (-\infty, +\infty);$ 

 $\mathbb{R}^{l}$  is the space of column-vectors  $z = (z_{i})_{i=1}^{l}$  with the real components  $z_{i} \in \mathbb{R}$ (i = 1, ..., l) and the norm  $||z|| = \max\{|z_{1}|, ..., |z_{l}|\};$  $\mathbb{R}^{l \times l}$  is the space of  $l \times l$  matrices  $Z = (z_{ik})_{i,k=1}^{l}$  with the components  $z_{ik} \in \mathbb{R}$ 

 $(i, k = 1, \ldots, l)$  and the norm

$$||Z|| = \max\left\{\sum_{k=1}^{l} |z_{ik}| : i = 1, \dots, l\right\};$$

If  $z = (z_i)_{i=1}^l \in \mathbb{R}^l$  and  $Z = (z_{ik})_{i,k=1}^l \in \mathbb{R}^{l \times l}$ , then

$$|z| = (|z_i|)_{i=1}^l, \quad |Z| = (|z_{ik}|)_{i,k=1}^l;$$

 $Z^{-1}$  is the matrix reciprocal to a nonsingular matrix  $Z \in \mathbb{R}^{l \times l};$ 

r(Z) is the spectral radius of a matrix  $Z \in \mathbb{R}^{l \times l}$ ;

 $C(I;\mathbb{R}^l)$  and  $C(\Omega;\mathbb{R}^l)$  are the spaces of continuous and bounded vector functions  $\varphi: I \to \mathbb{R}^l$  and  $z: \Omega \to \mathbb{R}^l$  with the norms

$$\|\varphi\|_{C(I;\mathbb{R}^l)} = \sup\{\|\varphi(s)\|: s \in I\}, \quad \|z\|_{C(\Omega;\mathbb{R}^l)} = \sup\{\|z(x,y)\|: (x,y) \in \Omega\};$$

 $S^n((0,b);\mathbb{R}^l)$  is the space of *n*-times continuously differentiable functions  $\varphi:(0,b)\to$  $\mathbb{R}^l$  such that

$$\|\varphi\|_{S^{n}((0,b);\mathbb{R}^{l})} = \sup\left\{\sum_{k=0}^{n} \gamma_{k}(y)\|\varphi^{(k)}(y)\| : 0 < y < b\right\} < +\infty;$$

 $S^{m,n}(\Omega;\mathbb{R}^l)$  is the space of functions  $u:\Omega\to\mathbb{R}^l$  having the continuous partial derivatives  $u^{(j,k)}$  (j = 0, ..., m; k = 0, ..., n) such that

$$\|u\|_{S^{m,n}(\Omega;\mathbb{R}^l)} = \sup\left\{\sum_{j=0}^m \sum_{k=0}^n \gamma_k(y) \|u^{(j,k)}(x,y)\| : (x,y) \in \Omega\right\} < +\infty;$$

If  $\varphi \in S^n((0,b); \mathbb{R}^l)$  and  $u \in S^{m,n}(\Omega; \mathbb{R}^l)$ , then there exist the limits

$$\lim_{y\to 0}\varphi(y), \quad \lim_{y\to b}\varphi(y), \quad \lim_{y\to 0}u^{(j,0)}(x,y), \quad \lim_{y\to b}u^{(j,0)}(x,y) \quad (j=0,\ldots,m),$$

which are denoted by  $\varphi(0)$ ,  $\varphi(b)$ ,  $u^{(j,0)}(x,0)$ ,  $u^{(j,0)}(x,b)$  (j = 0, ..., m).

By a solution of problem (1),(2) we understand a vector function  $u \in S^{m,n}(\Omega; \mathbb{R}^l)$ satisfying system (1) and conditions (2) in  $\Omega$ .

**Definition.** Problem (1),(2) is called *well-posed* if it is uniquely solvable for arbitrary  $q \in C(\Omega; \mathbb{R}^l), \varphi_j \in S^n((0, b); \mathbb{R}^l) \ (j = 0, \dots, m-1), \psi_k \in C(I; \mathbb{R}^l) \ (k = 1, \dots, n) \text{ and for}$ an arbitrary interval  $J \subset I$  containing zero the restriction of a solution of this problem on  $J \times (0, b)$  admits the estimate

$$\|u\|_{S^{m,n}(J\times(0,b);\mathbb{R}^{l})} \leq \rho \Big( \sum_{j=0}^{m-1} \|\varphi_{j}\|_{S^{n}((0,b);\mathbb{R}^{l})} + \sum_{k=1}^{n} \|\psi_{k}\|_{C(J;\mathbb{R}^{l})} + \|q\|_{C(J\times(0,b);\mathbb{R}^{l})} \Big),$$
(3)

where  $\rho$  is a positive constant independent of  $q, \varphi_j, \psi_k$   $(j = 0, \dots, m-1; k = 1, \dots, n)$ and J.

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For an arbitrarily fixed  $x \in I$  in the interval (0, b) consider the system of ordinary differential equations

$$\gamma_n(y)\frac{d^n v}{dy^n} = \sum_{k=0}^{n-1} \gamma_k(y) P_{mk}(x,y) \frac{d^k v}{dy^k} \tag{4}$$

with the homogeneous boundary conditions

$$h_k(v)(x) = 0 \quad (k = 1, \dots, n).$$
 (5)

We will seek for a solution of problem (4),(5) in the class of vector functions  $z: [0, b] \rightarrow$  $\mathbb{R}^l$  continuous on [0, b] and *n*-times continuously differentiable in (0, b).

**Theorem.** Problem (1), (2) is well-posed if and only if for any  $x \in I$  problem (3), (4)has only a trivial solution.

To prove the Theorem we need to give two auxiliary propositions. The first of them concerns continuity with respect to x of a solution of the problem

$$\gamma_n(y)\frac{d^n v}{dy^n} = \sum_{k=0}^{n-1} \gamma_k(y) P_{mk}(x,y) \frac{d^k v}{dy^k} + q_0(y), \tag{6}$$

$$h_k(v)(x) = c_k \quad (k = 1, \dots, n).$$
 (7)

**Lemma 1.** Let for any  $x \in I$  problem (4), (5) have only a trivial solution. Then for an arbitrary  $q_0 \in C((0,b); \mathbb{R}^l)$ ,  $c_k \in \mathbb{R}^l$  (k = 1, ..., n) and  $x \in I$  problem (6), (7) has a unique solution  $v(x, \cdot)$  which is continuous with respect to x. Moreover, the vector functions  $v^{(0,k)}: \Omega \to \mathbb{R}^l$  (k = 0, ..., n - 1) are continuous and there exists a positive constant  $\rho_0$ , independent of  $q_0$  and  $c_k$  (k = 1, ..., n), such that the inequality

$$\sum_{k=0}^{n} \gamma_{k}(y) \| v^{(0,k)}(x,y) \| \le \rho_{0} \Big( \sum_{k=1}^{n} \| c_{k} \| + \| q_{0} \|_{C((0,b);\mathbb{R}^{l})} \Big)$$

holds in  $\Omega$ .

This lemma follows from Theorem 1.1 from [2].

The following lemma concerns the operator equation

u(x,y) = g(u)(x,y) + f(x,y),where  $g: S^{m,n}(\Omega; \mathbb{R}^l) \to S^{m,n}(\Omega; \mathbb{R}^l)$  is a linear bounded operator and  $f \in S^{m,n}(\Omega; \mathbb{R}^l)$ . For an arbitrary  $i \in \{0, ..., m\}$  and  $z \in C^{m,n}(\Omega; \mathbb{R}^l)$  set

$$\|z^{(i,0)}(x,\cdot)\|_{S^n((0,b);\mathbb{R}^l)} = \sup\Big\{\sum_{k=0}^n \gamma_k(y)\|z^{(i,k)}(x,y)\| : 0 < y < b\Big\}.$$

**Lemma 2.** Let there exist a positive number  $\rho_1$  such that for any  $z \in S^{m,n}(\Omega; \mathbb{R}^l)$ the inequality

$$\sum_{i=0}^{m} \left\| \frac{\partial^{i} g(z)(x,\cdot)}{\partial x^{i}} \right\|_{S^{n}((0,b);\mathbb{R}^{l})} \le \rho_{1} \sum_{i=0}^{m} \left| \int_{0}^{x} \left\| z^{(i,0)}(\xi,\cdot) \right\|_{S^{n}((0,b);\mathbb{R}^{l})} d\xi \right|$$
(9)

holds in I. Then equation (8) has a unique solution u in the space  $S^{m,n}(\Omega; \mathbb{R}^l)$  and

$$\sum_{i=0}^{m} \left\| u^{(i,0)}(x,\cdot) \right\|_{S^{n}((0,b);\mathbb{R}^{l})} \le \rho_{1} \exp(|x|) \sum_{i=0}^{m} \left\| f^{(i,0)}(x,\cdot) \right\|_{S^{n}((0,b);\mathbb{R}^{l})} \quad for \ x \in I.$$
(10)

This lemma can be proved similarly to Lemma 2.3 from [3].

Proof of the Theorem. We will prove the sufficiency since the necessity can be proved by the method applied in [3] for proving Theorem 1.1.

By Lemma 1, there exists a linear bounded operator

$$g_0: \mathbb{R}^l \times C((0,b); \mathbb{R}^l) \to S^{0,n}(\Omega; \mathbb{R}^l)$$

such that if  $x \in I$ ,  $c_k \in \mathbb{R}^l$  (k = 1, ..., n) and  $q_0 \in C((0, b); \mathbb{R}^l)$ , then the vector function  $v(x, \cdot) : (0, b) \to \mathbb{R}^l$  is a solution of problem (6),(7) if and only if

$$v(x, y) = g_0(c_1, \dots, c_l, q_0)(x, y)$$
 for  $0 < y < b$ .

For an arbitrary  $z \in S^{m,n}(\Omega; \mathbb{R}^l)$  set

$$w(z)(x,y) = \sum_{j=0}^{m-1} \sum_{k=0}^{n} \frac{\gamma_k(y)}{(m-j-1)!} P_{jk}(x,y) \int_0^x (x-s)^{m-j-1} z^{(m,k)}(s,y) \, ds, \qquad (11)$$

$$g(z)(x,y) = \frac{1}{(m-1)!} \int_{0}^{x} (x-s)^{m-1} g_0(0,\dots,0,w(z)(s,\cdot))(s,y) \, ds.$$
(12)

Furthermore, introduce the vector functions

$$w_0(x,y) = \sum_{j=0}^{m-1} \sum_{k=0}^n \gamma_k(y) P_{jk}(x,y) \sum_{i=j}^{m-1} \frac{x^{i-j}}{(i-j)!} \varphi_i^{(k)}(y) + q(x,y),$$
(13)

$$f(x,y) = \frac{1}{(m-1)!} \int_{0}^{x} (x-s)^{m-1} g_0(\psi_1(s), \dots, \psi_l(s), w_0(s, \cdot))(s,y) \, ds.$$
(14)

In view of notation (11)–(14) it is not difficult to see that problem (1),(2) is equivalent to equation (8), i.e., every solution of problem (1),(2) is a solution of equation (8) and vice versa. Therefore to prove the theorem it is sufficient to show that in the space  $S^{m,n}(\Omega; \mathbb{R}^l)$  equation (8) has a unique solution admitting estimate (3) on every interval  $J \subset I$  containing zero, where  $\rho$  is a positive constant independent of  $q, \varphi_j, \psi_k$   $(j = 0, \ldots, m-1; k = 1, \ldots, n)$  and J.

By Lemma 1, there exists a positive constant  $\rho_0$  such that for arbitrary  $c_j \in \mathbb{R}^l$ (j = 1, ..., l) and  $q_0 \in C((0, b); \mathbb{R}^l)$  the inequality

$$\sum_{k=0}^{n} \gamma_{k}(y) \Big| \frac{\partial^{k}}{\partial y^{k}} g_{0}(c_{1}, \dots, c_{l}, q_{0})(x, y) \Big| \le \rho_{0} \Big( \sum_{k=1}^{n} \|c_{k}\| + \|q_{0}\|_{C((0, b); \mathbb{R}^{l})} \Big)$$
(15)

holds in the rectangle  $\Omega$ . According to equalities (11),(13) and boundedness of the matrix functions  $P_{jk}$  (j = 0, ..., m - 1; k = 0, ..., n), without loss of generality we may assume that the inequalities

$$\|w(z)(x,\cdot)\|_{C((0,b);\mathbb{R}^l)} \le \rho_0 \Big| \int_0^x \|z^{(m,0)}(s,\cdot)\|_{S^n((0,b);\mathbb{R}^l)} \, ds \Big|, \tag{16}$$

$$\|w_0(x,\cdot)\|_{C((0,b);\mathbb{R}^l)} \le \rho_0 \Big(\sum_{j=0}^{m-1} \|\varphi_j\|_{S^n((0,b);\mathbb{R}^l)} + \|q(x,\cdot)\|_{C((0,b);\mathbb{R}^l)}\Big)$$
(17)

hold on I.

In view of conditions (15) and (16), inequality (9) follows from (12), where

$$\rho_1 = \rho_0^2 \sum_{i=0}^m \frac{1}{(m-i)!} |I|^{m-i}$$

and |I| is the length of the interval I. On the other hand, by (15) and (17), it follows from (14) that for an arbitrary interval  $J \subset I$  the function f admits the estimate

$$\|f\|_{S^{m,n}(J\times(0,b);\mathbb{R}^{l})} \leq \rho_{1} \Big( \sum_{j=0}^{m-1} \|\varphi_{j}\|_{S^{n}((0,b);\mathbb{R}^{l})} + \sum_{k=1}^{n} \|\psi_{k}\|_{C(J;\mathbb{R}^{l})} + \|q\|_{C(J\times(0,b);\mathbb{R}^{l})} \Big).$$
(18)

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By Lemma 2, in the space  $S^{m,n}(\Omega; \mathbb{R}^l)$  equation (8) has a unique solution admitting estimate (10). However, estimate (3) follows from (10) and (18), where  $\rho = \rho_1^2 \exp(|I|)$  is a positive constant independent of q,  $\varphi_j$ ,  $\psi_k$   $(j = 0, \ldots, m-1; k = 1, \ldots, n)$  and J.

The initial–boundary conditions

 $u^{(j,0)}(0,y) = \varphi_j(y) \quad (j = 0, \dots, m-1), \quad u^{(m,0)}(x, y_k(x)) = \psi_k(x) \quad (k = 1, \dots, n) \quad (19)$ are the particular case of (2), where  $y_k : I \to \mathbb{R} \quad (k = 1, \dots, n)$  are continuous functions satisfying the inequalities

$$0 \le y_1(x) < y_2(x) \le \dots < y_n(x) \le b \quad \text{for} \quad x \in I.$$

Let  $g(\cdot,\cdot;x): [y_1(x),y_n(x)] \times [y_1(x),y_n(x)] \to \mathbb{R}$  be the Green's function of the differential equation

$$\frac{d^n v}{dy^n} = 0$$

with multi-point boundary conditions

$$v(y_k(x)) = 0$$
  $(k = 1, ..., n).$  (20)

Then by Lemma 8.5 from [1], we have

$$\mu_{nj}(x) \stackrel{def}{=} \sup \left\{ \frac{\gamma_j(y)}{\gamma_n(t)} \left| \frac{\partial^j g(y,t;x)}{\partial y^j} \right| : y_1(x) < y, \ t < y_n(x), \ y \neq t \right\} < < +\infty \quad \text{for} \quad x \in I \quad (j = 0, \dots, n-1).$$
(21)

Corollary. If

$$r\Big(\sum_{k=0}^{n-1}\mu_{nk}(x)\int_{y_1(x)}^{y_n(x)}|P_{mk}(x,t)|\,dt\Big) < 1 \quad for \ x \in I,$$
(22)

then problem (1), (19) is well-posed.

*Proof.* Let  $v = (v_i)_{i=1}^l$  be a solution of problem (4),(20) for an arbitrarily fixed  $x \in I$ . By the above proved theorem, to prove the Corollary we need to show that  $v(y) \equiv 0$ . It is easy to see

$$w_i = \sup\left\{\frac{\gamma_k(y)}{\mu_{nk}(x)}|v_l^{(k)}(y)| : 0 < y < b; \ k = 0, \dots, n-1\right\} < +\infty \quad (i = 1, \dots, l).$$

Set  $w = (w_i)_{i=1}^l$ . Then taking into account (21) from the equalities

$$\gamma_j(y)v^{(j)}(y) = \int_{y_1(x)}^{y_n(x)} \frac{\gamma_j(y)}{\gamma_n(t)} \frac{\partial^j g(y,t;x)}{\partial y^j} \Big(\sum_{k=0}^{n-1} P_{mk}(x,t)\gamma_k(t)v^{(k)}(t)\Big) dt \quad (j=0,\dots,n-1)$$

we find

$$w \le \Big(\sum_{k=0}^{m-1} \mu_{mk}(x) \int_{y_1(x)}^{y_n(x)} |P_{mk}(x,t)| \, dt \Big) w.$$

Hence in view of conditions (22) and nonnegativity of the vector w we get w = 0. Consequently  $v(y) \equiv 0$ .  $\Box$ 

 $Remark \ 1.$  Condition (22) is nonimprovable in the sense that it cannot be replaced by the condition

$$r\Big(\sum_{k=0}^{n-1}\mu_{nk}(x)\int_{y_1(x)}^{y_n(x)}|P_{mk}(x,t)|\,dt\Big)<1+\varepsilon$$

for arbitrarily small  $\varepsilon > 0$ .

Remark 2. It immediately follows from (21) that

$$\mu_{20}(x) = \frac{1}{y_2(x) - y_1(x)}, \quad \mu_{21}(x) = 1 \text{ for } x \in I.$$

Therefore in the case, where n = 2 condition (2) coincides with the condition of unique solvability of two-point problem (4),(20) given in [4].

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Author's address:

Faculty of Physics I. Javakhishvili Tbilisi State University 3, Chavchavadze Ave., Tbilisi 380028 Georgia E-mail: tkig@rmi.acnet.ge