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ON THE SOLVABILITY OF A MULTIDIMENSIONAL VERSION OF THE GOURSAT PROBLEM FOR A SECOND ORDER HYPERBOLIC EQUATION WITH CHARACTERISTIC DEGENERATION **Abstract.** A multidimensional version of the Goursat problem is considered for a second order hyperbolic equation with characteristic degeneration. Using the technique of functional spaces with a negative norm the correct formulation of this problem in the Sobolev weighted space is given.

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რეზიუმე. განხილულია გურსას ამოცანის მრავალგანზომილებიანი ვერსია მეორე რიგის ჰიპერბოლური განტოლებისათვის მახასიათებელი გადაგვარებით. უარყოფით ნორმიანი ფუნქციონალური სივრცეების ტექნიკის გამოყენებით მოცემულია ამ ამოცანის კორექტული ფორმულირება სობოლევის წონიან სივრცეში. In the space of variables x_1 , x_2 , t we shall consider a second order degenerating hyperbolic equation of the form

$$Lu \equiv u_{tt} - u_{x_1x_1} - (|x_2|^m u_{x_2})_{x_2} + a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u = F,$$
(1)

where a_i , i = 1, ..., 4, F are the given real functions and u is the desired real function, $1 \le m = const < 2$.

Denote by

$$D: \frac{2}{2-m}x_2^{\frac{2-m}{2}} < t < 1 - \frac{2}{2-m}x_2^{\frac{2-m}{2}}, \quad 0 < x_2 < \left(\frac{2-m}{4}\right)^{\frac{2}{2-m}}$$

the unbounded domain lying in a half-space $x_2 > 0$ bounded by the characteristic surfaces

$$S_1: t - \frac{2}{2-m} x_2^{\frac{2-m}{2}} = 0, \quad 0 < x_2 < \left(\frac{2-m}{4}\right)^{\frac{2}{2-m}},$$
$$S_2: t + \frac{2}{2-m} x_2^{\frac{2-m}{2}} = 1, \quad 0 < x_2 < \left(\frac{2-m}{4}\right)^{\frac{2}{2-m}}$$

of equation (1) and by the two-dimensional surface $S_0: x_2 = 0, 0 < t < 1$ on which this equation has characteristic degeneration. It will be assumed below that in the domain D the coefficients $a_i, i = 1, ..., 4$, of equation (1) are the bounded functions from the class $C^2(\overline{D})$.

For equation (1) we shall consider a multidimensional version of the Goursat problem formulated as follows: in the domain D find a solution $u(x_1, x_2, t)$ of equation (1) satisfying the boundary condition

$$u \mid_{S_1} = 0.$$
 (2)

In a similar manner we formulate the problem for the equation

$$L^* v \equiv v_{tt} - v_{x_1 x_1} - (|x_2|^m v_{x_2})_{x_2} - (a_1 v)_{x_1} - (a_2 v)_{x_2} - (a_3 v)_t + a_4 v = F$$
(3)

in the domain D using the boundary condition

$$v\mid_{S_2}=0,\tag{4}$$

where L^* is the formal conjugate operator of L.

Similar problems, in which, along with condition (2), it is required that the condition $u \mid_{S_0} = 0$ or $\frac{\partial u}{\partial n} \mid_{S_0} = 0$ be fulfilled on the section S_0 of the boundary ∂D of the domain D, are investigated in [1–6] for m = 0 when equation (1) is not the degenerating one and has, in its principal part, a wave operator. As will be shown below, by virtue of the degeneration character of equation (1), where $1 \leq m < 2$, we can get rid of the fulfillment of any boundary condition on the section S_0 of the boundary ∂D of the domain D, since problem (1), (2) will turn out to be correctly formulated. In the case of a second order hyperbolic equation with noncharacteristic degeneration of the form

$$u_{tt} - |x_2|^m u_{x_1x_1} - u_{x_2x_2} + a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u = F$$

a multidimensional variant of the first Darboux problem is studied in [7]. Other variants of the multidimensional Goursat and Darboux problems are treated in [8–10].

Denote by E and E^* the classes of functions from the Sobolev space $W_2^2(D)$ satisfying the boundary condition (2) or (4), respectively. Let $W_+(W_+^*)$ be the Hilbert space with weight obtained by the closure of the space $E(E^*)$ with respect to the norm

$$\|u\|_{1,+}^2 = \int_D (u_t^2 + u_{x_1}^2 + x_2^m u_{x_2}^2 + u^2) dD.$$

Remark 1. Since $m \geq 1$, by virtue of the familiar embedding theorems for Sobolev weighted spaces [11] the class of functions $E_0(E_0^*)$ belonging to the space $C^{\infty}(\overline{D})$, having the bounded carriers (i.e., diam $\operatorname{supp} u < +\infty$), satisfying the boundary condition (2) ((4)) and vanishing in some neighborhood (each function has its own neighborhood) of the surface S_0 , is a dense subspace of the weighed space $W_+(W_+^*)$. Therefore, below it will be sometimes convenient for us to use, instead of the spaces E and E^* , the spaces E_0 and E_0^* .

Denote by $W_{-}(W_{-}^{*})$ the space with negative norm constructed with respect to $L_{2}(D)$ and $W_{+}(W_{+}^{*})$ [12].

Consider the condition

$$M = \sup_{\overline{D}} \left| x_2^{-\frac{m}{2}} a_2(x_1, x_2, t) \right| < +\infty$$
 (5)

on the lower coefficient a_2 in equation (1).

The uniqueness theorem for solutions of problem (1), (2) belonging to the Sobolev space $W_2^2(D)$ is provided by

Lemma 1. Let condition (5) be fulfilled. Then for any $u \in W_2^2(D)$ satisfying the condition

$$\int_{S_1} \left[u^2 + x_2^{\frac{m}{2}} u_{x_1}^2 + x_2^{-\frac{m}{2}} \left(\frac{\partial u}{\partial N} \right)^2 \right] ds < +\infty$$
(6)

there holds the following a priori estimate

$$||u||_{1,+} \le c \big(||f||_{1,*} + ||F||_{L_2(D)} \big), \tag{7}$$

where the positive constant c does not depend on u; $f = u |_{S_1}$, F = Lu,

$$||f||_{1,*}^2 = \int_{S_1} \left[f^2 + x_2^{\frac{m}{2}} f_{x_1}^2 + x_2^{-\frac{m}{2}} \left(\frac{\partial f}{\partial N} \right)^2 \right] ds,$$

 $\frac{\partial}{\partial N}|_{S_1} = -(1+x_2^{-m})^{-\frac{1}{2}} \left[\frac{\partial}{\partial t} + x_2^m \frac{\partial}{\partial x_2} \right] \text{ is the derivative with respect to the conormal which is the internal differential operator on the characteristic surface S_1.$

Proof. Let $n = (\nu_1, \nu_2, \nu_0)$ be the unit vector of the external normal to ∂D , i.e., $\nu_1 = \cos(\widehat{n, x_1}), \nu_2 = \cos(\widehat{n, x_2}), \nu_0 = \cos(\widehat{n, t})$. By definition, the derivative with respect to the conormal on the boundary ∂D of the domain D for the operator L is calculated by the formula

$$\frac{\partial}{\partial N} = \nu_0 \frac{\partial}{\partial t} - \nu_1 \frac{\partial}{\partial x_1} - x_2^m \nu_2 \frac{\partial}{\partial x_2}.$$

Applying integration by parts, we have for $u \in W_2^2(D)$ and $\lambda = const > 0$:

$$2 \int_{D} e^{-\lambda t} u_{tt} u_{t} dD = \int_{\partial D} e^{-\lambda t} u_{t}^{2} \nu_{0} ds + \int_{D} \lambda e^{-\lambda t} u_{t}^{2} dD, \qquad (8)$$

$$-2 \int_{D} e^{-\lambda t} \left[u_{x_{1}x_{1}} u_{t} + (x_{2}^{m} u_{x_{2}})_{x_{2}} u_{t} \right] dD = -2 \int_{\partial D} e^{-\lambda t} (u_{x_{1}} u_{t} \nu_{1} + x_{2}^{m} u_{x_{2}} u_{t} \nu_{2}) ds + 2 \int_{D} e^{-\lambda t} (u_{x_{1}} u_{x_{1}t} + x_{2}^{m} u_{x_{2}} u_{x_{2}t}) dD =$$

$$= -2 \int_{\partial D} e^{-\lambda t} (u_{x_{1}} u_{t} \nu_{1} + x_{2}^{m} u_{x_{2}} u_{t} \nu_{2}) ds + \int_{D} e^{-\lambda t} \frac{\partial}{\partial t} (u_{x_{1}}^{2} + x_{2}^{m} u_{x_{2}}^{2}) dD =$$

$$= -2 \int_{\partial D} e^{-\lambda t} (u_{x_{1}} u_{t} \nu_{1} + x_{2}^{m} u_{x_{2}} u_{t} \nu_{2}) ds + \int_{D} e^{-\lambda t} (u_{x_{1}}^{2} + x_{2}^{m} u_{x_{2}}^{2}) \nu_{0} ds + \int_{D} e^{-\lambda t} \lambda (u_{x_{1}}^{2} + x_{2}^{m} u_{x_{2}}^{2}) dD. \qquad (9)$$

It is easy to verify that

$$\nu_{0}|_{S_{0}} = \nu_{1}|_{S_{0}} = 0, \quad \frac{\partial u}{\partial N}|_{S_{0}} = 0,$$

$$n|_{S_{1}} = \left(0, (1 + x_{2}^{-m})^{-\frac{1}{2}}x_{2}^{-\frac{m}{2}}, -(1 + x_{2}^{-m})^{-\frac{1}{2}}\right),$$

$$\nu_{0}|_{S_{2}} \ge 0, \quad (\nu_{0}^{2} - \nu_{1}^{2} - x_{2}^{m}\nu_{2}^{2})|_{S_{1} \cup S_{2}} = 0.$$
(10)

On multiplying both parts of equation (1) by $2e^{-\lambda t}u_t$, where F = Lu, and integrating the resulting expression with respect to the domain D we obtain by virtue of (6) and (8)–(10)

$$\begin{split} 2(Lu, e^{-\lambda t}u_t)_{L_2(D)} &= \int\limits_{S_1 \cup S_2} e^{-\lambda t} \left[(u_t^2 + u_{x_1}^2 + x_2^m u_{x_2}^2) \nu_0 - \right. \\ &\left. - 2(u_{x_1}u_t\nu_1 + x_2^m u_{x_2}u_t\nu_2) \right] ds + 2 \int\limits_D e^{-\lambda t} \left[a_1 u_{x_1} + a_2 u_{x_2} + \right. \\ &\left. + a_3 u_t + a_4 u \right] u_t dD + \int\limits_D e^{-\lambda t} \lambda \left[u_t^2 + u_{x_1}^2 + x_2^m u_{x_2}^2 \right] dD = \\ &= \int\limits_{S_1 \cup S_2} e^{-\lambda t} \nu_0^{-1} \left[(\nu_0 u_{x_1} - \nu_1 u_t)^2 + x_2^m (\nu_0 u_{x_2} - \nu_2 u_t)^2 + \right. \\ &\left. + (\nu_0^2 - \nu_1^2 - x_2^m \nu_2^2) u_t^2 \right] ds + 2 \int\limits_D e^{-\lambda t} \left[\lambda (u_t^2 + u_{x_1}^2 + x_2^m u_{x_2}^2) + \right. \\ &\left. + 2(a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u) u_t \right] dD \ge \\ &\ge 2 \int\limits_D e^{-\lambda t} \left[\lambda (u_t^2 + u_{x_1}^2 + x_2^m u_{x_2}^2) + 2(a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u) u_t \right] dD - \end{split}$$

$$-\int_{S_{1}} e^{-\lambda t} \Big[(1+x_{2}^{-m})^{-\frac{1}{2}} u_{x_{1}}^{2} + (1+x_{2}^{-m})^{\frac{1}{2}} \Big(\frac{\partial u}{\partial N} \Big)^{2} \Big] ds \geq 2 \int_{D} e^{-\lambda t} \Big[\lambda (u_{t}^{2}+u_{x_{1}}^{2}+x_{2}^{m}u_{x_{2}}^{2}) + 2(a_{1}u_{x_{1}}+a_{2}u_{x_{2}}+a_{3}u_{t}+a_{4}u)u_{t} \Big] dD - \\ -2 \int_{S_{1}} \Big[x_{2}^{\frac{m}{2}} u_{x_{1}}^{2} + x_{2}^{-\frac{m}{2}} \Big(\frac{\partial u}{\partial N} \Big)^{2} \Big] ds.$$
(11)

In deriving inequality (11), we used the fact that

$$\left(\frac{\partial u}{\partial N}\right)^2\Big|_{S_1} = x_2^m (\nu_0 u_{x_2} - \nu_2 u_t)^2\Big|_{S_1}.$$

The structure of the domain ${\cal D}$ allows one to easily verify the validity of the inequality

$$\int_{D} u^2 dD \le c_0 \left[\int_{S_1} u^2 ds + \int_{D} u_t^2 dD \right]$$
(12)

for some $c_0 = const > 0$ not depending on $u \in W_2^2(D)$.

By inequality (5) we readily obtain

$$|2a_2u_xu_t| \le 2M(x_2^{\frac{m}{2}}u_{x_2})u_t \le M(x_2^mu_{x_2}^2 + u_t^2).$$
(13)

By virtue of (12) and (13), inequality (11) implies for sufficiently large λ that

$$2(Lu, e^{-\lambda t}u_t)_{L_2(D)} \ge c_1 \int_D (u_t^2 + u_{x_1}^2 + x_2^m u_{x_2}^2 + u^2) dD - - c_2 \int_{S_1} \left[u^2 + x_2^{\frac{m}{2}} u_{x_1}^2 + x_2^{-\frac{m}{2}} \left(\frac{\partial u}{\partial N}\right)^2 \right] ds,$$
(14)

where the positive constants c_1 and c_2 do not depend on u and the constant c_1 can be chosen arbitrarily large depending on λ . Therefore (14) obviously implies estimate (7).

Remark 2. Since for the operator L the derivative with respect to the conormal $\frac{\partial}{\partial N}$ is the internal differential operator on the characteristic surfaces of equation (1), by virtue of (2) and (4) we find for the functions $u \in E$ and $v \in E^*$ that

$$\frac{\partial u}{\partial N}\Big|_{S_1} = 0, \quad \frac{\partial v}{\partial N}\Big|_{S_2} = 0.$$
 (15)

Lemma 2. Let condition (5) be fulfilled. Then for all $u \in E$, $v \in E^*$ we have the inequalities

$$||Lu||_{W_{-}^{*}} \le c_{1} ||u||_{W_{+}}, \tag{16}$$

$$\|L^*v\|_{W_-} \le c_2 \|v\|_{W_1^*},\tag{17}$$

where the positive constants c_1 and c_2 do not depend on u and v, respectively, $\|\cdot\|_{W_+} = \|\cdot\|_{W_+^*} = \|\cdot\|_{1,+}$.

Proof. By the definition of a negative norm for $u \in E$ and by equalities (2), (4), (10), (15) we have

$$\begin{split} \|Lu\|_{W_{-}^{*}} &= \sup_{v \in W_{+}^{*}} \|v\|_{W_{+}^{*}}^{-1} (Lu, v)_{L_{2}(D)} = \sup_{v \in E^{*}} \|v\|_{W_{+}^{*}}^{-1} (Lu, v)_{L_{2}(D)} = \\ &= \sup_{v \in E^{*}} \|v\|_{W_{+}^{*}}^{-1} \int_{D} [u_{tt}v - u_{x_{1}x_{1}}v - (x_{2}^{m}u_{x_{2}})_{x_{2}}v + a_{1}u_{x_{1}}v + a_{2}u_{x_{2}}v + \\ &+ a_{3}u_{t}v + a_{4}uv] dD = \sup_{v \in E^{*}} \|v\|_{W_{+}^{*}}^{-1} \int_{\partial D} [u_{t}v\nu_{0} - u_{x_{1}}v\nu_{1} - x_{2}^{m}u_{x_{2}}v\nu_{2}] ds + \\ &+ \sup_{v \in E^{*}} \|v\|_{W_{+}^{*}}^{-1} \int_{D} [-u_{t}v_{t} + u_{x_{1}}v_{x_{1}} + x_{2}^{m}u_{x_{2}}v_{x_{2}} + a_{1}u_{x_{1}}v + a_{2}u_{x_{2}}v + \\ &+ a_{3}u_{t}v + a_{4}uv] dD = \sup_{v \in E^{*}} \|v\|_{W_{+}^{*}}^{-1} \int_{S_{1} \cup S_{2}} \frac{\partial u}{\partial N}v \, ds + \\ &+ \sup_{v \in E^{*}} \|v\|_{W_{+}^{*}}^{-1} \int_{D} [-u_{t}v_{t} + u_{x_{1}}v_{x_{1}} + x_{2}^{m}u_{x_{2}}v_{x_{2}} + a_{1}u_{x_{1}}v + a_{2}u_{x_{2}}v + \\ &+ a_{3}u_{t}v + a_{4}uv] dD = \sup_{v \in E^{*}} \|v\|_{W_{+}^{*}}^{-1} \int_{D} [-u_{t}v_{t} + u_{x_{1}}v_{x_{1}} + x_{2}^{m}u_{x_{2}}v_{x_{2}} + a_{1}u_{x_{1}}v + a_{2}u_{x_{2}}v_{x_{2}} + \\ &+ a_{3}u_{t}v + a_{4}uv] dD = \sup_{v \in E^{*}} \|v\|_{W_{+}^{*}}^{-1} \int_{D} [-u_{t}v_{t} + u_{x_{1}}v_{x_{1}} + x_{2}^{m}u_{x_{2}}v_{x_{2}} + \\ &+ a_{1}u_{x_{1}}v + a_{2}u_{x_{2}}v + a_{3}u_{t}v + a_{4}uv] dD. \end{split}$$

In view of condition (5) and the Schwartz inequality we obtain

$$\begin{split} \left| \int_{D} \left[-u_{t}v_{t} + u_{x_{1}}v_{x_{1}} + x_{2}^{m}u_{x_{2}}v_{x_{2}} \right] dD \right| &\leq 3 \left[\int_{D} \left(u_{t}^{2} + u_{x_{1}}^{2} + u_{x_{1}}^{2} + x_{2}^{m}u_{x_{2}}^{2} \right) dD \right]^{\frac{1}{2}} \left[\int_{D} \left(v_{t}^{2} + v_{x_{1}}^{2} + x_{2}^{m}v_{x_{2}}^{2} \right) dD \right]^{\frac{1}{2}} &\leq 3 \|u\|_{W_{+}} \|v\|_{W_{+}^{*}}, \end{split}$$
(19)
$$\left| \int_{D} \left[a_{1}u_{x_{1}}v + a_{2}u_{x_{2}}v + a_{3}u_{t}v + a_{4}uv \right] dD \right| \leq \\ &\leq \sup_{D} |a_{1}| \|u_{x_{2}}\|_{L_{2}(D)} \|v\|_{L_{2}(D)} + M \left(\int_{D} x_{2}^{m}u_{x_{2}}^{2} dD \right)^{\frac{1}{2}} \|v\|_{L_{2}(D)} + \\ &+ \sup_{D} |a_{3}| \|u_{t}\|_{L_{2}(D)} \|v\|_{L_{2}(D)} + \sup_{D} |a_{4}| \|u\|_{L_{2}(D)} \|v\|_{L_{2}(D)} \leq \\ &\leq \left(M + \sum_{i=1, i \neq 2}^{4} \sup_{D} |a_{i}| \right) \|u\|_{W_{+}} \|v\|_{W_{+}^{*}} = \widetilde{c} \|u\|_{W_{+}} \|v\|_{W_{+}^{*}}. \end{aligned}$$
(20)

From (18)–(20) it follows that

$$||Lu||_{W_{-}^{*}} \leq (3+\widetilde{c}) \sup_{v \in E^{*}} ||v||_{W_{+}^{*}}^{-1} ||u||_{W_{+}} ||v||_{W_{+}^{*}} = c_{1} ||u||_{W_{+}},$$

which proves inequality (16). Since the proof of inequality (17) is quite similar to that of inequality (16), Lemma 2 is thereby completely proved. \blacksquare

Remark 3. By virtue of inequality (16) ((17)) the operator $L: W_+ \to W_-^*$ ($L: W_+^* \to W_-$) with the dense definition domain of $E(E^*)$ admits a closure which is a continuous operator from the space $W_+(W_+^*)$ into the space $W_-^*(W_-)$. If we denote this closure as previously by $L(L^*)$, it will be defined throughout the Hilbert space $W_+(W_+^*)$.

Lemma 3. Problems (1), (2) and (3), (4) are mutually conjugate, i.e., the equality

$$(Lu, v) = (u, L^*v).$$
 (21)

holds for any $u \in W_+$ and $v \in W_+^*$.

Proof. By Remark 3 it is enough to prove equality (21) when $u \in E$ and $v \in E^*$. In that case it is obvious that $(Lu, v) = (Lu, v)_{L_2(D)}$. therefore we have

$$(Lu, v) = (Lu, v)_{L_{2}(D)} = \int_{\partial D} [u_{t}v\nu_{0} - u_{x_{1}}v\nu_{1} - x_{2}^{m}u_{x_{2}}v\nu_{2}]ds + + \int_{\partial D} [a_{1}\nu_{1} + a_{2}\nu_{2} + a_{3}\nu_{0}]uv \, ds + \int_{D} [-u_{t}v_{t} + u_{x_{1}}v_{x_{1}} + + x_{2}^{m}u_{x_{2}}v_{x_{2}} - u(a_{1}v)_{x_{1}} - u(a_{2}v)_{x_{2}} - u(a_{3}v)_{t} + a_{4}uv] dD = = \int_{\partial D} [u_{t}v\nu_{0} - u_{x_{1}}v\nu_{1} - x_{2}^{m}u_{x_{2}}v\nu_{2}]ds + \int_{\partial D} [a_{1}\nu_{1} + a_{2}\nu_{2} + + a_{3}\nu_{0}]uv \, ds - \int_{\partial D} [uv_{t}\nu_{0} - uv_{x_{1}}\nu_{1} - x_{2}^{m}uv_{x_{2}}\nu_{2}]ds + + \int_{D} [uv_{tt} - uv_{x_{1}x_{1}} - u(x_{2}^{m}v_{x_{2}})_{x_{2}} - u(a_{1}v)_{x_{1}} - - u(a_{2}v)_{x_{2}} - u(a_{3}v)_{t} + a_{4}uv] \, dD = \int_{\partial D} \left[\left(v \frac{\partial u}{\partial N} - u \frac{\partial v}{\partial N} \right) + + (a_{1}\nu_{1} + a_{2}\nu_{2} + a_{3}\nu_{0})uv \right] ds + (u, L^{*}v)_{L_{2}(D)}.$$

$$(22)$$

Since condition (5) implies $a_2|_{S_0} = 0$, by virtue of (2), (4), (10) and (15) we readily obtain equality (21) from (22), which proves Lemma 3.

Consider the conditions

$$\Omega\Big|_{S_1} \le 0, \quad (\lambda\Omega + \Omega_t)\Big|_D \le 0, \tag{23}$$

where the second inequality is fulfilled for sufficiently large λ , $\Omega = a_{1x_1} + a_{2x_2} + a_{3t} - a_4$.

Lemma 4. Let conditions (5) and (23) be fulfilled. Then for any $u \in W_+$ we have the inequality

$$c\|u\|_{L_2(D)} \le \|Lu\|_{W_{-}^*} \tag{24}$$

where the positive constant c does not depend on u.

Proof. By Remarks 1 and 3 it is enough to show that inequality (24) is fulfilled when $u \in E_0$. If $u \in E_0$ and thus vanishes in some neighborhood of the surface S_0 , then one can easily verify that the function

$$v(x_1, x_2, t) = \int_t^{\varphi_2(x_1, x_2)} e^{-\lambda \tau} u(x_1, x_2, \tau) d\tau, \quad \lambda = const > 0,$$

where $t = \varphi_2(x_1, x_2)$ is an equation of the characteristic surface S_2 , belongs to the space E_0^* and the equalities

$$v_t(x_1, x_2, t) = -e^{-\lambda t}u(x_1, x_2, t), \quad u(x_1, x_2, t) = -e^{\lambda t}v_t(x_1, x_2, t).$$
(25)

are fulfilled.

In view of (10), (15) and (25) we have

$$(Lu, v)_{L_{2}(D)} = \int_{\partial D} \left[v \frac{\partial u}{\partial N} + (a_{1}\nu_{1} + a_{2}\nu_{2} + a_{3}\nu_{0})uv \right] ds + + \int_{D} \left[-u_{t}v_{t} + u_{x_{1}}v_{x_{1}} + x_{2}^{m}u_{x_{2}}v_{x_{2}} - ua_{1x_{1}}v - ua_{1}v_{x_{1}} - ua_{2x_{2}}v - - ua_{2}v_{x_{2}} - ua_{3t}v - ua_{3}v_{t} + a_{4}uv \right] dD = \int_{D} e^{-\lambda t}u_{t}u \, dD + + \int_{D} e^{\lambda t} \left[-v_{x_{1}t}v_{x_{1}} - x_{2}^{m}v_{x_{2}t}v_{x_{2}} + a_{1x_{1}}v_{t}v + a_{1}v_{t}v_{x_{1}} + a_{2x_{2}}v_{t}v + + a_{2}v_{t}v_{x_{2}} + a_{3t}v_{t}v + a_{3}v_{t}^{2} - a_{4}v_{t}v \right] dD.$$
(26)

By (2) we obtain similarly to (8) and (9)

$$\int_{D} e^{-\lambda t} u_{t} u \, dD = \frac{1}{2} \int_{\partial D} e^{-\lambda t} u^{2} \nu_{0} \, ds + \frac{1}{2} \int_{D} e^{-\lambda t} \lambda u^{2} \, dD =$$

$$= \frac{1}{2} \int_{S_{2}} e^{-\lambda t} u^{2} \nu_{0} \, ds + \frac{1}{2} \int_{D} e^{\lambda t} \lambda v_{t}^{2} \, dD =$$

$$= \frac{1}{2} \int_{S_{2}} e^{\lambda t} v_{t}^{2} \nu_{0} \, ds + \frac{1}{2} \int_{D} e^{\lambda t} \lambda v_{t}^{2} \, dD, \qquad (27)$$

$$\int_{D} e^{\lambda t} [-v_{x_{1}t} v_{x_{1}} - x_{2}^{m} v_{x_{2}t} v_{x_{2}}] dD = -\frac{1}{2} \int_{\partial D} e^{\lambda t} [v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] \nu_{0} \, ds +$$

$$+ \frac{1}{2} \int_{D} e^{\lambda t} \lambda [v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] dD. \qquad (28)$$

Since $v|_{S_2} = 0$, for some α we have $v_t = \alpha \nu_0$, $v_{x_1} = \alpha \nu_1$, $v_{x_2} = \alpha \nu_2$ on S_2 . Therefore, recalling that the surface S_2 is characteristic, we obtain

$$\left(v_t^2 - v_{x_1}^2 - x_2^m v_{x_2}^2\right)\Big|_{S_2} = \alpha^2 \left(\nu_0^2 - \nu_1^2 - x_2^m \nu_2^2\right)\Big|_{S_2} = 0.$$
(29)

By virtue of $\nu_0|_{S_0} = 0$, $\nu_0|_{S_1} \le 0$, and equalities (4), (29) we find that

$$\frac{1}{2} \int_{S_2} e^{\lambda t} v_t^2 \nu_0 \, ds - \frac{1}{2} \int_{\partial D} e^{\lambda t} [v_{x_1}^2 + x_2^m v_{x_2}^2] \nu_0 \, ds =
= \frac{1}{2} \int_{S_2} e^{\lambda t} v_t^2 \nu_0 \, ds - \frac{1}{2} \int_{S_1} e^{\lambda t} [v_{x_1}^2 + x_2^m v_{x_2}^2] \nu_0 \, ds -
- \frac{1}{2} \int_{S_2} e^{\lambda t} [v_{x_1}^2 + x_2^m v_{x_2}^2] \nu_0 \, ds \ge \frac{1}{2} \int_{S_2} e^{\lambda t} v_t^2 \nu_0 \, ds - \frac{1}{2} \int_{S_2} e^{\lambda t} [v_{x_1}^2 + x_2^m v_{x_2}^2] \nu_0 \, ds = \frac{1}{2} \int_{S_2} e^{\lambda t} [v_t^2 - v_{x_1}^2 - x_2^m v_{x_2}^2] \nu_0 \, ds = 0.$$
(30)

Taking into account (27), (28) and (30), we obtain from (26)

$$(Lu, v)_{L_{2}(D)} = \frac{1}{2} \int_{S_{2}} e^{\lambda t} v_{t}^{2} \nu_{0} \, ds + \frac{1}{2} \int_{D} e^{\lambda t} \lambda v_{t}^{2} \, dD - \\ -\frac{1}{2} \int_{\partial D} e^{\lambda t} [v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] \nu_{0} \, ds + \frac{1}{2} \int_{D} e^{\lambda t} \lambda [v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] dD + \\ + \int_{D} e^{\lambda t} [a_{1}v_{t}v_{x_{1}} + a_{2}v_{t}v_{x_{2}} + a_{3}v_{t}^{2} + (a_{1x_{1}} + a_{2x_{2}} + a_{3t} - a_{4})v_{t}v] dD \geq \\ \geq \frac{\lambda}{2} \int_{D} e^{\lambda t} [v_{t}^{2} + v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] dD + \int_{D} e^{\lambda t} [a_{1}v_{t}v_{x_{1}} + a_{2}v_{t}v_{x_{2}} + a_{3}v_{t}^{2} + (a_{1x_{1}} + a_{2x_{2}} + a_{3t} - a_{4})v_{t}v] dD \geq$$

$$(31)$$

Using $\nu_0\big|_{S_1} \leq 0$ and conditions (4), (10), (23) and performing integration by parts we derive

$$\int_{D} e^{\lambda t} (a_{1x_{1}} + a_{2x_{2}} + a_{3t} - a_{4}) v_{t} v \, dD = \frac{1}{2} \int_{\partial D} e^{\lambda t} (a_{1x_{1}} + a_{2x_{2}} + a_{3t} - a_{4}) v^{2} \nu_{0} ds - \frac{1}{2} \int_{D} e^{\lambda t} \left[\lambda (a_{1x_{1}} + a_{2x_{2}} + a_{3t} - a_{4}) + (a_{1x_{1}} + a_{2x_{2}} + a_{3t} - a_{4})_{t} \right] v^{2} dD \ge 0,$$

$$(32)$$

where λ is a sufficiently large positive number.

With (32) taken into account (31) implies

$$\begin{split} (Lu,v)_{L_2(D)} &\geq \frac{\lambda}{2} \int_D e^{\lambda t} [v_t^2 + v_{x_1}^2 + x_2^m v_{x_2}^2] dD + \\ &+ \int_D e^{\lambda t} [a_1 v_t v_{x_1} + a_2 v_t v_{x_2} + a_3 v_t^2] dD \geq \frac{\lambda}{2} \int_D e^{\lambda t} [v_t^2 + v_{x_1}^2 + v_{x_2}^2] dD \end{split}$$

$$+x_{2}^{m}v_{x_{2}}^{2}]dD - \Big|\int_{D} e^{\lambda t} [a_{1}v_{t}v_{x_{1}} + a_{2}v_{t}v_{x_{2}} + a_{3}v_{t}^{2}]dD\Big|.$$
(33)

Assuming

$$\mu = \max \left(\sup_{D} |a_1|, \sup_{D} |a_3|
ight)$$

by condition (5) we find that

$$\left| \int_{D} e^{\lambda t} [a_{1}v_{t}v_{x_{1}} + a_{2}v_{t}v_{x_{2}} + a_{3}v_{t}^{2}]dD \right| \leq \\ \leq \int_{D} e^{\lambda t} \left[\frac{\mu}{2} (v_{x_{1}}^{2} + v_{t}^{2}) + M \frac{1}{2} (x_{2}^{m}v_{x_{2}}^{2} + v_{t}^{2}) + \mu v_{t}^{2} \right] dD \leq \\ \leq \left(\frac{1}{2}M + \frac{3}{2}\mu \right) \int_{D} e^{\lambda t} [v_{t}^{2} + v_{x_{1}}^{2} + x_{2}^{m}v_{x_{2}}^{2}] dD.$$
(34)

By virtue of (34) and (25) inequality (33) implies

$$(Lu, v)_{L_{2}(D)} \geq \left[\frac{\lambda}{2} - \left(\frac{1}{2}M + \frac{3}{2}\mu\right)\right] \int_{D} e^{\lambda t} [v_{t}^{2} + v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] dD \geq \geq \sigma \left[\int_{D} e^{\lambda t} v_{t}^{2} dD\right]^{\frac{1}{2}} \left[\int_{D} [v_{t}^{2} + v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] dD\right]^{\frac{1}{2}} = = \sigma \left[\int_{D} e^{-\lambda t} u^{2} dD\right]^{\frac{1}{2}} \left[\int_{D} [v_{t}^{2} + v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] dD\right]^{\frac{1}{2}} \geq \geq \sigma \inf_{D} e^{-\lambda t} ||u||_{L_{2}(D)} \left[\int_{D} [v_{t}^{2} + v_{x_{1}}^{2} + x_{2}^{m} v_{x_{2}}^{2}] dD\right]^{\frac{1}{2}},$$
(35)

where $\sigma = \left(\frac{\lambda}{2} - \left(\frac{1}{2}M + \frac{3}{2}\mu\right)\right) > 0$ for sufficiently large λ , and $\inf_{D} e^{-\lambda t} = const > 0$ by the structure of the domain D. Since $v|_{S_2} = 0$, similarly to (12) one can easily show that the inequality

$$\int_{D} v^2 dD \le c_0 \int_{D} v_t^2 dD$$

is valid for some $c_0 = const > 0$ not depending on v. Thus we conclude that, in the space $W_+(W_+^*)$, the norm

$$||u||_{W_{+}(W_{+}^{*})}^{2} = \int_{D} (u_{t}^{2} + u_{x_{1}}^{2} + x_{2}^{m}u_{x_{2}}^{2} + u^{2})dD$$

is equivalent to the norm

$$||u||^{2} = \int_{D} (u_{t}^{2} + u_{x_{1}}^{2} + x_{2}^{m} u_{x_{2}}^{2}) dD.$$
(36)

Therefore, retaining the previous notation $||u||_{W_+(W_+^*)}$ for norm (36), we obtain from (35)

$$(Lu, v)_{L_2(D)} \ge \sigma \inf_D e^{-\lambda t} ||u||_{L_2(D)} ||v||_{W_+^*}.$$
(37)

If now we apply the generalized Schwartz inequality

$$(Lu, v) \le \|Lu\|_{W^*_{-}} \|v\|_{W^*_{+}}$$

to the left-hand side of (37), then after reducing by $||v||_{W_+^*}$, we obtain inequality (24) where $c = \sigma \inf_D e^{-\lambda t} = const > 0$. Lemma 4 is thereby completely proved.

Consider the conditions

$$a_4|_{S_2} \ge 0, \quad (\lambda a_4 - a_{4t})|_D \ge 0,$$
 (38)

where the second inequality holds for sufficiently large λ .

Lemma 5. Let conditions (5) and (38) be fulfilled. Then for any $v \in W_+^*$ the inequality

$$c\|v\|_{L_2(D)} \le \|L^*v\|_{W_-} \tag{39}$$

holds for a constant c = const > 0 which does not depend on $v \in W_+^*$.

Proof. Like in the case of Lemma 4, by Remarks 1 and 3 it is enough to show that inequality (39) is valid for $v \in E_0^*$. Assume that $v \in E_0^*$ and introduce into the consideration the function

$$u(x_1, x_2, t) = \int\limits_{\varphi_1(x_1, x_2)}^t e^{\lambda \tau} v(x_1, x_2, \tau) d\tau, \quad \lambda = const > 0,$$

where $t = \varphi_1(x_1, x_2)$ is an equation of the characteristic surface S_1 . It is easy to verify that the function $u(x_1, x_2, t)$ belongs to the class E_0 and the following equalities are fulfilled:

$$u_t(x_1, x_2, t) = e^{\lambda t} v(x_1, x_2, t), \quad v(x_1, x_2, t) = e^{-\lambda t} u_t(x_1, x_2, t).$$
(40)

From (10), (15) and (40) we have

$$(L^*v, u)_{L_2(D)} = \int_{\partial D} \left[u \frac{\partial v}{\partial N} - (a_1 \nu_1 + a_2 \nu_2 + a_3 \nu_0) v u \right] ds + + \int_D \left[-v_t u_t + v_{x_1} u_{x_1} + x_2^m v_{x_2} u_{x_2} + a_1 v u_{x_1} + a_2 v u_{x_2} + a_3 v u_t + + a_4 u v \right] dD = - \int_D e^{\lambda t} v_t v \, dD + \int_D e^{-\lambda t} \left[u_{x_1 t} u_{x_1} + x_2^m u_{x_2 t} u_{x_2} \right] dD + + \int_D e^{-\lambda t} \left[a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u \right] u_t \, dD.$$
(41)

Similarly to (27)–(30), we can prove the equalities

$$-\int_{D} e^{\lambda t} v_{t} v \, dD = -\frac{1}{2} \int_{\partial D} e^{\lambda t} v^{2} \nu_{0} \, ds + \frac{1}{2} \int_{D} e^{\lambda t} \lambda v^{2} \, dD =$$

$$= -\frac{1}{2} \int_{S_{1}} e^{\lambda t} v^{2} \nu_{0} \, ds + \frac{1}{2} \int_{D} e^{-\lambda t} \lambda u_{t}^{2} \, dD =$$

$$= -\frac{1}{2} \int_{S_{1}} e^{-\lambda t} u_{t}^{2} \nu_{0} \, ds + \frac{1}{2} \int_{D} e^{-\lambda t} \lambda u_{t}^{2} \, dD, \qquad (42)$$

$$\int_{D} e^{-\lambda t} [u_{x_1t} u_{x_1} + x_2^m u_{x_2t} u_{x_2}] dD = \frac{1}{2} \int_{\partial D} e^{-\lambda t} [u_{x_1}^2 + x_2^m u_{x_2}^2] \nu_0 \, ds + \frac{1}{2} \int_{\partial D} e^{-\lambda t} \lambda [u_{x_1}^2 + x_2^m u_{x_2}^2] dD,$$
(43)

$$(u_t^2 - u_{x_1}^2 - x_2^m u_{x_2}^2)\big|_{S_1} = 0, (44)$$

as well as the inequality

$$-\frac{1}{2} \int_{S_1} e^{-\lambda t} u_t^2 \nu_0 \, ds + \frac{1}{2} \int_{\partial D} e^{-\lambda t} [u_{x_1}^2 + x_2^m u_{x_2}^2] \nu_0 \, ds =$$

$$= -\frac{1}{2} \int_{S_1} e^{-\lambda t} u_t^2 \nu_0 \, ds + \frac{1}{2} \int_{S_1} e^{-\lambda t} [u_{x_1}^2 + x_2^m u_{x_2}^2] \nu_0 \, ds +$$

$$+ \frac{1}{2} \int_{S_2} e^{-\lambda t} [u_{x_1}^2 + x_2^m u_{x_2}^2] \nu_0 \, ds \ge$$

$$\ge -\frac{1}{2} \int_{S_1} e^{-\lambda t} [u_t^2 - u_{x_1}^2 - x_2^m u_{x_2}^2] \nu_0 \, ds = 0.$$
(45)

In deriving (45), we used the fact that $\nu_0 |_{S_2} \ge 0$. By virtue of (42)–(45) equality (41) implies

$$(L^*v, u)_{L_2(D)} \ge \frac{1}{2} \int_D e^{-\lambda t} \lambda [u_t^2 + u_{x_1}^2 + x_2^m u_{x_2}^2] dD + \int_D e^{-\lambda t} [a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u] u_t \, dD.$$
(46)

Using the fact that $\nu_0|_{S_2} \ge 0$ and conditions (2), (10), (38) and performing integration by parts, we obtain

$$\int_{D} e^{-\lambda t} a_4 u u_t dD = \frac{1}{2} \int_{\partial D} e^{-\lambda t} a_4 u^2 \nu_0 ds + \frac{1}{2} \int_{D} e^{-\lambda t} (\lambda a_4 - a_{4t}) u^2 dD \ge 0.$$

$$(47)$$

By (47) we find from (46) that

$$(L^*v, u)_{L_2(D)} \ge \frac{1}{2} \int_D e^{-\lambda t} \lambda [u_t^2 + u_{x_1}^2 + x_2^m u_{x_2}^2] dD + + \int_D e^{-\lambda t} [a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t] u_t \, dD \ge \frac{\lambda}{2} \int_D e^{-\lambda t} [u_t^2 + u_{x_1}^2 + u_{x_2}^2] dD - \Big| \int_D e^{-\lambda t} [a_1 u_{x_1} + a_2 u_{x_2} + a_3 u_t + a_4 u] u_t \, dD \Big|.$$

Hence, like in deriving inequality (35), from (33) we obtain

$$(L^*v, u)_{L_2(D)} \ge \left[\frac{\lambda}{2} - \left(\frac{1}{2}M + \frac{3}{2}\mu\right)\right] \inf_D e^{-\lambda t} \|v\|_{L_2(D)} \|u\|_{W_+}.$$
 (48)

For sufficiently large λ the latter inequality immediately implies (39). This proves Lemma 5.

Definition 1. For $F \in L_2(D)$ the function u will be called a strongly generalized solution of problem (1), (2) from the class W_+ provided that $u \in W_+$ and there exists a sequence of functions $u_n \in E_0$ such that $u_n \to u$ in the space W_+ and $Lu_n \to F$ in the space W_-^* , i.e.,

$$\lim_{n \to \infty} \|u_n - u\|_{W_+} = 0, \quad \lim_{n \to \infty} \|Lu_n - F\|_{W_-^*} = 0.$$

Definition 2. For $F \in W_{-}^{*}$ the function u will be called a strongly generalized solution of problem (1), (2) from the class L_2 provided that $u \in L_2(D)$ and there exists a sequence of functions $u_n \in E_0$ such that $u_n \to u$ in the space $L_2(D)$ and $Lu_n \to F$, $n \to \infty$, in the space W_{-}^{*} , i.e.,

$$\lim_{n \to \infty} \|u_n - u\|_{L_2(D)} = 0. \quad \lim_{n \to \infty} \|Lu_n - F\|_{W_{-}^*} = 0.$$

By the results of [13] Lemmas 2–5 give rise to the following theorems.

Theorem 1. Let conditions (5), (23) and (38) be fulfilled. Then for any $F \in W_{-}^*$ there exists a unique strongly generalized solution u of problem (1), (2) from the class L_2 , for which the estimate

$$\|u\|_{L_2(D)} \le c\|F\|_{W^*_{-}} \tag{49}$$

where the positive constant c does not depend on F, is valid.

Theorem 2. Let conditions (5), (23) and (38) be fulfilled. Then for any $F \in L_2(D)$ there exists a unique strongly generalized solution u of problem (1), (2) from the class W_+ , for which estimate (49) holds.

Similar results hold for problem (3), (4) as well.

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