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THE SCREEN TYPE BOUNDARY VALUE PROBLEMS FOR ANISOTROPIC PSEUDO-MAXWELL'S EQUATIONS

INTRODUCTION

Let Ω denote either a bounded $\Omega^+ \subset \mathbb{R}^3$ or an unbounded $\Omega^- := \mathbb{R}^3 \setminus \overline{\Omega^+}$ domain with smooth boundary $\mathcal{S} := \partial\Omega^+$ and let ν be the outer unit normal vector field to \mathcal{S} .

By \mathcal{C} we denote an orientable smooth open surface in \mathbb{R}^3 (a screen) with the smooth boundary $\partial\mathcal{C}$. The screen has two faces \mathcal{C}^- and \mathcal{C}^+ distinguished by the orientation of the normal vector field: ν is pointing from \mathcal{C}^+ to \mathcal{C}^- . Moreover, we assume that \mathcal{C} is a part of some smooth and simple (non self intersecting) hypersurface \mathcal{S} that divides the space \mathbb{R}^3 into two disjoint domains Ω^+ and $\Omega^- := \mathbb{R}^3 \setminus \overline{\Omega^+}$ such that Ω^+ is bounded and $\mathcal{S} = \partial\Omega^\pm$.

Our purpose is to investigate the screen-type boundary value problem for pseudo-Maxwell's equations

$$\operatorname{curl} \mu^{-1} \operatorname{curl} \mathbf{U} - s \varepsilon \operatorname{grad} \operatorname{div} (\varepsilon \mathbf{U}) - \omega^2 \varepsilon \mathbf{U} = 0 \quad \text{in } \mathbb{R}_\mathcal{C}^3, \quad (1)$$

where $\mathbb{R}_\mathcal{C}^3 := \mathbb{R}^3 \setminus \mathcal{C}$ is the domain with a screen, using the potential method.

The present investigation covers the anisotropic case when the matrices in (1)

$$\varepsilon = [\varepsilon_{jk}]_{3 \times 3}, \quad \mu = [\mu_{jk}]_{3 \times 3}, \quad (2)$$

are real valued, constant, symmetric and positive definite, i.e.,

$$\langle \varepsilon \xi, \xi \rangle \geq c |\xi|^2, \quad \langle \mu \xi, \xi \rangle \geq d |\xi|^2, \quad \forall \xi \in \mathbb{R}^3,$$

for some positive constants $c > 0$, $d > 0$, where

$$\langle \eta, \xi \rangle := \sum_{j=1}^3 \eta_j \bar{\xi}_j, \quad \eta, \xi \in \mathbb{C}^3.$$

s is a positive real number and the frequency parameter ω is assumed to be non-zero and complex valued, i.e., $\operatorname{Im} \omega \neq 0$.

The study of boundary value problems in electromagnetism naturally leads us to the pseudo-Maxwell's equations inherited with tangent boundary

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conditions, which are in some sense non-standard for the elliptic equations (1), cf. works of Buffa, Costabel, Christiansen, Dauge, Hazard, Lenoir, Mitrea, Niciase and others. The case with the Dirichlet type boundary condition $\boldsymbol{\nu} \times \mathbf{U}$ is mostly investigated by variational methods, here $\boldsymbol{\nu}$ is the unit normal to the boundary $\partial\Omega$. Our goal is investigate well posedness of the Neumann type boundary value problems for (1) as well as its unique solvability in unbounded domains with screen $\mathbb{R}_{\mathcal{C}}^3$.

For rigorous formulation of conditions for the unique solvability of the formulated boundary value problems we use the Bessel potential $\mathbb{H}^r(\Omega)$, $\mathbb{H}^r(\mathcal{S})$ spaces. We quote [3] for definitions and properties of these spaces.

The space $\widetilde{\mathbb{H}}^r(\mathcal{C})$ comprises those functions $\varphi \in \mathbb{H}^r(\mathcal{S})$ which are supported in $\overline{\mathcal{C}}$ (functions with the ‘‘vanishing traces on the boundary’’). For the detailed definitions and properties of these spaces we refer, e.g., to [3].

It is well known that the space $\mathbb{H}^{r-1/2}(\mathcal{S})$ is a trace space for $\mathbb{H}^r(\Omega)$, provided that $r > 1/2$ and the corresponding trace operator is denoted by $\gamma_{\mathcal{S}}$. For the detailed definitions and properties of these spaces we refer, e.g., to [3].

We introduce the following spaces:

$$\begin{aligned}\mathbb{H}_{\varepsilon\boldsymbol{\nu},0}^r(\mathcal{S}) &:= \left\{ \mathbf{U} \in \mathbb{H}^r(\mathcal{S}) : \langle \varepsilon\boldsymbol{\nu}, \mathbf{U} \rangle = 0 \right\}, \\ \mathbb{H}_{\varepsilon\boldsymbol{\nu},0}^1(\Omega^+) &= \left\{ \mathbf{U} \in \mathbb{H}^1(\Omega^+) : \langle \varepsilon\boldsymbol{\nu}, \gamma_{\mathcal{S}}\mathbf{U} \rangle = 0 \text{ on } \mathcal{S} \right\}, \\ \mathbb{H}_{\varepsilon\boldsymbol{\nu},0}^1(\mathbb{R}_{\mathcal{C}}^3) &= \left\{ \mathbf{U} \in \mathbb{H}^1(\mathbb{R}_{\mathcal{C}}^3) : \langle \varepsilon\boldsymbol{\nu}, \gamma_{\mathcal{C}\pm}\mathbf{U} \rangle = 0 \text{ on } \mathcal{C} \right\}.\end{aligned}$$

Theorem 0.1. *The operator in (1)*

$$\mathbf{A}(D)\mathbf{U} := \operatorname{curl} \mu^{-1} \operatorname{curl} \mathbf{U} - s \varepsilon \operatorname{grad} \operatorname{div}(\varepsilon \mathbf{U}) - \omega^2 \varepsilon \mathbf{U}$$

is elliptic, has the positive definite principal symbol

$$\mathcal{A}_{\operatorname{pr}}(\boldsymbol{\xi}) := \sigma_{\operatorname{curl}}(\boldsymbol{\xi}) \mu^{-1} \sigma_{\operatorname{curl}}(\boldsymbol{\xi}) + s \varepsilon [\xi_j \xi_k]_{3 \times 3} \varepsilon, \quad \boldsymbol{\xi} = (\xi_1, \xi_2, \xi_3)^\top \in \mathbb{R}^3, \quad (3)$$

where

$$\sigma_{\operatorname{curl}}(\boldsymbol{\xi}) := \begin{bmatrix} 0 & i\xi_3 & -i\xi_2 \\ -i\xi_3 & 0 & i\xi_1 \\ i\xi_2 & -i\xi_1 & 0 \end{bmatrix},$$

is non-vanishing $\det \mathcal{A}_{\operatorname{pr}}(\boldsymbol{\xi}) \neq 0$ for $\boldsymbol{\xi} \neq 0$ and positive definite

$$\langle \mathcal{A}_{\operatorname{pr}}(\boldsymbol{\xi})\boldsymbol{\eta}, \boldsymbol{\eta} \rangle \geq c |\boldsymbol{\xi}|^2 |\boldsymbol{\eta}|^2 \quad c = \operatorname{const} > 0, \quad \forall \boldsymbol{\xi} \in \mathbb{R}^3, \quad \forall \boldsymbol{\eta} \in \mathbb{C}^3. \quad (4)$$

Moreover, the operator $\mathbf{A}(D)$ is self-adjoint and the following Green’s formula holds

$$(\mathbf{A}(D)\mathbf{U}, \mathbf{V})_{\Omega^+} = (\mathfrak{N}(D, \boldsymbol{\nu})\mathbf{U}, \mathbf{V})_{\mathcal{S}} + \mathbf{a}_{\varepsilon, \mu}(\mathbf{U}, \mathbf{V})_{\Omega^+} - \omega^2 (\varepsilon \mathbf{U}, \mathbf{V})_{\Omega^+}, \quad (5)$$

for all $\mathbf{U}, \mathbf{V} \in \mathbb{H}^1(\Omega^+)$. Here $\mathfrak{N}(D, \boldsymbol{\nu})$ is the Neumann’s boundary operator

$$\mathfrak{N}(D, \boldsymbol{\nu})\mathbf{U} := \boldsymbol{\nu} \times \mu^{-1} \operatorname{curl} \mathbf{U} - s \operatorname{div}(\varepsilon \mathbf{U}) \varepsilon \boldsymbol{\nu}, \quad \mathbf{U} \in \mathbb{H}^1(\Omega^+) \quad (6)$$

and $\mathbf{a}_{\varepsilon,\mu}$ is the natural bilinear differential form associated with the Green formula

$$\mathbf{a}_{\varepsilon,\mu}(\mathbf{U}, \mathbf{V})_{\Omega} := (\mu^{-1} \operatorname{curl} \mathbf{U}, \operatorname{curl} \mathbf{V})_{\Omega} + s (\operatorname{div}(\varepsilon \mathbf{U}), \operatorname{div}(\varepsilon \mathbf{V}))_{\Omega}. \quad (7)$$

Based on this fact we obtain that the Neumann's trace $\mathfrak{N}(D, \boldsymbol{\nu})\mathbf{U} \in \mathbb{H}^{-\frac{1}{2}}(\mathcal{S})$.

Let us mention the well known fact, that the Neumann boundary value problem

$$\mathbf{A}(D)\mathbf{U} = 0 \quad \text{in } \Omega^+, \quad \mathfrak{N}(D, \boldsymbol{\nu})\mathbf{U} = g \quad \text{on } \mathcal{S}, \quad g \in \mathbb{H}^{-\frac{1}{2}}(\mathcal{S}),$$

is not an elliptic boundary value problem in the sense of the Shapiro-Lopatinski condition. To overcome the problem we consider the tangent boundary conditions and look for a solution in tangent spaces. First, for any $\mathbf{V} \in \mathbb{H}_{\varepsilon\nu,0}^1(\Omega^+)$ we have $\pi_{\varepsilon\nu}\mathbf{V} = \mathbf{V}$, where $\pi_{\varepsilon\nu}\mathbf{U} := \mathbf{U} - \langle \mathbf{U}, \varepsilon\nu \rangle \varepsilon\nu$ is a projection on the hyperplane, orthogonal to the vector field $\varepsilon\nu$. Therefore from (6) and (7) we obtain

$$(\mathfrak{N}(D, \boldsymbol{\nu})\mathbf{U}, \mathbf{V}) = (\mathfrak{N}(D, \boldsymbol{\nu})\mathbf{U}, \pi_{\varepsilon\nu}\mathbf{V}) = (\pi_{\varepsilon\nu}\mathfrak{N}(D, \boldsymbol{\nu})\mathbf{U}, \pi_{\varepsilon\nu}\mathbf{V}).$$

Thus $\pi_{\varepsilon\nu}\mathfrak{N}(D, \boldsymbol{\nu})\mathbf{U}$ is well-defined as a functional on $\mathbb{H}_{\varepsilon\nu,0}^{\frac{1}{2}}(\mathcal{S})$ and belongs to $\mathbb{H}_{\varepsilon\nu,0}^{-\frac{1}{2}}(\mathcal{S})$.

An important role in the investigation goes to the following lemma, which was proved by M. Costabel in [2] for a compact domain, We have extended the result for a non-compact domains, including domains with a screen.

Lemma 0.2. *The bilinear differential form $\mathbf{a}_{\varepsilon,\mu}(\mathbf{U}, \mathbf{U})_{\Omega^+}$ in (7) is coercive, i.e., there exist positive constants c_1 and c_2 such that*

$$\operatorname{Re} \mathbf{a}_{\varepsilon,\mu}(\mathbf{U}, \mathbf{U})_{\Omega^{\pm}} \geq c_1 \|\mathbf{U}\|_{\mathbb{H}^1(\Omega^{\pm})}^2 - c_2 \|\mathbf{U}\|_{\mathbb{L}_2(\Omega^{\pm})}^2 \quad (8)$$

on the space $\mathbb{H}_{\varepsilon\nu,0}^1(\Omega^+)$.

Moreover, the bilinear differential form $\mathbf{a}_{\varepsilon,\mu}(\mathbf{U}, \mathbf{U})_{\Omega^-}$ is coercive for all vector fields $\mathbf{U} \in \mathbb{H}_{\varepsilon\nu,0}^1(\Omega^-)$ provided they are solutions to pseudo-Maxwell's equation.

1. BASIC RESULTS

Our main goal is to investigate following screen type Neumann boundary value problem (BVP) for pseudo-Maxwell's equations:

Problem. Find $\mathbf{U} \in \mathbb{H}_{\varepsilon\nu,0}^1(\mathbb{R}_{\mathcal{C}}^3)$ such that

$$\begin{cases} \mathbf{A}(D)\mathbf{U} = \operatorname{curl} \mu^{-1} \operatorname{curl} \mathbf{U} - s \varepsilon \operatorname{grad} \operatorname{div}(\varepsilon \mathbf{U}) - \omega^2 \varepsilon \mathbf{U} = 0 & \text{in } \mathbb{R}_{\mathcal{C}}^3, \\ \gamma_{\mathcal{C}}^{\pm} (\pi_{\varepsilon\nu} \mathfrak{N}(D, \boldsymbol{\nu}) \mathbf{U}) = \mathbf{g}^{\pm} & \text{on } \mathcal{C}, \end{cases} \quad (9)$$

where s is an arbitrary positive constant and the given data \mathbf{g}^{\pm} satisfy the conditions

$$\mathbf{g}^{\pm} \in \mathbb{H}_{\varepsilon\nu,0}^{-1/2}(\mathcal{C}), \quad \mathbf{g}^+ - \mathbf{g}^- \in r_{\mathcal{C}} \widetilde{\mathbb{H}}_{\varepsilon\nu,0}^{-1/2}(\mathcal{C}). \quad (10)$$

Let us consider, respectively, the *single layer* and *double layer* potential operators

$$\begin{aligned}\mathbf{V}\mathbf{U}(x) &:= \oint_{\mathcal{S}} \mathbf{F}_{\mathbf{A}}(x - \tau)\mathbf{U}(\tau) dS, \\ \mathbf{W}\mathbf{U}(x) &:= \oint_{\mathcal{S}} [(\mathfrak{N}(D, \nu(\tau))\mathbf{F}_{\mathbf{A}})(x - \tau)]^{\top} \mathbf{U}(\tau) dS, \quad x \in \Omega, \quad (11)\end{aligned}$$

related to pseudo-Maxwell's equations in (9), where $\mathbf{F}_{\mathbf{A}}$ is a fundamental solution to $\mathbf{A}(D)$.

Lemma 1.1. *The direct value \mathbf{V}_{-1} of the single layer potential in (11) is invertible in the following space settings*

$$\mathbf{V}_{-1} : \mathbb{H}^r(\mathcal{S}) \rightarrow \mathbb{H}^{r+1}(\mathcal{S}) \quad \forall r \in \mathbb{R}.$$

The principal symbol of the pseudodifferential operator \mathbf{V}_{-1} is positive definite

$$\langle V_{-1, \text{pr}}(x, \xi)\eta, \eta \rangle \geq c_0 |\eta|^2 |\xi|^{-1} \quad \forall \eta \in C^3, \quad x \in \mathcal{S}, \quad \xi \in \mathbb{R}^3,$$

for some positive constant c_0 .

The foregoing Lemma 1.1 enables to look for a solution of the BVP (9)–(10) in the form

$$\mathbf{U}(x) = \begin{cases} \mathbf{V}(\mathbf{V}_{-1})^{-1} \Phi^+(x) & x \in \Omega^+, \\ \mathbf{V}(\mathbf{V}_{-1})^{-1} \Phi^-(x) & x \in \Omega^- \quad \text{for some } \Phi^{\pm} \in \mathbb{H}_{\varepsilon\nu, 0}^{1/2}(\mathcal{S}), \end{cases}$$

where Ω^{\pm} are the domains bordered by a surface $\mathcal{S} = \partial\Omega^+ = \partial\Omega^-$, which contains \mathcal{C} as a subsurface $\mathcal{C} \subset \mathcal{S}$. Then \mathbf{U} satisfies the basic differential equation from BVP (9) in the domains Ω^{\pm} and, due to the mapping properties of \mathbf{V} we have $\mathbf{U} \in \mathbb{H}_{\varepsilon\nu, 0}^1(\mathbb{R}^3)$. Further we need to fulfill the boundary conditions (cf. (6))

$$r_{\mathcal{C}} \gamma_{\mathcal{S}^{\pm}} (\pi_{\varepsilon\nu} \mathfrak{N}(D, \nu)\mathbf{U}) = \mathbf{g}^{\pm} \quad \text{on } \mathcal{C}.$$

Due to the Plemelji formulae we derive the following boundary pseudodifferential equations

$$r_{\mathcal{C}} \mathcal{P}_{\pm} \Phi^{\pm} = \mathbf{g}^{\pm} \quad \text{on } \mathcal{C},$$

where

$$\mathcal{P}_{\pm} := \pi_{\varepsilon\nu} \left(\frac{1}{2} I \mp (\mathbf{W}_{\mathbf{0}})^* \right) (\mathbf{V}_{-1})^{-1}$$

are the *modified Poincaré-Steklov* pseudodifferential operators of order 1. $\mathbf{W}_{\mathbf{0}}$ is the direct value of the double layer potential in (11), while $(\mathbf{W}_{\mathbf{0}})^*$ is the adjoint operator.

Lemma 1.2. *For an open subsurface $\mathcal{C} \subset \mathcal{S}$ the operators*

$$r_{\mathcal{C}} \mathcal{P}_{\pm} : \tilde{\mathbb{H}}_{\varepsilon\nu, 0}^{1/2}(\mathcal{C}) \rightarrow \mathbb{H}_{\varepsilon\nu, 0}^{-1/2}(\mathcal{C})$$

are coercive

$$\operatorname{Re}(r_C \mathcal{P}_\pm \Phi, \Phi)_C \geq c_0 \|\Phi\|_{\widetilde{\mathbb{H}}_{\varepsilon\nu,0}^{1/2}(C)}^2 - c_1 \|\Phi\|_{\mathbb{L}_{2,\varepsilon\nu,0}(C)}^2$$

for some positive constants c_0, c_1 and all $\Phi \in \widetilde{\mathbb{H}}_{\varepsilon\nu,0}^{1/2}(C)$. Moreover, the operators have the trivial kernels $\operatorname{Ker} r_C \mathcal{P}_\pm = \{0\}$ and are invertible.

If the frequency is purely imaginary $\omega = i\beta \neq 0$, $\beta \in \mathbb{R}$, the operators $r_C \mathcal{P}_\pm$ are positive definite

$$(r_C \mathcal{P}_\pm \Phi, \Phi)_C \geq M_\pm \|\Phi\|_{\widetilde{\mathbb{H}}_{\varepsilon\nu,0}^{1/2}(C)}$$

for some positive constants M_\pm .

Based on the foregoing lemmata in [1] we have proved the following result.

Theorem 1.3. Let $0 \leq r < \frac{1}{2}$ and the condition

$$\mathbf{g}^\pm \in \mathbb{H}_{\varepsilon\nu,0}^{r-1/2}(C), \quad \mathbf{g}^+ - \mathbf{g}^- \in r_C \widetilde{\mathbb{H}}_{\varepsilon\nu,0}^{r-1/2}(C).$$

hold. Then the elliptic BVP (9) has a unique solution $\mathbf{U} \in \mathbb{H}_{\varepsilon\nu,0}^{r+1}(\mathbb{R}_C^3)$.

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