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On the Complex Points of Planar Endomorphisms

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**ABSTRACT.** We present an explicit formula for the number of complex points on the graph of a polynomial endomorphism of the plane. We also show that one can compute the number of elliptic complex points and explain relation of our results to Bishop's problem.

**Key words:** complex point of a surface, elliptic complex point, Gaussian curvature.

1. We deal with certain aspects of the so-called Bishop's problem concerned with the existence of analytic discs attached to the graph of a complex valued function in the plane [1]. As was shown by Bishop, in many cases a positive solution to this problem follows from the existence of points where the tangent plane to graph is a complex line in  $\mathbb{C}^2$ . Such points are called complex points of a given function (and its graph) and they can be of the two essentially different types according to the local geometric properties of the graph near the point in question. Thus it is very desirable to obtain detailed information about the existence and amount of the complex points of both types and this is exactly the problem which we are going to attack. In this note we give an effective solution of the latter problem in the case when the real and imaginary parts of the given function are (real) polynomials of the real and imaginary parts of the argument. Obviously the same assumption may be expressed by saying that we are given a polynomial endomorphism of the plane which will be called a planar endomorphism (plend).

Following the general strategy of singularity theory [2] it is reasonable to consider first „generic” plends which satisfy certain jet transversality conditions. For our purposes it is appropriate to require that a plend is proper and the Gauss mapping of its graph is transversal to the subset of complex lines  $G_c$  in the real Grassmanian  $\text{Gr}[2,4]$  (cf. [3], [4]). We call them „perfect plends” (by analogy with „excellent maps” of H. Whitney [5]).

It is well known that such plends are indeed generic in the standard sense [1], i.e., they form an open dense subset in the space of all plends [2], [3]. In particular any plend can be approximated by arbitrarily close perfect ones (so-called perfect perturbations). From our transversality condition by dimension reasons it follows that a perfect plend can only have a finite number of complex points. A general „deformation paradigm” of singularity theory suggests then that important information on an arbitrary plend can be obtained by counting complex points of its sufficiently small perfect perturbations.

2. In line with that we concentrate on counting complex points of a perfect plend. Let  $F = (f, g): \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be a perfect endomorphism defined by real polynomials  $f(x, y)$ ,  $g(x, y)$ . Denote by  $G_F$  its graph in  $\mathbb{R}^2 \times \mathbb{R}^2$  which is identified with  $\mathbb{C}^2$  in the usual way. Recall that a point  $p \in \mathbb{R}^2$  is called a complex point of  $F$  (and  $G_F$ ) if the tangent plane  $T_p G_F$  is a complex line in  $\mathbb{C}^2$ .







appeal to the notion of Gaussian curvature of a two-surface [7]. We denote by  $K_p(p)$  the Gaussian curvature at point  $p$  of the graph of a perfect plend  $F$ .

**Lemma 3.** *A complex point  $p$  is an elliptic complex point if and only if the Gaussian curvature  $K_p(p)$  is positive.*

This follows from the aforementioned representation of the graph  $G_F$  as a hypersurface in three-dimensional Euclidean space, because in that representation it becomes obvious that  $K_p(p)$  is positive exactly in the case when the graph lies on one side of the tangent plane at  $p$ .

**Proposition 2.** *The set of elliptic complex points is a semi-algebraic subset of the plane.*

From preceding remarks it is clear that  $C_e(F) = \{F_* = 0, K_p > 0\}$  and the result follows if we show that the second condition can be expressed as a polynomial inequality. In order to show that, we refer to some well-known results about the Gaussian curvature of a parameterized two-dimensional surface [7]. First of all, from the general formula for the Gaussian curvature in terms of Riemann tensor [7], it follows that in our case the sign of  $K_p$  coincides with the sign of the component  $R_{1212}$  of the Riemann tensor  $R$  of  $G_F$ . The component  $R_{1212}$  can be computed by simple explicit formulae which show that, for a two-dimensional surface given by a polynomial parametrization, it is a polynomial function of parameters. In our case this means that  $R_{1212}$  is a polynomial in  $x, y$  so the condition of positivity of  $K_p$  is indeed a polynomial inequality, which shows that  $C_e(F)$  is indeed a semi-algebraic subset.

Now we can apply results of Chapter 9 of [7] and obtain the desired conclusion about the effective computability of  $e(F)$ .

**Theorem 2.** *The number of elliptic complex points of a perfect plend can be effectively computed using a finite number of algebraic and logical operations on its coefficients.*

Actually, this number can be expressed through signatures of explicitly constructible quadratic forms on the factor-algebra of polynomial algebra over the ideal generated by components of  $F_*$  (cf. [6]). In concrete cases necessary computations can be done using the program from [8].

4. In conclusion we show that some information about the complex points of small perfect deformations of an arbitrary proper plend may be obtained in a purely algebraic way from its coefficients. To this end we use a version of the Maslov index which was introduced in [3, 4]. In our setting it is convenient to define the Maslov index of a proper plend  $F$  in geometric way in the spirit of [3, 4]. For a proper plend, the number of complex points is always finite so its graph is a totally real surface „at infinity”, i.e., outside sufficiently big discs. Take a circle  $S$  of sufficiently big radius and consider its image  $G(S)$  in  $Gr(2,4)$  under the Gauss map  $G$  of the graph  $G_F$ . Obviously  $G(S)$  is an oriented one-dimensional submanifold which does not intersect the oriented two-dimensional submanifold of complex lines  $G_c$  and the sum of dimensions of these two oriented submanifolds is by one less than the dimension of the ambient manifold  $Gr(2,4)$  so one can define the linking number of these two submanifolds.

Actually, in order that complex points are counted properly it is necessary to consider both connected components  $G_+$  and  $G_-$  of  $G_c$  consisting of complex lines with their natural orientation, and with the opposite orientation respectively. Then the Maslov index of  $G_F$  is defined as the linking number  $L(G(S), G_+ \cup -G_-)$ , where  $-G_-$  denotes the component  $G_-$  taken



with the opposite orientation (cf. [3, 4]). It is easy to verify that it does not depend on a (sufficiently big) circle  $S$  and is invariant under homotopies of proper plends. If the complex points are generic then the Maslov index can be computed by properly counting complex points of various types, in particular formulae from [3] and [4] can be easily extended to this situation. Since Maslov index is homotopy invariant this means that it gives some information about complex points of small perfect perturbations. Thus our next result can be considered as a first step towards counting complex points of perfect perturbations.

**Theorem 3.** *The Maslov index of a sufficiently small perfect perturbations of a proper plend  $F$  can be computed as the local topological degree of an explicitly constructible planar endomorphism.*

**Corollary 2.** *The Maslov index is equal to the signature of the so-called Gorenstein quadratic form on the local algebra of an explicitly constructible polynomial endomorphism.*

Both these statements follow from the method of computing Maslov index in terms of the local topological degree developed in [3, 4] and from the well-known algebraic formula for the local topological degree (see, e.g., [6], Chapter 5).

Using estimates for the topological degree of homogeneous polynomial endomorphisms it is now easy to give an exact estimate for the possible values of Maslov index of a planar endomorphism with fixed algebraic degrees of its components (cf. [6], Chapter 6). These estimates and similar estimates for the number of complex points and elliptic complex points will be presented elsewhere.

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გამომცემი

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სიბრტყის ენდომორფიზმთა კომპლექსური წერტილების შესახებ

**რეზიუმე:** დადგენილია ზუსტი ფორმულა სიბრტყის ენდომორფიზმის კომპლექსური წერტილების რიცხვისათვის. გამოთვლილია აგრეთვე ელიფსური წერტილების რაოდენობა.

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On Marcinkiewicz Type M

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**ABSTRACT.** In the paper the best possible conditions for the existence and integrability of Marcinkiewicz operators are established.

**Key words:** multidimensional operators

1. We use some notations from monogenic elements of  $n$  ( $n \geq 2$ )-dimensional Euclidean space  $x = (x_1, x_2, \dots, x_n), y = (y_1, y_2, \dots, y_n), \dots, s = (s_1, s_2, \dots, s_n)$ .

$$M = \{1, 2, \dots, n\}, B = \{i_1^{\beta_1}, i_2^{\beta_2}, \dots, i_n^{\beta_n}\} \\ |B| = \text{Card } B, T^B = \{ \dots \}$$

If  $x \in R^n$ , then  $x_B$  denotes the point, where the plane  $B$  coincides with corresponding coordinates  $(x_M \equiv x, x_{\emptyset} \equiv 0)$ .

2. We consider the functions  $f: R^n \rightarrow R^m, f \in L(T^m)$ . We denote

$$F(x) = F(x, f) = F(x, f)$$

where  $ds_B = ds_{i_1} ds_{i_2} \dots ds_{i_k}$ . We assume that  $f$  is continuous in each variable. If  $B_1 = \{i_1\}$ , then we assume

$$\Delta_{B_1}(F, x, s_{B_1}) = F(x + s_{B_1}, f)$$

When  $|B| \geq 2$ , then by  $\Delta_B(F, x, s_B)$  we denote the operation fixed in (1) to all indices from  $B$ . The results depend on the sequence of operations. Let

$$F_B^*(x, \varepsilon_B) = \int_{\varepsilon_B} F(x, f)$$

3. In the paper the best possible conditions for the existence of the function