

ON PARTICLE TYPE STRING SOLUTIONS IN $\text{AdS}_3 \times \text{S}^3$

G. JORJADZE, Z. KEPULADZE AND L. MEGRELIDZE

Abstract. The $\text{AdS}_3 \times \text{S}^3$ string dynamics is described in a conformal gauge using the $\text{SL}(2, \mathbb{R})$ and $\text{SU}(2)$ group variables as the target space coordinates. A subclass of string surfaces with constant induced metric tensor on both AdS_3 and S^3 projections is considered. The general solution of string equations on this subclass is presented and the corresponding conserved charges related to the isometry transformations are calculated. The subclass of solutions is characterized by a finite number of parameters. The Poisson bracket structure on the space of parameters is calculated, its connection to the particle dynamics in $\text{SL}(2, \mathbb{R}) \times \text{SU}(2)$ is analyzed and a possible way of quantization is discussed.

რეზიუმე. $\text{SL}(2, \mathbb{R})$ და $\text{SU}(2)$ ჯგუფური ცვლადები გამოყენებულია სივრცე-დროის კოორდინატებად და მათი საშუალებით აღწერილია $\text{AdS}_3 \times \text{S}^3$ სიმის დინამიკა კონფორმულ ყალბში. განხილულია სიმის ზედაპირების ქვეკლასი მუდმივი ინდუცირებული მეტრიკით როგორც AdS_3 ისე S^3 პროექციაზე. აღნიშნული ქვეკლასისთვის ნაპოვნია სიმის განტოლებების ზოგადი ამოხსნა, რომლისთვისაც გამოთვლილია იზომეტრული გარდაქმნების შესაბამისი შენახვადი მუხტები. ამოხსნების ქვეკლასი ხასიათდება სასრული რაოდენობის პარამეტრებით. ამ პარამეტრების სივრცეზე ნაპოვნია პუანსონის ფრჩხილების სტრუქტურა, გაანალიზებულია მისი კავშირი $\text{SL}(2, \mathbb{R}) \times \text{SU}(2)$ ნაწილაკის დინამიკასთან და აღწერილია დაქვანტების შესაძლო გზები.

INTRODUCTION

The AdS/CFT correspondence [1] is one of the most fruitful research topic in modern theoretical and mathematical physics of the last decade. The correspondence is usually realized by a set of mapping rules for certain quantities of the partner theories, which are $\mathcal{N} = 4$ supersymmetric Yang-Mills gauge theory in four-dimensional Minkowski space from one side and $\text{AdS}_5 \times \text{S}^5$ superstring theory from the other. One of such rules is the map of conformal scaling dimensions of composite operators of the gauge theory to

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the energy spectrum of certain string configurations [2]. After the discovery of an integrable structure behind the spectral problem of scaling dimensions [3] and the Lax pair formulation of the $\text{AdS}_5 \times \text{S}^5$ string dynamics [4], the issue of integrability became the main research line in AdS/CFT [5].

In the present paper we study string dynamics in the $\text{AdS}_3 \times \text{S}^3$ background, which can be treated as a subspace of $\text{AdS}_5 \times \text{S}^5$. The paper is a natural continuation of the work done in [6] and [7], where the authors studied spacelike string configurations in $\text{AdS}_3 \times \text{S}^3$ with null polygons at the AdS boundary. The motivation of that work was the analysis of gluon scattering amplitudes at strong coupling given by a regularized area of string surfaces [8–12].

The integration methods used in [6, 7] can be generalized for dynamical strings, replacing the holomorphic structure of Euclidean surfaces by the chiral structure of Lorentzian worldsheets. An additional new point is the periodicity condition, which has to be imposed for closed string dynamics.

The aim of the work we are starting here is to quantize $\text{AdS}_3 \times \text{S}^3$ string dynamics and to investigate its energy spectrum. This is a hard problem, in general, and in the present paper we restrict ourselves to a subclass of string solutions, with similar characteristics as in [6, 7]. In terms of invariant geometrical quantities these are intrinsically flat surfaces, with constant mean curvatures on both AdS_3 and S^3 projections. These restrictions provide a finite dimensional mechanical system like a particle in $\text{AdS}_3 \times \text{S}^3$. However, in contrast to a particle, our string solutions are characterized by winding numbers and they have additional degrees of freedom.

The fact that AdS_3 and S^3 spaces can be treated as group manifolds, simplifies the analysis of integrability on the basis of the left and right symmetry transformations. However, for a physical interpretation of results, usually it is more convenient to use embedding coordinates of AdS_3 and S^3 . Therefore, we apply both target space coordinates in the text. Due to the additional freedom mentioned above, the left and right Casimir numbers, in general, are different. This asymmetry, which is absent for the particle dynamics, has to be realized on the quantum level by a special representation of the $\text{SL}(2, \mathbb{R}) \times \text{SL}(2, \mathbb{R})$ and $\text{SU}(2) \times \text{SU}(2)$ symmetries.

The outline of the paper is the following: we describe the $\text{AdS}_3 \times \text{S}^3$ string dynamics in terms $\text{SL}(2, \mathbb{R})$ and $\text{SU}(2)$ target space variables and conformal worldsheet coordinates. Components of the metric tensors on the AdS_3 and S^3 projections are simplified by turning the chiral and antichiral ones to constants, as in the Pohlmeyer reduction [13–17]. We then consider the subclass of worldsheets which have the remaining component of the metric tensor also constant on both AdS_3 and S^3 parts. This subclass is exactly integrable and the corresponding string solutions are characterized by a finite number of parameters. Among the parameters are four integers which describe different topological sectors of string configuration. We calculate the

conserved charges related to the isometry transformations and reduce the symplectic structure of the system to the subspace of solutions. To simplify the analysis of the physical phase space, we choose a topological sector of the solutions characterized by one winding number around a cylinder and a torus, which describe string configurations in AdS_3 and S^3 projections, respectively. Finally, we compare the obtained string configurations to the particle dynamics in $\text{AdS}_3 \times \text{S}^3$ and discuss a possible way of quantization. Some technical details are given in the Appendix.

AD S_3 AND S^3 AS GROUP MANIFOLDS

The AdS_3 and S^3 spaces are realized as the $\text{SL}(2, \mathbb{R})$ and $\text{SU}(2)$ group manifolds, respectively, via

$$g = \begin{pmatrix} Y^{0'} + Y^2 & Y^1 + Y^0 \\ Y^1 - Y^0 & Y^{0'} - Y^2 \end{pmatrix}, \quad h = \begin{pmatrix} X^4 + iX^3 & X^2 + iX^1 \\ -X^2 + iX^1 & X^4 - iX^3 \end{pmatrix}. \quad (1)$$

Here $(Y^{0'}, Y^0, Y^1, Y^2)$ are coordinates of the embedding space $\mathbb{R}^{2,2}$ and the equation for the hyperboloid

$$Y \cdot Y \equiv -Y_0'^2 - Y_0^2 + Y_1^2 + Y_2^2 = -1, \quad (2)$$

which defines the AdS_3 space, is equivalent to $g \in \text{SL}(2, \mathbb{R})$. Similarly, the equation for S^3 embedded in \mathbb{R}^4

$$X \cdot X \equiv X_1^2 + X_2^2 + X_3^2 + X_4^2 = 1 \quad (3)$$

is equivalent to $h \in \text{SU}(2)$.

We use the following basis in $\mathfrak{sl}(2, \mathbb{R})$

$$\mathbf{t}_0 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad \mathbf{t}_1 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \mathbf{t}_2 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}. \quad (4)$$

These three matrices \mathbf{t}_μ ($\mu = 0, 1, 2$) satisfy the relations

$$\mathbf{t}_\mu \mathbf{t}_\nu = \eta_{\mu\nu} \mathbf{I} + \epsilon_{\mu\nu}^\rho \mathbf{t}_\rho, \quad (5)$$

where $\eta_{\mu\nu} = \text{diag}(-1, 1, 1)$ and $\epsilon_{\mu\nu\rho}$ is the Levi-Civita tensor with $\epsilon_{012} = 1$. The inner product defined by $\langle \mathbf{t}_\mu, \mathbf{t}_\nu \rangle \equiv \frac{1}{2} \text{tr}(\mathbf{t}_\mu \mathbf{t}_\nu) = \eta_{\mu\nu}$ provides the isometry between $\mathfrak{sl}(2, \mathbb{R})$ and 3d Minkowski space.

A similar basis in $\mathfrak{su}(2)$ is given by the anti-hermitian matrices $\mathbf{s}_n = i\boldsymbol{\sigma}_n$ ($n = 1, 2, 3$), where $\boldsymbol{\sigma}_n$ are the Pauli matrices ($\boldsymbol{\sigma}_1 = \mathbf{t}_1$, $\boldsymbol{\sigma}_2 = -i\mathbf{t}_0$, $\boldsymbol{\sigma}_3 = \mathbf{t}_2$), and they form the algebra

$$\mathbf{s}_m \mathbf{s}_n = -\delta_{mn} \mathbf{I} - \epsilon_{mnl} \mathbf{s}_l. \quad (6)$$

The inner product is introduced by a similarly normalized trace, but with the negative sign $\langle \mathbf{s}_m, \mathbf{s}_n \rangle \equiv -\frac{1}{2} \text{tr}(\mathbf{s}_m \mathbf{s}_n) = \delta_{mn}$. That provides the isometry of $\mathfrak{su}(2)$ with \mathbb{R}^3 .

Two definitions in (1) can be written as $g = Y^{0'} \mathbf{I} + Y^\mu \mathbf{t}_\mu$, $h = X_4 \mathbf{I} + X_n \mathbf{s}_n$ and the corresponding inverse group elements are $g^{-1} = Y^{0'} \mathbf{I} - Y^\mu \mathbf{t}_\mu$,

$h^{-1} = X_4 \mathbf{I} - X_n \mathbf{s}_n$. Using now (5) and (6), one finds the following relations between the metrics on these spaces

$$dY \cdot dY = \langle (g^{-1} dg) (g^{-1} dg) \rangle, \quad dX \cdot dX = \langle (h^{-1} dh) (h^{-1} dh) \rangle. \quad (7)$$

These relations allow to write the $\text{AdS}_3 \times \text{S}^3$ string action in terms of the group variables.

STRING DESCRIPTION IN TERMS OF GROUP VARIABLES

According to (7), the components of the induced metric tensors on the AdS_3 and S^3 projections can be written as*

$$f_{ab} = \langle (g^{-1} \partial_a g) (g^{-1} \partial_b g) \rangle, \quad f_{ab}^s = \langle (h^{-1} \partial_a h) (h^{-1} \partial_b h) \rangle, \quad (8)$$

where we use the covariant notation $\partial_a = \partial_{\xi^a}$ ($a = 0, 1$), $(\xi^0, \xi^1) = (\tau, \sigma)$.

A timelike surface in $\text{AdS}_3 \times \text{S}^3$ can be parameterized by conformal worldsheet coordinates $z = \tau + \sigma$, $\bar{z} = \tau - \sigma$ and one gets a pair of worldsheet fields $g(z, \bar{z}) \in \text{SL}(2, \mathbb{R})$ and $h(z, \bar{z}) \in \text{SU}(2)$. With the notation $\partial = \frac{1}{2}(\partial_\tau + \partial_\sigma)$, $\bar{\partial} = \frac{1}{2}(\partial_\tau - \partial_\sigma)$, the conformal gauge conditions take the form

$$\langle (g^{-1} \partial g)^2 \rangle + \langle (h^{-1} \partial h)^2 \rangle = 0 = \langle (g^{-1} \bar{\partial} g)^2 \rangle + \langle (h^{-1} \bar{\partial} h)^2 \rangle. \quad (9)$$

We consider a closed string with periodic ($\sigma \in \text{S}^1$) boundary conditions. Its action in the gauge (9) is given by

$$S = \frac{\sqrt{\lambda}}{\pi} \int d\tau \int_0^{2\pi} d\sigma [\langle (g^{-1} \partial g) (g^{-1} \bar{\partial} g) \rangle + \langle (h^{-1} \partial h) (h^{-1} \bar{\partial} h) \rangle], \quad (10)$$

where λ is a coupling constant, and the equations of motion become

$$\partial (g^{-1} \bar{\partial} g) + \bar{\partial} (g^{-1} \partial g) = 0, \quad \partial (h^{-1} \bar{\partial} h) + \bar{\partial} (h^{-1} \partial h) = 0. \quad (11)$$

These equations provide the chirality conditions

$$\begin{aligned} \bar{\partial} \langle (g^{-1} \partial g)^2 \rangle &= 0 = \partial \langle (g^{-1} \bar{\partial} g)^2 \rangle, \\ \bar{\partial} \langle (h^{-1} \partial h)^2 \rangle &= 0 = \partial \langle (h^{-1} \bar{\partial} h)^2 \rangle. \end{aligned} \quad (12)$$

Using then the freedom of conformal transformations one can map the chiral $\langle (h^{-1} \partial h)^2 \rangle$ and antichiral $\langle (h^{-1} \bar{\partial} h)^2 \rangle$ components of the metric tensor on S^3 to positive constants. As a result, from (9) we get the gauge fixing conditions

$$\begin{aligned} \langle (g^{-1} \partial g)^2 \rangle &= -\mu^2 = -\langle (h^{-1} \partial h)^2 \rangle, \\ \langle (g^{-1} \bar{\partial} g)^2 \rangle &= -\bar{\mu}^2 = -\langle (h^{-1} \bar{\partial} h)^2 \rangle, \end{aligned} \quad (13)$$

with constant μ and $\bar{\mu}$. These constants become dynamical parameters of string solutions like zero modes on a cylinder.

*In this paper (as in [6, 7]) the index s is used for some variables of the spherical part to distinguish them from similar variables of the AdS part.

After imposing the gauge fixing conditions (13), the $z\bar{z}$ component of the metric tensor still remains arbitrary and due to (13) its $\text{SL}(2, \mathbb{R})$ and $\text{SU}(2)$ parts can be written as

$$\langle g^{-1} \partial g g^{-1} \bar{\partial} g \rangle = -\mu \bar{\mu} \cosh \alpha, \quad \langle h^{-1} \partial h h^{-1} \bar{\partial} h \rangle = \mu \bar{\mu} \cos \beta, \quad (14)$$

where α and β are worldsheet fields.

In the next sections we consider string solutions with constant α and β . They are characterized by a finite number of parameters. Note that a constant induced metric tensor on a cylindrical worldsheet is invariant under translations of (τ, σ) coordinates and this freedom can be used to reduced the number of parameters by two. Finally, the obtained dynamical system becomes similar to a particle in $\text{SL}(2, \mathbb{R}) \times \text{SU}(2)$. However, there is also an essential difference, which has to be taken into account in quantization.

PARTICLE TYPE SOLUTIONS

In (τ, σ) coordinates the equations of motion (11) takes the form

$$\partial_\tau(g^{-1}\partial_\tau g) - \partial_\sigma(g^{-1}\partial_\sigma g) = 0, \quad \partial_\tau(h^{-1}\partial_\tau h) - \partial_\sigma(h^{-1}\partial_\sigma h) = 0, \quad (15)$$

and the metric tensors (8) become

$$f_{ab} = \begin{pmatrix} -2\bar{\mu}\mu \cosh \alpha - \bar{\mu}^2 - \mu^2 & \bar{\mu}^2 - \mu^2 \\ \bar{\mu}^2 - \mu^2 & 2\bar{\mu}\mu \cosh \alpha - \bar{\mu}^2 - \mu^2 \end{pmatrix}, \quad (16)$$

$$f_{ab}^s = \begin{pmatrix} \bar{\mu}^2 + \mu^2 + 2\bar{\mu}\mu \cos \beta & \mu^2 - \bar{\mu}^2 \\ \mu^2 - \bar{\mu}^2 & \bar{\mu}^2 + \mu^2 - 2\bar{\mu}\mu \cos \beta \end{pmatrix}.$$

The integration of (15) for constant metric tensors (16) can be done similarly to the spacelike surfaces with the help of auxiliary linear systems [7]. Constant metric tensors (16) provide constant coefficients of the linear systems. The integration is then straightforward and we find the solutions

$$g(\tau, \sigma) = e^{(\lambda\tau + \frac{m}{2}\sigma)\hat{l}} g_0 e^{(\rho\tau + \frac{n}{2}\sigma)\hat{r}}, \quad (17)$$

$$h(\tau, \sigma) = e^{(\lambda_s\tau + \frac{m_s}{2}\sigma)\hat{l}_s} h_0 e^{(\rho_s\tau + \frac{n_s}{2}\sigma)\hat{r}_s}.$$

Here $g_0 \in \text{SL}(2, \mathbb{R})$ and $h_0 \in \text{SU}(2)$ are constant group elements, \hat{l} and \hat{r} are unit timelike elements of $\mathfrak{sl}(2, \mathbb{R})$, \hat{l}_s and \hat{r}_s are unit vectors of $\mathfrak{su}(2)$

$$\langle \hat{l} \hat{l} \rangle = -1 = \langle \hat{r} \hat{r} \rangle, \quad \langle \hat{l}_s \hat{l}_s \rangle = 1 = \langle \hat{r}_s \hat{r}_s \rangle, \quad (18)$$

and the other parameters are related to each other by

$$4\lambda\rho = mn, \quad 4\lambda_s\rho_s = m_s n_s. \quad (19)$$

The numbers m and n (as well as m_s and n_s) are integers with a same parity $m - n = 2k$ ($m_s - n_s = 2k_s$), that provides the periodicity conditions

$$g(\tau, \sigma + 2\pi) = g(\tau, \sigma), \quad h(\tau, \sigma + 2\pi) = h(\tau, \sigma). \quad (20)$$

The isometry transformations of $SL(2, \mathbb{R})$ and $SU(2)$ are given by the left and right multiplications of the group variables

$$g \mapsto g_L g g_R, \quad h \mapsto h_L h h_R, \quad (21)$$

and they transform the parameters of the solutions (17) by

$$\begin{aligned} \hat{l} &\mapsto g_L \hat{l} g_L^{-1}, & \hat{r} &\mapsto g_R^{-1} \hat{r} g_R, & \hat{l}_s &\mapsto h_L \hat{l}_s h_L^{-1}, & \hat{r}_s &\mapsto h_R^{-1} \hat{r}_s h_R, \\ g_0 &\mapsto g_L g_0 g_R, & h_0 &\mapsto h_L h_0 h_R, \end{aligned} \quad (22)$$

leaving λ, ρ and λ_s, ρ_s invariant. The integers m, n, m_s, n_s are, of course, also invariant. Additional invariants of the isometry transformations are the following parameters

$$\cosh 2\theta = -\langle \hat{l} g_0 \hat{r} g_0^{-1} \rangle, \quad \cos 2\theta_s = \langle \hat{l}_s h_0 \hat{r}_s h_0^{-1} \rangle, \quad (23)$$

which have an invariant geometrical meaning. Namely, the mean curvatures of the surfaces in $SL(2, \mathbb{R})$ and $SU(2)$ are given by $H = -\coth 2\theta$ and $H_s = \cot 2\theta_s$, respectively.

Using the isometry transformations (21) one can bring the solutions (17) to the form

$$\begin{aligned} g &= e^{\theta_l t_0} e^{\theta t_1} e^{\theta_r t_0}, & h &= e^{\theta_l^s s_3} e^{\theta_s s_2} e^{\theta_r^s s_3}, \\ \theta_l &= \lambda \tau + \frac{m}{2} \sigma, & \theta_r &= \rho \tau + \frac{n}{2} \sigma, & \theta_l^s &= \lambda_s \tau + \frac{m_s}{2} \sigma, & \theta_r^s &= \rho_s \tau + \frac{n_s}{2} \sigma. \end{aligned} \quad (24)$$

The corresponding 2×2 matrices are (see Appendix)

$$\begin{aligned} g &= \begin{pmatrix} \sinh \theta \sin \xi + \cosh \theta \cos \eta & \cosh \theta \sin \eta + \sinh \theta \cos \xi \\ \sinh \theta \cos \xi - \cosh \theta \sin \eta & \cosh \theta \cos \eta - \sinh \theta \sin \xi \end{pmatrix}, \\ h &= \begin{pmatrix} \cos \theta_s e^{i\xi_s} & \sin \theta_s e^{i\eta_s} \\ -\sin \theta_s e^{-i\eta_s} & \cos \theta_s e^{-i\xi_s} \end{pmatrix}, \end{aligned} \quad (25)$$

with $\eta = \theta_l + \theta_r$, $\xi = \theta_l - \theta_r$, $\eta_s = \theta_l^s - \theta_r^s$, $\xi_s = \theta_l^s + \theta_r^s$. The embedding coordinates of the AdS_3 and S^3 spaces then become

$$\begin{aligned} Y^{0'} &= \cosh \theta \cos \eta, & Y^0 &= \cosh \theta \sin \eta, \\ Y^1 &= \sinh \theta \cos \xi, & Y^2 &= \sinh \theta \sin \xi, \\ X_1 &= \sin \theta_s \sin \eta_s, & X_2 &= \sin \theta_s \cos \eta_s, \\ X_3 &= \cos \theta_s \sin \xi_s, & X_4 &= \cos \theta_s \cos \xi_s. \end{aligned} \quad (26)$$

These surfaces represent a tube in AdS_3 and a torus in S^3 (see Fig. 1). Thus, the string is located around the ‘center’ of AdS_3 like a static particle in a rest frame. If one makes a boost transformation, string will oscillate around the center like a massive particle in AdS .

To understand the physical characteristics of the solutions (17), we introduce the conserved currents related to the isometry transformations

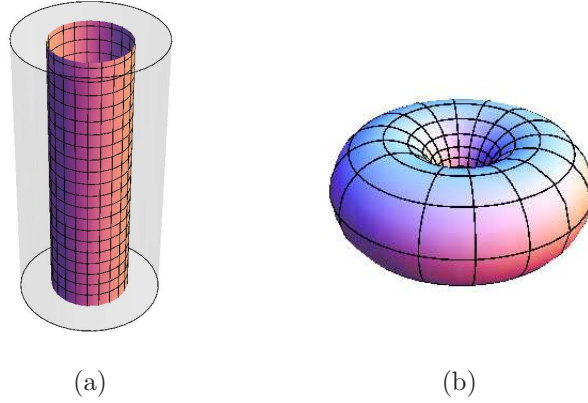


FIGURE 1. The plot (a) here corresponds to the AdS projection given by the first line of equation (26) and the plot (b) to the spherical one.

(21). The Lie algebra valued currents in the $SL(2, \mathbb{R})$ sector are given by $L_a = \partial_a g g^{-1}$, $R_a = g^{-1} \partial_a g$ and inserting here the solution (17), we find

$$\begin{aligned} L_\tau &= \lambda \hat{l} + \rho e^{\theta_i \hat{l}} g_0 \hat{r} g_0^{-1} e^{-\theta_i \hat{l}}, & R_\tau &= \lambda e^{-\theta_r \hat{r}} g_0^{-1} \hat{l} g_0 e^{\theta_r \hat{r}} + \rho \hat{r} \\ L_\sigma &= \frac{m}{2} \hat{l} + \frac{n}{2} e^{\theta_i \hat{l}} g_0 \hat{r} g_0^{-1} e^{-\theta_i \hat{l}}, & R_\sigma &= \frac{m}{2} e^{-\theta_r \hat{r}} g_0^{-1} \hat{l} g_0 e^{\theta_r \hat{r}} + \frac{n}{2} \hat{r}. \end{aligned} \quad (27)$$

The equation of motion (15) for the $SL(2, \mathbb{R})$ part is equivalent to the current conservation law $\partial_\tau R_\tau - \partial_\sigma R_\sigma = 0 = \partial_\tau L_\tau - \partial_\sigma L_\sigma$, which is simply fulfilled by (19).

The induced metric tensor on the $SL(2, \mathbb{R})$ part can be written as

$$f_{ab} = \langle L_a L_b \rangle = \langle R_a R_b \rangle, \quad (28)$$

and comparing it with (16) we obtain the equations

$$\begin{aligned} \lambda^2 + \rho^2 + 2\lambda\rho \cosh 2\theta &= \bar{\mu}^2 + \mu^2 + 2\bar{\mu}\mu \cosh \alpha, \\ \frac{1}{4}(m^2 + n^2 + 2mn \cosh 2\theta) &= \bar{\mu}^2 + \mu^2 - 2\bar{\mu}\mu \cosh \alpha, \\ \frac{1}{2}[\lambda m + \rho n + (\lambda n + \rho m) \cosh 2\theta] &= \mu^2 - \bar{\mu}^2, \end{aligned} \quad (29)$$

which connect the parameters of the solution to the components of the induced metric tensor.

The SU(2) conserved currents have the same form $L_a^s = \partial_a h h^{-1}$, $R_a^s = h^{-1} \partial_a h$ and from (16) and (17) we find the relations similar to (29)

$$\begin{aligned} \lambda_s^2 + \rho_s^2 + 2\lambda_s \rho_s \cos 2\theta_s &= \bar{\mu}^2 + \mu^2 + 2\bar{\mu}\mu \cos \beta, \\ \frac{1}{4}(m_s^2 + n_s^2 + 2m_s n_s \cos 2\theta_s) &= \bar{\mu}^2 + \mu^2 - 2\bar{\mu}\mu \cos \beta, \\ \frac{1}{2}[\lambda_s m_s + \rho_s n_s + (\lambda_s n_s + \rho_s m_s) \cos 2\theta_s] &= \mu^2 - \bar{\mu}^2. \end{aligned} \quad (30)$$

The calculation of the SL(2, \mathbb{R}) conserved charges

$$L = \int_0^{2\pi} \frac{d\sigma}{2\pi} L_\tau, \quad R = \int_0^{2\pi} \frac{d\sigma}{2\pi} R_\tau, \quad (31)$$

for the solution (17) yields (see Appendix)

$$L = (\lambda + \rho \cosh 2\theta) \hat{l}, \quad R = (\lambda \cosh 2\theta + \rho) \hat{r}, \quad (32)$$

and, similarly, for the SU(2) charges one gets

$$L_s = (\lambda_s + \rho_s \cos 2\theta_s) \hat{l}_s, \quad R_s = (\lambda_s \cos 2\theta_s + \rho_s) \hat{r}_s. \quad (33)$$

One can solve μ^2 and $\bar{\mu}^2$ from the equations (29) and (30) separately and then comparing these solutions one finds two relations between the invariant parameters λ , ρ , θ and their spherical counterparts λ_s , ρ_s , θ_s . Together with (19), we conclude that the space of isometrically invariant parameters is two dimensional. At this point we relate to each other the parameters of the AdS₃ and S³ spaces. The joint analysis of the equations (29)-(30) for arbitrary m , n and m_s , n_s is rather complicated and, in general, they have no consistent solutions. In this paper we concentrate to the case $m_s = n_s = -m = n > 0$. The corresponding AdS₃ and S³ solutions (26) become

$$\begin{aligned} Y &= (\cosh \theta \cos E\tau, \cosh \theta \sin E\tau, \\ &\quad \sinh \theta \cos(F\tau - n\sigma), \sinh \theta \sin(F\tau - n\sigma)), \\ X &= (\sin \theta_s \sin A\tau, \sin \theta_s \cos A\tau, \cos \theta_s \sin(B\tau + n\sigma), \\ &\quad \cos \theta_s \cos(B\tau + n\sigma)), \end{aligned} \quad (34)$$

where $E = \lambda + \rho$, $F = \lambda - \rho$, $A = \lambda_s - \rho_s$ and $B = \lambda_s + \rho_s$. Due to (19), the new parameters are related by

$$F^2 - E^2 = n^2, \quad B^2 - A^2 = n^2, \quad (35)$$

where n is the winding number. For fixed τ , the string (34) winds n -times around the circles in the (Y^1, Y^2) and (X^3, X^4) planes. Since the polar angle in the $(Y^{0'}, Y^0)$ plane corresponds to the time variable, the solution (34) describes string in a static gauge.

From equation (29) we find

$$\begin{aligned} \mu^2 &= \frac{n^2}{4} (f-1)(f+\cosh 2\theta), & \bar{\mu}^2 &= \frac{n^2}{4} (f+1)(f-\cosh 2\theta), \\ \cosh \alpha &= \frac{e}{\sqrt{e^2 - \sinh^2 2\theta}}, \end{aligned} \quad (36)$$

where e and f are the rescaled variable $e = E/n$, $f = F/n$, with $f^2 - e^2 = 1$. Similarly, equation (30) provides

$$\begin{aligned} \mu^2 &= \frac{n^2}{4} (b+1)(b+\cos 2\theta_s), & \bar{\mu}^2 &= \frac{n^2}{4} (b-1)(b-\cos 2\theta_s), \\ \cos \beta &= \frac{a}{\sqrt{a^2 - \sin^2 2\theta_s}}, \end{aligned} \quad (37)$$

with $a = A/n$, $b = B/n$, $b^2 - a^2 = 1$. Choosing b and f as independent variables on the space of invariants, we find

$$\cosh 2\theta = bf - b^2 + 1, \quad \cos 2\theta_s = f^2 - bf - 1. \quad (38)$$

Let us consider the parametrization of g_0 . It can be written as

$$g_0 = e^{\phi_l \hat{l}} e^{-(\gamma+\theta)\hat{n}} e^{\phi_r \hat{r}}, \quad (39)$$

where \hat{n} is a normalized commutator of the matrixes \hat{l} and \hat{r} (see (A.6)), γ is the corresponding ‘angle’ variable between them and ϕ_l, ϕ_r are arbitrary parameters. Equation (39) has the following geometrical interpretation: \hat{n} is a generator of boosts in the (\hat{l}, \hat{r}) ‘plane’ (see (A.8)) and by (A.9) one finds the boost parameter $\alpha = \gamma + \theta$ to match (23). The angle parameters ϕ_l and ϕ_r in (39) then describe the freedom that leaves (23) invariant.

The parametrization of h_0 is obtained in a similar way

$$h_0 = e^{\phi_l^s \hat{l}_s} e^{-(\gamma_s+\theta_s)\hat{n}_s} e^{\phi_r^s \hat{r}_s}, \quad (40)$$

where n_s, γ_s and ϕ_l^s, ϕ_r^s have the same geometrical interpretation in $SU(2)$ as their counterparts in $SL(2, \mathbb{R})$.

Now we recall that (τ, σ) coordinates still have a freedom in translations. Using equations (39), (40), and the form of the solutions (17), one can reduce the number of angle parameters $(\phi_l, \phi_r, \phi_l^s, \phi_r^s)$ from four to two. We denote these two parameter by φ_1, φ_2 . One can choose, for example, $\varphi_1 = \phi_l = -\phi_r$ and $\varphi_2 = \phi_l^s = \phi_r^s$.

Thus, solutions (17) are described by four unit vectors $(\hat{l}, \hat{r}, \hat{l}_s, \hat{r}_s)$, two isometrically invariant parameters (f, b) and two remaining angle variables (φ_1, φ_2) . Totally, one gets twelve dimensional space of parameter.

To find the Poisson bracket structure on this space, one can calculate the symplectic form of the system $\omega = d\vartheta$ on the space of solutions (17) and

invert it. The presymplectic 1-form ϑ is defined from the string Lagrangian in the first order formalism

$$\vartheta = \int_0^{2\pi} \frac{d\sigma}{2\pi} [\langle R g^{-1} dg \rangle + \langle R_s h^{-1} dh \rangle]. \quad (41)$$

Here R and R_s are Lie algebra valued variables, which in the conformal gauge are associated with $g^{-1}\partial_\tau g$ and $h^{-1}\partial_\tau h$, respectively. Before we discuss the reduction of the symplectic form on the string solutions, let us consider particle dynamics in $SL(2, \mathbb{R}) \times SU(2)$ and compare it to our system.

Particle trajectories in the $SL(2, \mathbb{R})$ sector are parameterized either by a pair (g_0, R) or (g_0, L)

$$g(\tau) = e^{L\tau} g_0 = g_0 e^{R\tau}, \quad (42)$$

where R and L are the dynamical integrals for the isometry transformations.[†] They are related to each other by the adjoint transformation

$$g R g^{-1} = L, \quad (43)$$

and, therefore, they are on the same coadjoint orbit.

The description of $SU(2)$ sector is similar and the orbits in both cases are defined by the Casimir numbers

$$\langle LL \rangle = \langle RR \rangle = -m^2, \quad \langle L_s L_s \rangle = \langle R_s R_s \rangle = m_s^2. \quad (44)$$

These numbers are related to the particle mass M by the massshell condition

$$m^2 - m_s^2 = M^2, \quad (45)$$

and the dynamical integrals can be written as

$$L = m \hat{l}, \quad R = m \hat{r}; \quad L_s = m_s \hat{l}_s, \quad R_s = m_s \hat{r}_s, \quad (46)$$

where \hat{l} , \hat{r} and \hat{l}_s , \hat{r}_s are unit vectors as for the string solutions (see (32)-(33)).

Hamiltonian formulation can be started in (R, g) , (R_s, h) variables and the presymplectic 1-form $\vartheta = \langle R g^{-1} dg \rangle + \langle R_s h^{-1} dh \rangle$, as in (41). However, in order to make further comparison with the string solutions, it is more convenient to use left and right dynamical integrals symmetrically and express g and h through them.

Let us consider the $SL(2, \mathbb{R})$ part. One can show that equation (43) defines g up to an angle variable φ [18]

$$g = e^{\theta_L \hat{n}_L} e^{\varphi \mathbf{t}_0} e^{\theta_R \hat{n}_R}. \quad (47)$$

[†]We use same notations as for string solutions.

Here

$$\hat{n}_L = \frac{[\mathbf{t}_0, \hat{l}]}{2 \sinh 2\theta_L}, \quad \hat{n}_R = -\frac{[\mathbf{t}_0, \hat{r}]}{2 \sinh 2\theta_R} \quad (48)$$

are normalized vectors and $\cosh 2\theta_L = -\langle \hat{l}, \mathbf{t}_0 \rangle$, $\cosh 2\theta_R = -\langle \hat{r}, \mathbf{t}_0 \rangle$ (see Appendix).

The symplectic form of the AdS part $\omega_{AdS} = d\langle Rg^{-1}dg \rangle$ calculate in the coordinates $(\hat{l}, \hat{r}, m, \varphi)$ splits into the sum of three terms

$$\omega_{AdS} = m\omega_L + m\omega_R - dm \wedge d\varphi, \quad (49)$$

where

$$\omega_L = \frac{dl_2 \wedge dl_1}{l_0}, \quad \omega_R = \frac{dr_1 \wedge dr_2}{r_0} \quad (50)$$

are the symplectic forms on the unit $SL(2, \mathbb{R})$ coadjoint orbits expressed in terms of the vector components $l_\mu = \langle \mathbf{t}_\mu, \hat{l} \rangle$ and $r_\mu = \langle \mathbf{t}_\mu, \hat{r} \rangle$.

The $SU(2)$ part of the symplectic form has a similar structure

$$\omega_s = m_s \omega_L^s + m_s \omega_R^s + dm_s \wedge d\varphi_s, \quad (51)$$

where now ω_L^s and ω_R^s are symplectic forms on the unit $SU(2)$ coadjoint orbits.

Finally, the total symplectic form $\omega = \omega_{AdS} + \omega_s$ has to be reduced on the massshell (45). This reduction leads to a ten dimensional phase space with the symplectic form

$$\omega = m\omega_L + m\omega_R + m_s \omega_L^s + m_s \omega_R^s + dm_s \wedge d\left(\varphi_s - \frac{\varphi}{\sqrt{m_s^2 + M^2}}\right), \quad (52)$$

where $m = \sqrt{M^2 + m_s^2}$. The reduced phase space is parameterized by four unit vectors $(\hat{l}, \hat{r}, \hat{l}_s, \hat{r}_s)$, one isometrically invariant parameter m_s and the corresponding angle variable. The inversion of (52) provides a Poisson bracket realization of the left-right symmetries

$$\{L_\mu, L_\nu\} = -2\epsilon_{\mu\nu}{}^\rho L_\rho, \quad \{R_\mu, R_\nu\} = 2\epsilon_{\mu\nu}{}^\rho R_\rho \quad (53)$$

with $L_\mu = \langle \mathbf{t}_\mu, L \rangle$, $R_\mu = \langle \mathbf{t}_\mu, R \rangle$ and similarly in the $SU(2)$ part.

The quantization of the particle dynamics on the basis of the symplectic form (52) is straightforward and it reproduces the same spectrum as other quantization schemes [19, 20]. Details of the quantization of the particle dynamics will be presented in a forthcoming paper, which will include the analysis of more general string solutions as well.

At the end of the present paper we return to the $SL(2, \mathbb{R}) \times SU(2)$ string dynamics. The calculation of the presymplectic 1-form (41) on the space of solutions (17) is similar to the calculation of the conserved charges given in Appendix. The exterior derivative then acts on the space of parameters and provides the following symplectic form

$$\omega = m_L \omega_L + m_R \omega_R + m_L^s \omega_L^s + m_R^s \omega_R^s + \tilde{\omega}(f, b; \varphi_1, \varphi_2). \quad (54)$$

Here m_L , m_R , m_L^s , m_R^s are the coefficients of the unit vectors in (32)-(33) and they define the Casimir numbers. An essential difference with the particle case is the asymmetry between the left and right Casimir numbers here. The rest part of the symplectic form (54) given by $\tilde{\omega}(f, b; \varphi_1, \varphi_2)$ is rather complicated. However, it does not contribute to the Poisson bracket structure of dynamical integrals. In particular, the isometrically invariant variables m_L , m_R , m_L^s , m_R^s have vanishing Poisson brackets with themselves and with the dynamical integrals. As it was mentioned above, the space of isometrically invariant variables is two dimensional. The structure of this space defines the character of coadjoint orbits, that is crucial for the symmetry group representations.

Quantization based on the symplectic form (54) is in progress.

APPENDIX

Here we present useful formulas for the $SU(2)$ and $SL(2, \mathbb{R})$ groups and sketch some calculations used in the main text.

From the algebras (5) and (6) follow simple exponentiation rules

$$e^{\theta \mathbf{t}_0} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}, \quad e^{\theta \mathbf{t}_1} = \begin{pmatrix} \cosh \theta & \sinh \theta \\ \sinh \theta & \cosh \theta \end{pmatrix}, \quad (\text{A.1})$$

$$e^{\theta \mathbf{s}_2} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}, \quad e^{\theta \mathbf{s}_3} = \begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}, \quad (\text{A.2})$$

which gives to the solutions (24) a compact matrix form (25).

Our convention on signatures correspond to the following summation rule

$$\epsilon_{\mu\nu\rho}\epsilon_{\mu'\nu'}{}^\rho = \eta_{\mu\nu'}\eta_{\nu\mu'} - \eta_{\mu\mu'}\eta_{\nu\nu'}. \quad (\text{A.3})$$

The charge R in (31) can be written as $R = \lambda\hat{J} + \rho\hat{r}$, where \hat{J} is the integral (see (27))

$$\hat{J} = \int_0^{2\pi} \frac{d\sigma}{2\pi} e^{-\theta_r \hat{r}} \hat{l}' e^{\theta_r \hat{r}}, \quad (\text{A.4})$$

with $\hat{l}' = g_0^{-1} \hat{l} g_0$ and θ_r given by (24). The exponents $e^{\pm\theta_r \hat{r}} = \cos \theta_r \mathbf{I} \pm \sin \theta_r \hat{r}$ create σ dependent trigonometric functions in (A.4) and after integration we find $\hat{J} = \frac{1}{2}(\hat{l}' - \hat{r} \hat{l}' \hat{r})$. By (5) and (A.3) one gets

$$\hat{r} \hat{l}' \hat{r} = \hat{l}' + 2\langle \hat{r} \hat{l}' \rangle \hat{r}, \quad (\text{A.5})$$

and taking into account (23), we obtain $\hat{J} = \cosh 2\theta \hat{r}$. This leads to equation (32) for R . The calculation of other charges is similar.

Let us introduce a normalized commutator of \hat{l} and \hat{r}

$$\hat{n} = \frac{[\hat{l}, \hat{r}]}{2 \sinh 2\gamma}, \quad \text{with} \quad \cosh 2\gamma = -\langle \hat{l} \hat{r} \rangle. \quad (\text{A.6})$$

This matrix satisfies the relations $\hat{n}^2 = \mathbf{I}$, $\hat{n}\hat{r} = -\hat{r}\hat{n}$ and it generates the boost transformation between \hat{l} and \hat{r}

$$e^{-\gamma\hat{n}}\hat{r}e^{\gamma\hat{n}} = e^{-2\gamma\hat{n}}\hat{r} = \hat{l}. \quad (\text{A.7})$$

The general boost transformation of \hat{r} is given by

$$e^{-\alpha\hat{n}}\hat{r}e^{\alpha\hat{n}} = \frac{\sinh 2(\gamma - \alpha)}{\sinh 2\gamma}\hat{r} + \frac{\sinh 2\alpha}{\sinh 2\gamma}\hat{l}, \quad (\text{A.8})$$

and provides

$$\langle \hat{l} e^{-\alpha\hat{n}} \hat{r} e^{\alpha\hat{n}} \rangle = -\cosh 2(\gamma - \alpha). \quad (\text{A.9})$$

This equation is used in (39) to fix the boost parameter α in g_0 .

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Authors' addresses:

G. Jorjadze

A. Razmadze Mathematical Institute
I. Javakhishvili Tbilisi State University
2, University Str., Tbilisi 0186
Georgia

Free University of Tbilisi
Bedia Str., 0183, Tbilisi, Georgia
E-mail: jorj@physik.hu-berlin.de

Z. Kepuladze and L. Megrelidze

Ilia State University
K. Cholokashvili Ave 3/5, 0162, Tbilisi, Georgia
E-mail: zkepuladze@yahoo.com
luka.megrelidze@gmail.com,