

On Initial-Boundary Value Problems for Quasilinear Hyperbolic Systems of Second Order

Maram M. Alrumayh

Florida Institute of Technology, Melbourne, USA

E-mail: malsalem2017@my.fit.edu

In the rectangle $\Omega = [0, a] \times [0, b]$ consider the nonlinear hyperbolic system

$$u_{xy} = f(x, y, u_x, u_y, u), \tag{1}$$

$$u(0, y) = \varphi(y), \quad h(u_x(x, \cdot))(x) = \psi'(x), \tag{2}$$

where $f : \Omega \times \mathbb{R}^{3n} \rightarrow \mathbb{R}^n$ is a continuous vector function that is continuously differentiable with respect to the first $2n$ phase variables, $\varphi \in C^1([0, b]; \mathbb{R}^n)$, $\psi \in C^1([0, a]; \mathbb{R}^n)$, and $h : C([0, b]; \mathbb{R}^n) \rightarrow C([0, a]; \mathbb{R}^n)$ is a bounded linear operator.

Let $v = (v_1, \dots, v_n)$, $w = (w_1, \dots, w_n)$ and $z = (z_1, \dots, z_n)$. For a function $f(x, y, v, w, u)$ that is continuously differentiable with respect to v , w and u , set:

$$F_1(x, y, v, w, z) = \frac{\partial f(x, y, v, w, z)}{\partial v}, \quad F_2(x, y, v, w, z) = \frac{\partial f(x, y, v, w, z)}{\partial w},$$

$$F_0(x, y, v, w, z) = \frac{\partial f(x, y, v, w, z)}{\partial z},$$

$$P_j[u](x, y) = F_j(x, y, u_x(x, y), u_y(x, y), u(x, y)) \quad (j = 0, 1, 2).$$

$C^{1,1}(\Omega; \mathbb{R}^n)$ is the Banach space of continuous vector functions $u : \Omega \rightarrow \mathbb{R}^n$, having continuous partial derivatives u_x, u_y, u_{xy} , endowed with the norm

$$\|u\|_{C^{1,1}} = \|u\|_C + \|u_x\|_C + \|u_y\|_C + \|u_{xy}\|_C.$$

$C^1(\Omega; \mathbb{R}^n)$ is the Banach space of continuous vector functions $u : \Omega \rightarrow \mathbb{R}^n$, having continuous partial derivatives u_x, u_y , endowed with the norm

$$\|u\|_{C^1} = \|u\|_C + \|u_x\|_C + \|u_y\|_C.$$

If $u_0 \in C(\Omega; \mathbb{R}^n)$ and $r > 0$, then

$$\mathbf{B}(u_0; r) = \{u \in C(\Omega; \mathbb{R}^n) : \|u - u_0\| \leq r\}.$$

If $u_0 \in C^1(\Omega; \mathbb{R}^n)$ and $r > 0$, then

$$\mathbf{B}^1(u_0; r) = \{u \in C^1(\Omega; \mathbb{R}^n) : \|u - u_0\|_{C^1} \leq r\}.$$

Definition 1. Let u_0 be a solution of problem (1), (2), and $r > 0$. Problem (1), (2) is said to be (u_0, r) -well-posed if:

- (i) $u_0(x, y)$ is the unique solution of the problem in the ball $\tilde{\mathbf{B}}^1(u_0; r)$;

- (ii) There exists $\varepsilon_0 > 0$ such that for an arbitrary $\varepsilon > 0$ and $M > 0$ there exists $\delta > 0$ such that for any $\tilde{f}(x, y, v, w, z)$ that is continuously differentiable with respect to v and w , $\tilde{\varphi} \in C^1([0, b]; \mathbb{R}^n)$, $\tilde{\psi} \in C^1([0, a]; \mathbb{R}^n)$, satisfying the inequalities

$$\left\| \frac{\partial \tilde{f}(x, y, v, w, z)}{\partial v} \right\| \leq \varepsilon_0 \quad \text{for } (x, y, v, w, z) \in \Omega \times \mathbb{R}^{3n} \quad (3)$$

$$\left\| \frac{\partial \tilde{f}(x, y, v, w, z)}{\partial w} \right\| \leq M \quad \text{for } (x, y, v, w, z) \in \Omega \times \mathbb{R}^{3n},$$

$$\|\tilde{f}(x, y, v, w, z)\| \leq \delta \quad \text{for } (x, y, v, w, z) \in \Omega \times \mathbb{R}^{3n}, \quad \|\tilde{\varphi}\|_{C^1([0, b])} + \|\tilde{\psi}\|_{C^1([0, a])} \leq \delta, \quad (4)$$

the problem

$$u_{xy} = f(x, y, u_x, u_y, u) + \tilde{f}(x, y, u_x, u_y, u), \quad (1)$$

$$u(0, y) = \varphi(y) + \tilde{\varphi}(y), \quad h(u_x(x, \cdot))(x) = \psi'(x) + \tilde{\psi}'(x), \quad (2)$$

has at least one solution in the ball $\mathbf{B}^1(u_0; r)$, and each such solution belongs to the ball $\mathbf{B}^1(u_0; \varepsilon)$.

Definition 2. Let u_0 be a solution of problem (1), (2), and $r > 0$. Problem (1), (2) is said to be *strongly* (u_0, r) -*well-posed* if:

- (i) Problem (1), (2) is (u_0, r) -well-posed;
- (ii) There exist positive numbers M_0 and δ_0 such that for arbitrary $\delta \in (0, \delta_0)$, $\tilde{f}(x, y, v, w, z)$ that is continuously differentiable with respect to v and w , $\tilde{\varphi} \in C^1([0, b]; \mathbb{R}^n)$ and $\tilde{\psi} \in C^1([0, a]; \mathbb{R}^n)$, satisfying the inequalities (3) and (4), problem (1), (2) has at least one solution in the ball $\mathbf{B}^1(u_0; r)$, and each such solution belongs to the ball $\mathbf{B}^1(u_0; M_0 \delta)$.

Definition 3. Problem (1), (2) is called *well-posed* (*strongly well-posed*) if it has a unique solution u_0 and it is (u_0, r) -well-posed (*strongly* (u_0, r) -well-posed) for every $r > 0$.

Consider the boundary value problem for the system of nonlinear ordinary differential equations

$$z' = p(t, z), \quad \ell(z) = c, \quad (5)$$

where $p \in C([0, b] \times \mathbb{R}^n; \mathbb{R}^n)$, $c \in \mathbb{R}^n$ and $\ell : C([0, b]; \mathbb{R}^n) \rightarrow \mathbb{R}^n$ is a bounded linear operator.

Definition 4. Let z_0 be a solution of problem (5), and $r > 0$. Problem (5) is said to be (z_0, r) -*well-posed* if:

- (i) $z_0(t)$ is the unique solution of the problem in the ball $\mathbf{B}(z_0; r)$;
- (ii) For an arbitrary $\varepsilon > 0$ there exists $\delta > 0$ such that for any \tilde{c} , and $\tilde{p} \in C([0, b] \times \mathbb{R}^n)$ satisfying the inequalities

$$\|c - \tilde{c}\| < \delta, \quad \|p - \tilde{p}\|_C < \delta \quad (6)$$

the problem

$$z' = \tilde{p}(t, z), \quad \ell(z) = \tilde{c}, \quad (5)$$

has at least one solution in the ball $\mathbf{B}(z_0; r)$, and each such solution belongs to the ball $\mathbf{B}(z_0; \varepsilon)$.

Definition 4 is a slight modification of Definition 3.2 from [1]. Definition 1 is an adaptation of the idea of Definition 4 to problem (1), (2).

Definition 5. Let u_0 be a solution of problem (5), and $r > 0$. Problem (5) is said to be *strongly* (z_0, r) -*well-posed* if:

- (i) $z_0(t)$ is the unique solution of the problem in the ball $\mathbf{B}(z_0; r)$;
- (ii) There exist positive numbers M and δ_0 such that for arbitrary $\delta \in (0, \delta_0)$, \tilde{c}_k , and $\tilde{p} \in C([0, b] \times \mathbb{R}^n)$ satisfying inequalities (6), problem (5) has at least one solution in the ball $\mathbf{B}(z_0; r)$, and each such solution belongs to the ball $\mathbf{B}(z_0; M \delta)$.

Remark 1. It is obvious that strong well-posedness implies well-posedness. The converse, however, is not true. As an example, consider the problem

$$z' = z^3, \quad z(0) = z(\omega), \tag{7}$$

which is well-posed and has the unique solution $z_0(t) \equiv 0$. The perturbed problem

$$z' = z^3 - \delta, \quad z(0) = z(b)$$

has the unique solution $z_\delta(t) = \delta^{\frac{1}{3}}$. It is clear that there exists no positive number M such that $\delta^{\frac{1}{3}} \leq M\delta$ as $\delta \rightarrow 0$. Consequently, problem (7) is not strongly well-posed.

Definition 6. A solution z_0 of problem (5) is said to be strongly isolated, if problem (5) is strongly (z_0, r) -well-posed for some $r > 0$.

Remark 2. The concept of a strongly isolated solution of a nonlinear boundary value problem was introduced in [1]. However, our definition of a strongly isolated solution is a modification of Definition 3.1 from [1]. Also, Corollary 3.6 from [1] implies that if the vector function $p(t, z)$ is continuously differentiable with respect to the phase variables, then strong isolation of a solution z_0 is equivalent to the fact that the linear homogeneous problem

$$z' = P(t)z, \quad \ell(z) = 0, \tag{8}$$

has only the trivial solution, where $P(t) = \frac{\partial p}{\partial z}(t, z_0(t))$.

Theorem 1. Let f be a continuously differentiable function with respect to the phase variables v, w and z , and let u_0 be a solution of problem (1), (2). Then, problem (1), (2) is strongly (u_0, r) -well-posed for some $r > 0$, if and only if the linear homogeneous problem

$$u_{xy} = P_0(x, y)u + P_1(x, y)u_x + P_2(x, y)u_y, \tag{10}$$

$$u(0, y) = 0, \quad h(u_x(x, \cdot))(x) = 0, \tag{20}$$

where $P_j(x, y) = P_j[u_0](x, y)$ ($j = 0, 1, 2$), is well-posed.

Theorem 2. Problem (1₀), (2₀) is well-posed if and only if the linear homogeneous problem

$$\frac{dz}{dy} = P_1(x, y)z, \quad h(z)(x) = 0$$

has only the trivial solution for every $x \in [0, a]$.

Remark 3. The sufficiency part of Theorem 2 was proved in [2] (see Theorems 4.1 and 4.1'). Similar theorem for higher order linear hyperbolic equations for proved in [4] (see Theorem 1.1).

Theorem 3. Let f be a continuously differentiable with respect to the phase variables v, w and z , and let there exist matrix functions $Q_i \in C(\Omega; \mathbb{R}^{n \times n})$ ($i = 1, 2$) and a positive constant ρ such that:

(A₁) $\|F_0(x, y, v, w, z)\| + \|F_2(x, y, v, w, z)\| \leq \rho$ for $(x, y, v, w, z) \in \Omega \times \mathbb{R}^{3n}$;

(A₂) $Q_1(x, y) \leq F_1(x, y, v, w, z) \leq Q_2(x, y)$ for $(x, y, v, w, z) \in \Omega \times \mathbb{R}^{3n}$;

(A₃) for every $x \in [0, a]$ and arbitrary measurable matrix function $P : [0, b] \rightarrow \mathbb{R}^{n \times n}$ satisfying the inequalities

$$Q_1(x, y) \leq P(y) \leq Q_2(x, y) \text{ for } y \in [0, b],$$

problem (8) has only the trivial solution. Then problem (1), (2) is strongly well-posed.

Theorem 4. Let f be a continuously differentiable function with respect to the phase variables v , w and z , and let v_0 be a strongly isolated solution of the problem

$$v' = p(y, v), \quad h(v)(0) = \psi'(0), \quad (9)$$

where

$$p(y, v) = f(0, y, v, \varphi'(y), \varphi(y)).$$

Then there exists $\alpha \in (0, a]$ such that in the rectangle $\Omega_\alpha = [0, \alpha] \times [0, b]$ problem (1), (2) has a unique solution u satisfying the condition

$$u_x(0, y) = v_0(y) \text{ for } y \in [0, b].$$

Remark 4. Conditions of Theorem 4 do not guarantee unique solvability of problem (1), (2). Indeed, consider the problem

$$u_{xy} = \prod_{k=1}^m (u_x - k) + x f_0(x, y, u_x, u_y, u), \quad (10)$$

$$u(0, y) = 0, \quad u^{(1,0)}(x, 0) = u^{(1,0)}(x, b), \quad (11)$$

where $f_0 : \Omega \times \mathbb{R}^3 \rightarrow \mathbb{R}$ is a continuously differentiable function. For this case problem (9) has the form

$$v' = \prod_{k=1}^m (v - k), \quad v(0) = v(b).$$

The latter problem has exactly m strongly isolated solutions $v_k = k\pi$ ($k = 1, \dots, m$). By Theorem 4, for every integer $k \in \{1, \dots, m\}$ there exists $\alpha_k > 0$ such that in $\Omega_{\alpha_k} = [0, \alpha_k] \times [0, b]$, problem (10), (11) has a unique solution u_k satisfying the condition

$$u_k^{(1,0)}(0, y) = k \text{ for } y \in [0, b].$$

Consider the family of problems

$$z' = p_\lambda(t, z), \quad \ell_\lambda(z) = c_\lambda, \quad (12_\lambda)$$

where $\lambda \in \Lambda$, $p_\lambda \in C([0, b] \times \mathbb{R}^n; \mathbb{R}^n)$, $\ell_\lambda : C([0, b]) \rightarrow \mathbb{R}^n$ are bounded linear functionals, and $c_\lambda \in \mathbb{R}^n$.

Let for $\lambda \in \Lambda$ and $r > 0$, z_λ be a solution of problem (12_λ). The family of problems (12_λ) ($\lambda \in \Lambda$) is said to be *uniformly strongly* (z_λ, r)-*well-posed*, if:

- (i) z_λ is unique in the ball $\mathbf{B}(z_\lambda; r)$;

- (ii) There exist positive numbers M and δ_0 independent of λ such that for arbitrary $\delta \in (0, \delta_0)$, $\tilde{c} \in \mathbb{R}^n$, and $\tilde{p}_\lambda \in C([0, b] \times \mathbb{R}^n; \mathbb{R}^n)$ satisfying the inequalities

$$\|c - \tilde{c}\| < \delta, \quad \|p_\lambda - \tilde{p}_\lambda\|_C < \delta,$$

the problem

$$z' = \tilde{p}_\lambda(t, z), \quad \ell_\lambda(z) = \tilde{c}_\lambda, \tag{12\lambda}$$

has at least one solution in the ball $\mathbf{B}(z_\lambda; r)$, and each such solution belongs to the ball $\mathbf{B}(z_\lambda; M\delta)$.

A family of solutions $\{z_\lambda\}_{\lambda \in \Lambda}$ is said to be *uniformly strongly isolated* if the family of problems (12 λ) ($\lambda \in \Lambda$) is *uniformly strongly* (z_λ, r) -*well-posed* for some $r > 0$.

Let $J = [0, \alpha]$, $\alpha \in (0, a]$, ($J = [0, \alpha]$, $\alpha \in (0, a)$), and u be a solution of problem (1), (2) in the rectangle $J \times [0, b]$. u is called *continuable*, if there exists $\alpha_1 \in [\alpha, a]$ ($\alpha_1 \in (\alpha, a]$) and a solution u_1 of problem (1), (2) in $[0, \alpha_1] \times [0, b]$ such that

$$u_1(x, y) = u(x, y) \text{ for } (x, y) \in [0, \alpha] \times [0, b].$$

Otherwise u is called *non-continuable*.

Theorem 5. *Let u be a non-continuable solution of problem (1), (2) defined on $J \times [0, b]$, and let for every $x_0 \in J$, $v(y) = u_x(x_0, y)$ be a solution of the problem*

$$v' = p[u](x_0, y, v), \quad h(v)(x_0) = \psi(x_0). \tag{13}$$

If the family of solutions $v(y) = u_x(x_0, y)$ ($x_0 \in J$) is uniformly strongly isolated, then either $J = [0, a]$, or $J = [0, \alpha]$ and

$$\lim_{x \rightarrow \alpha} \left(\|u_x(x, \cdot)\|_{C([0, b])} + \|u(x, \cdot)\|_{C([0, b])} + \|u_y(x, \cdot)\|_{C([0, b])} \right) = +\infty. \tag{14}$$

Definition 7. Let u be a non-continuable solution of problem (1), (2) in $J \times [0, b]$ and let $\alpha = \sup J$. We say that a measurable matrix function $P : [0, b] \rightarrow \mathbb{R}^{n \times n}$ belongs to the set $S_f^\alpha[u]$, if there exists an increasing sequence $x_k \uparrow \alpha$ as $k \rightarrow \infty$ such that

$$\lim_{k \rightarrow \infty} \int_0^y P_1[u](x_k, t) dt = \int_0^y P(t) dt$$

uniformly on $[0, b]$.

Corollary. *Let u be a non-continuable solution of problem (1), (2) in $J \times [0, b]$, and let $\alpha = \sup J$. If for an arbitrary $P \in S_f^\alpha[u]$ the homogeneous problem*

$$z' = P(t)z, \quad h(z)(\alpha) = 0$$

has only the trivial solution, then either $J = [0, a]$, or $J = [0, \alpha]$ and (14) holds.

References

- [1] I. T. Kiguradze, Boundary value problems for systems of ordinary differential equations. (Russian) Translated in *J. Soviet Math.* **43** (1988), no. 2, 2259–2339. *Itogi Nauki i Tekhniki, Current problems in mathematics. Newest results, Vol. 30 (Russian)*, 3–103, 204, Akad. Nauk SSSR, Vsesoyuz. Inst. Nauchn. i Tekhn. Inform., Moscow, 1987.
- [2] T. Kiguradze, Some boundary value problems for systems of linear partial differential equations of hyperbolic type. *Mem. Differential Equations Math. Phys.* **1** (1994), 1–144.
- [3] T. Kiguradze and R. Ben-Rabha, On strong well-posedness of initial-boundary value problems for higher order nonlinear hyperbolic equations with two independent variables. *Georgian Math. J.* **24** (2017), no. 3, 409–428.
- [4] T. I. Kiguradze and T. Kusano, On the well-posedness of initial-boundary value problems for higher-order linear hyperbolic equations with two independent variables. (Russian) *Differ. Uravn.* **39** (2003), no. 4, 516–526; translation in *Differ. Equ.* **39** (2003), no. 4, 553–563.