

Some Properties of Minimal Malkin Estimates

E. K. Makarov

Institute of Mathematics of the National Academy of Sciences of Belarus, Minsk, Belarus

E-mail: jcm@im.bas-net.by

Consider the linear differential system

$$\dot{x} = A(t)x, \quad x \in \mathbb{R}^n, \quad t \geq 0, \tag{1}$$

with a bounded piecewise continuous coefficient matrix A and the Cauchy matrix X_A . Suppose that $\|A(t)\| \leq a < +\infty$ for all $t \geq 0$. In [8], see also [9, p. 379] and [1, p. 236], I. G. Malkin has used estimations of the form

$$\|X_A(t, s)\| \leq D \exp(\alpha(t - s) + \beta s), \quad t \geq s \geq 0, \quad D > 0, \quad \alpha, \beta \in \mathbb{R}, \tag{2}$$

in order to investigate asymptotic stability of the trivial solution to a system

$$\dot{y} = A(t)y + f(t, y), \quad y \in \mathbb{R}^n, \quad t \geq 0,$$

with a nonlinear perturbation $f(t, y)$ of a higher order. An ordered pair $(\alpha, \beta) \in \mathbb{R}^2$ is called a Malkin estimation for system (1) if there exists a number $D = D(\alpha, \beta) > 0$ such that (2) holds. We denote the set of all Malkin estimations for system (1) by $E(A)$.

A pair $(\alpha, \beta) \in \mathbb{R}^2$ is said to be a minimal Malkin estimation [7] if $(\alpha + \xi, \beta + \eta) \in E(A)$ for all $\xi > 0, \eta > 0$, and $(\alpha + \xi, \beta + \eta) \notin E(A)$ for all $\xi \leq 0, \eta \leq 0, \xi^2 + \eta^2 \neq 0$. Note that a minimal Malkin estimation is not necessarily an element of $E(A)$ by definition; an example is given below. On the other hand, if $(\alpha, \beta) \in E(A)$ and numbers ξ and η are nonnegative, then the pair $(\alpha + \xi, \beta + \eta)$ satisfies inequality (2) with the same $D = D(\alpha, \beta)$ since $t \geq s \geq 0$, i.e. the inclusion $(\alpha + \xi, \beta + \eta) \in E(A)$ is now valid.

We denote the set of all minimal Malkin estimations for system (1) by $M(A)$.

It can be easily seen that the set of minimal Malkin estimations for system (1) coincides with the set of Grudo characteristic vectors [2] for the function $\|X_A(t, s)\|$ with respect to the cone $C = \{(t, s) \in \mathbb{R}^2 : t \geq s \geq 0\}$. Using this fact and the results of [2] we can give [7] another description for the set $M(A)$. Let $K = \{(\alpha, \beta) \in \mathbb{R}^2 : \alpha > 0, \beta > 0\}$ be the positive cone of \mathbb{R}^2 and \preceq be the partial order in \mathbb{R}^2 corresponding to K . Then $M(A)$ coincides with the set of all minimal with respect to \preceq elements of $\text{cl } E(A)$, where cl is the operator of closure.

The invariant uniform exponent $\iota[x]$ of a nonzero solution x to system (1) is the number $\sup N(x)$, where the set $N(x)$ consists of all numbers

$$\overline{\lim}_{k \rightarrow +\infty} \frac{1}{(t_k - s_k)} \ln \frac{\|x(t_k)\|}{\|x(s_k)\|}$$

such that the sequence of pairs $\tau_k = (t_k, s_k) \in \mathbb{R}^2, t_k \geq s_k \geq 0, k \in \mathbb{N}$, satisfy the condition $\inf_k s_k^{-1} t_k > 1$ and $t_k - s_k \rightarrow +\infty$ as $k \rightarrow +\infty$.

The invariant general exponent $I_0(A)$ for system (1) is the number

$$I_0(A) = \sup_{\theta > 0} \overline{\lim}_{s \rightarrow +\infty} \frac{1}{(\theta - 1)s} \ln \|X_A(\theta s, s)\|. \tag{3}$$

These two exponents are invariant with respect to generalized Lyapunov transformations [3], whereas the analogous Bohl uniform and general exponents are not invariant.

There exists an alternative characterization for $I_0(A)$ given in [7]. Namely, $I_0(A)$ is the first component of a unique pair $(\alpha, 0) \in M(A)$. It should be stressed that the pair $(I_0(A), 0)$ is always in $M(A)$, but the inclusion $(I_0(A), 0) \in E(A)$ is not valid in general. Indeed, according to [1, p. 109], [4, p. 68], and [5, p. 63] for any $\varepsilon > 0$ we have

$$\|X_A(t, s)\| \leq D_\varepsilon \exp((\Omega_0(A) + \varepsilon)(t - s)) \tag{4}$$

with some $D_\varepsilon > 0$, where

$$\Omega_0(A) = \lim_{T \rightarrow +\infty} \overline{\lim}_{k \rightarrow \infty} T^{-1} \ln \|X_A(kT, kT - T)\| \tag{5}$$

is the general exponent of system (1). A similar estimation

$$\|X_A(t, s)\| \leq D_\varepsilon \exp(\alpha(t - s)) \tag{6}$$

with $\alpha < \Omega_0(A)$ is not possible at all. Thus, $(\Omega_0(A) + \varepsilon, 0) \in E(A)$ for each $\varepsilon > 0$ and there are no pairs $(\alpha, 0) \in E(A)$ with $\alpha < \Omega_0(A)$. On the other hand, from (3) and (5) we can assert that the inequality $\Omega_0(A) \geq I_0(A)$ is always valid and that $\Omega_0(A) > I_0(A)$ in general. Thereby $(I_0(A), 0) \notin E(A)$ in general too.

It was proved in [7] that the invariant general exponent $I_0(A)$ is the attainable upper bound for invariant uniform exponents under exponentially small perturbations. Our aim is to obtain some similar interpretation for all elements of $M(A)$. To this end, we first obtain some alternative formulas for $I_0(A)$ and $\iota[x]$.

Proposition 1. *For any system (1) the equalities*

$$I_0(A) = \lim_{\theta \rightarrow 1+0} \overline{\lim}_{s \rightarrow +\infty} \frac{1}{(\theta - 1)s} \ln \|X_A(\theta s, s)\| = \lim_{\theta \rightarrow 1+0} \overline{\lim}_{k \rightarrow \infty} \frac{1}{(\theta - 1)\theta^k} \ln \|X_A(\theta^{k+1}, \theta^k)\|$$

hold.

Proof. Let

$$R(\theta, s) = \frac{1}{(\theta - 1)s} \ln \|X_A(\theta s, s)\|, \quad R(\theta) = \overline{\lim}_{k \rightarrow \infty} R(\theta, \theta^k), \quad \underline{I} = \underline{\lim}_{\theta \rightarrow 1+0} R(\theta).$$

Take any $\varepsilon > 0$, $\theta > 1$ and put $\vartheta = 1 + \varepsilon a^{-1}(\theta - 1)/(\theta + 1)$. By definition of lower limit, for any $\varepsilon > 0$ and $\vartheta > 1$ there exists a number $\theta_\varepsilon \in]1, \vartheta]$ such that the inequality $R(\theta_\varepsilon) < \underline{I} + \varepsilon$ holds. Then by definition of upper limit, for the same $\varepsilon > 0$ there exists a number $N_\varepsilon \in \mathbb{N}$ such that the inequality

$$R(\theta_\varepsilon, \theta_\varepsilon^j) < \overline{\lim}_{j \rightarrow \infty} R(\theta_\varepsilon, \theta_\varepsilon^j) + \varepsilon < \underline{I} + 2\varepsilon$$

is valid for each $j > N_\varepsilon$.

Take any $s > \theta_\varepsilon^{N_\varepsilon}$ and find numbers $p, q \in \mathbb{N}$ such that $s \in [\theta_\varepsilon^p, \theta_\varepsilon^{p-1}[$ and $\theta s \in [\theta_\varepsilon^{q+2}, \theta_\varepsilon^{q+1}[$. Then we have

$$\begin{aligned} \theta_\varepsilon^p - s &\leq \theta_\varepsilon^p - \theta_\varepsilon^{p-1} = \theta_\varepsilon^{p-1}(\theta_\varepsilon - 1) \leq (\theta_\varepsilon - 1)s, \\ \theta s - \theta_\varepsilon^{q+1} &\leq \theta_\varepsilon^{q+2} - \theta_\varepsilon^{q+1} = \theta_\varepsilon^{q+1}(\theta_\varepsilon - 1) \leq (\theta_\varepsilon - 1)\theta s, \end{aligned}$$

and

$$\begin{aligned}
 (\theta - 1)sR(\theta, s) &\leq \ln \|X(\theta s, \theta_\varepsilon^{q+1})\| + \ln \|X(\theta_\varepsilon^p, s)\| + \sum_{j=p}^q \ln \|X(\theta_\varepsilon^{j+1}, \theta_\varepsilon^j)\| \\
 &\leq a(\theta s - \theta_\varepsilon^{q+1} + \theta_\varepsilon^p - s) + \sum_{j=p}^q (\theta_\varepsilon^{j+1} - \theta_\varepsilon^j) R(\theta_\varepsilon, \theta_\varepsilon^j) \\
 &\leq as(\theta + 1)(\theta_\varepsilon - 1) + (\theta_\varepsilon^{q+1} - \theta_\varepsilon^p) \max_{q \leq j \leq p} R(\theta_\varepsilon, \theta_\varepsilon^j) \leq as(\theta + 1)(\vartheta - 1) + (\theta - 1)s \max_{q \leq j \leq p} R(\theta_\varepsilon, \theta_\varepsilon^j).
 \end{aligned}$$

By the above assumptions we have

$$R(\theta, s) \leq a(\theta + 1)(\vartheta - 1)/(\theta - 1) + \max_{q \leq j \leq p} R(\theta_\varepsilon, \theta_\varepsilon^j) \leq \max_{j \geq N_\varepsilon} R(\theta_\varepsilon, \theta_\varepsilon^j) + \varepsilon \leq \underline{I} + 3\varepsilon,$$

for all $\varepsilon > 0$ and $\theta > 1$ and all sufficiently large s . Hence, the relation $\tilde{R}(\theta) := \overline{\lim}_{s \rightarrow \infty} R(\theta, s) \leq \underline{I}$ is valid for each $\theta > 1$. Now, we obtain

$$I_0 := \sup_{\theta > 1} \tilde{R}(\theta) \leq \underline{I} \text{ and } \overline{\lim}_{\theta \rightarrow 1+0} \tilde{R}(\theta) \leq \underline{I}.$$

On the other hand, $\underline{\lim}_{\theta \rightarrow 1+0} \tilde{R}(\theta) \geq \overline{\lim}_{\theta \rightarrow 1+0} R(\theta) = \underline{I}$, since $\tilde{R}(\theta) \geq R(\theta)$. Thus,

$$\underline{\lim}_{\theta \rightarrow 1+0} \tilde{R}(\theta) \geq \underline{I} \geq \overline{\lim}_{\theta \rightarrow 1+0} \tilde{R}(\theta)$$

and therefore the limit $\lim_{\theta \rightarrow 1+0} \tilde{R}(\theta) = \underline{I} \geq I_0$ exists. Since the last inequality is possible only as an equality, we have the required assertion. □

Remark. The above proof essentially follows from the well-known scheme of the similar proof for general exponent, see [1, p. 110], [4, p. 67], or [5, p. 61].

Proposition 2. *For any nonzero solution x to system (1) the following equalities*

$$\begin{aligned}
 \iota[x] &= \sup_{\theta > 0} \overline{\lim}_{s \rightarrow +\infty} \frac{1}{(\theta - 1)s} \ln \frac{\|x(\theta s)\|}{\|x(s)\|} = \lim_{\theta \rightarrow 1+0} \overline{\lim}_{s \rightarrow +\infty} \frac{1}{(\theta - 1)s} \ln \frac{\|x(\theta s)\|}{\|x(s)\|} \\
 &= \lim_{\theta \rightarrow 1+0} \overline{\lim}_{k \rightarrow \infty} \frac{1}{(\theta - 1)\theta^k} \ln \frac{\|x(\theta^{k+1})\|}{\|x(\theta^k)\|}
 \end{aligned}$$

are valid.

To prove Proposition 2, we use some theorems from [11] concerning the growth of x instead of standard estimates for the Cauchy matrix used in the proof of Proposition 1, but the rest of the proof is rather analogous to previous one.

Definition. The number

$$\iota_\theta[x] := \overline{\lim}_{s \rightarrow +\infty} \frac{1}{(\theta - 1)s} \ln \frac{\|x(\theta s)\|}{\|x(s)\|}$$

is called the θ -uniform exponent of a nonzero solution x to system (1).

Together with original system (1), consider the perturbed system

$$\dot{y} = A(t)y + Q(t)y, \quad y \in \mathbb{R}^n, \quad t \geq 0, \quad (7)$$

with piecewise continuous bounded perturbation matrix Q . Let \mathfrak{R}_σ be the set of all piecewise continuous bounded perturbations Q such that

$$\lambda[Q] = \overline{\lim}_{t \rightarrow +\infty} t^{-1} \ln \|Q(t)\| < -\sigma, \quad \sigma \in \mathbb{R}.$$

Put

$$i_\theta(A + Q) = \sup_y \iota_\theta[y],$$

where the supremum is taken over all non-trivial solutions of system (7).

Theorem. *For any $(\alpha, \beta) \in M(A)$, there exists a number $\theta > 1$ such that*

$$\alpha = \sup \{i_\theta(A + Q) : Q \in \mathfrak{R}_\beta\}.$$

The proof is based on Millionshchikov's rotation method [10], [3], [5, p. 75].

References

- [1] B. F. Bylov, R. È. Vinograd, D. M. Grobman, and V. V. Nemyckii, Theory of Ljapunov exponents and its application to problems of stability. (Russian) *Izdat. "Nauka", Moscow*, 1966.
- [2] È. I. Grudo, Characteristic vectors and sets of functions of two variables and their fundamental properties. (Russian) *Differencial'nye Uravnenija* **12** (1976), no. 12, 2115–2118.
- [3] N. A. Izobov, Linear systems of ordinary differential equations. (Russian) *Mathematical analysis, Vol. 12 (Russian)*, pp. 71–146, 468. (loose errata) *Akad. Nauk SSSR Vsesojuz. Inst. Nauchn. i Tehn. Informacii, Moscow*, 1974.
- [4] N. A. Izobov, Introduction to the theory of Lyapunov exponents. (Russian) *Minsk*, 2006.
- [5] N. A. Izobov, Lyapunov exponents and stability. *Stability Oscillations and Optimization of Systems 6. Cambridge Scientific Publishers, Cambridge*, 2013.
- [6] E. K. Makarov, On the interrelation between characteristic functionals and weak characteristic exponents. (Russian) *Differentsial'nye Uravneniya* **30** (1994), no. 3, 393–399, 547; translation in *Differential Equations* **30** (1994), no. 3, 362–367.
- [7] E. K. Makarov, Malkin estimates for the norm of the Cauchy matrix of a linear differential system. (Russian) *Differ. Uravn.* **32** (1996), no. 3, 328–334, 429; translation in *Differential Equations* **32** (1996), no. 3, 333–339.
- [8] I. G. Malkin, On stability of motion via the first approximation. (Russian) *C. R. (Dokl.) Acad. Sci. URSS, n. Ser.* **18** (1938), 159–162.
- [9] I. G. Malkin, Theory of stability of motion. (Russian) *Izdat. "Nauka", Moscow*, 1966.
- [10] D. V. Millionshchikov, Cohomology of graded Lie algebras of maximal class with coefficients in the adjoint representation. (Russian) *Tr. Mat. Inst. Steklova* **263** (2008), Geometriya, Topologiya i Matematicheskaya Fizika. I, 106–119; translation in *Proc. Steklov Inst. Math.* **263** (2008), no. 1, 99–111.
- [11] I. N. Sergeev, On the theory of Lyapunov exponents of linear systems of differential equations. (Russian) *Trudy Sem. Petrovsk.* No. 9 (1983), 111–166.